Sensorimotor Control of Posture Postural control involves continuous and dynamic interactions between the neuromuscular system and the sensory system (Horak & Macpherson, 1996).

Sensorimotor Control Of Movement And Posture

Reinhard Dengler, Andon R. Kossev

Sensorimotor Control Of Movement And Posture:

Sensorimotor Control of Movement and Posture Simon C. Gandevia, Uwe Proske, Douglas G. Stuart, 2012-12-06 This collection of contributions on the subject of the neural mechanisms of sensorimotor control resulted from a conference held in Cairns Australia September 3 6 2001 While the three of us were attending the International Union of Physiological Sciences IUPS Congress in St Petersburg Russia in 1997 we discussed the implications of the next Congress being awarded to New Zealand We agreed to organise a satellite to this congress in an area of mutual interest the neuroscience of movement and sensation Australia has a long standing and enviable reputation in the field of neural mechanisms of sensorimotor control Arguably this reached its peak with the award of a Nobel Prize to Sir John Eccles in 1963 for his work on synaptic transmission in the central nervous system Since that time the subject of neuroscience has progressed considerably One advance is the exploitation of knowledge acquired from animal experiments to studies on conscious human subjects In this development Australians have achieved international prominence particularly in the areas of kinaesthesia and movement control This bias is evident in the choice of subject matter for the conference and subsequently this book It was also decided to assign a whole section to muscle mechanics a subject that is often left out altogether from conferences on Sensorimotor Control Reinhard motor control Cairns is a lovely city and September is a good time to visit it Dengler, Andon R. Kossev, 2001 Despite the intensive experimental and theoretical studies for over a century the general processes involved in neural control of pasture and movement in learning of motor behaviour in healthy subjects and in adaptation in pathology were and remain a challenging problems for the scientists in the field of sensorimotor control The book is the outcome of the Advanced Research Workshop Sensorimotor Control where the focus was on the state and the perspectives of the study in the field Biomechanics and Neural Control of Posture and Movement Jack M. Winters, Patrick E. Crago, 2012-12-06 Most routine motor tasks are complex involving load transmission through out the body intricate balance and eye head shoulder hand torso leg coor dination. The quest toward understanding how we perform such tasks with skill and grace often in the presence of unpredictable perturbations has a long history This book arose from the Ninth Engineering Foundation Con ference on Biomechanics and Neural Control of Movement held in Deer Creek Ohio in June 1996 This unique conference which has met every 2 to 4 years since the late 1960s is well known for its informal format that promotes high level up to date discussions on the key issues in the field The intent is to capture the high quality of the knowledge and discourse that is an integral part of this conference series The book is organized into ten sections Section I provides a brief intro duction to the terminology and conceptual foundations of the field of move ment science it is intended primarily for students All but two of the re maining nine sections share a common format l a designated section editor 2 an introductory didactic chapter solicited from recognized lead ers and 3 three to six state of the art perspective chapters Some per spective chapters are followed by commentaries by selected experts that provide balance and insight Section VI is the

largest section and it con sists of nine perspective chapters without commentaries Neural and Computational Modeling of Movement Control Ning Lan, Vincent C. K. Cheung, Simon C. Gandevia, 2017-04-17 In the study of sensorimotor systems an important research goal has been to understand the way neural networks in the spinal cord and brain interact to control voluntary movement Computational modeling has provided insight into the interaction between centrally generated commands proprioceptive feedback signals and the biomechanical responses of the moving body Research in this field is also driven by the need to improve and optimize rehabilitation after nervous system injury and to devise biomimetic methods of control in robotic devices This research topic is focused on efforts dedicated to identify and model the neuromechanical control of movement Neural networks in the brain and spinal cord are known to generate patterned activity that mediates coordinated activation of multiple muscles in both rhythmic and discrete movements e g locomotion and reaching Commands descending from the higher centres in the CNS modulate the activity of spinal networks which control movement on the basis of sensory feedback of various types including that from proprioceptive afferents The computational models will continue to shed light on the central strategies and mechanisms of sensorimotor control and learning This research topic demonstrated that computational modeling is playing a more and more prominent role in the studies of postural and movement control With increasing ability to gather data from all levels of the neuromechanical sensorimotor systems there is a compelling need for novel creative modeling of new and existing data sets because the more systematic means to extract knowledge and insights about neural computations of sensorimotor systems from these data is through computational modeling While models should be based on experimental data and validated with experimental evidence they should also be flexible to provide a conceptual framework for unifying diverse data sets to generate new insights of neural mechanisms to integrate new data sets into the general framework to validate or refute hypotheses and to suggest new testable hypotheses for future experimental investigation It is thus expected that neural and computational modeling of the sensorimotor system should create new opportunities for experimentalists and modelers to collaborate in a joint endeavor to advance our understanding of the neural mechanisms for postural and movement control The editors would like to thank Professor Arthur Prochazka who helped initially to set up this research topic and all authors who contributed their articles to this research topic Our appreciation also goes to the reviewers who volunteered their time and effort to help achieve the goal of this research topic We would also like to thank the staff members of editorial office of Frontiers in Computational Neuroscience for their expertise in the process of manuscript handling publishing and in bringing this ebook to the readers The support from the Editor in Chief Dr Misha Tsodyks and Dr Si Wu is crucial for this research topic to come to a successful conclusion We are indebted to Dr Si Li and Ms Ting Xu whose assistant is important for this ebook to become a reality Finally this work is supported in part by grants to Dr Ning Lan from the Ministry of Science and Technology of China 2011CB013304 the Natural Science Foundation of China No 81271684 No 61361160415 No 81630050 and the Interdisciplinary Research Grant cross

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of human motor control with an approach that has movement biomechanics as a common base The reader can find interesting information in this book and a stimulus for new studies and investigations Routledge Handbook of Motor Control and Motor Learning Albert Gollhofer, Wolfgang Taube, Jens Bo Nielsen, 2013 This text offers a comprehensive survey of neurophysiological behavioural and biomechanical aspects of motor function Adopting an integrative approach it examines the full range of key topics in contemporary human movement studies explaining motor behaviour in depth from the molecular level to behavioural consequences Neuromechanical Modeling of Posture and Locomotion Boris I. Prilutsky, Donald H. Edwards, 2015-12-30 Neuromechanics is a new quickly growing field of neuroscience research that merges neurophysiology biomechanics and motor control and aims at understanding living systems and their elements through interactions between their neural and mechanical dynamic properties Although research in Neuromechanics is not limited by computational approaches neuromechanical modeling is a powerful tool that allows for integration of massive knowledge gained in the past several decades in organization of motion related brain and spinal cord activity various body sensors and reflex pathways muscle mechanical and physiological properties and detailed quantitative morphology of musculoskeletal systems Recent work in neuromechanical modeling has demonstrated advantages of such an integrative approach and led to discoveries of new emergent properties of neuromechanical systems Neuromechanical Modeling of Posture and Locomotion will cover a wide range of topics from theoretical studies linking the organization of reflex pathways and central pattern generating circuits with morphology and mechanics of the musculoskeletal system Burkholder Nichols Shevtsova et al to detailed neuromechanical models of postural and locomotor control Bunderson Edwards Marking et al Ting Furthermore uniquely diverse modeling approaches will be presented in the book including a theoretical dynamic analysis of locomotor phase transitions Spardy and Rubin a hybrid computational modeling that allows for in vivo interactions between parts of a living organism and a computer model Edwards et al a physical neuromechanical model of the human locomotor Machine Learning Approaches to Human Movement Analysis Matteo Zago, Peter A. Federolf, Ana system Lewis and others Francisca Rozin Kleiner, 2021-03-04 Modularity in Motor Control: From Muscle Synergies to Cognitive Action Representation Andrea d'Avella, Martin Giese, Yuri P Ivanenko, Thomas Schack, Tamar Flash, 2016-04-21 Mastering a rich repertoire of motor behaviors as humans and other animals do is a surprising and still poorly understood outcome of evolution development and learning Many degrees of freedom non linear dynamics and sensory delays provide formidable challenges for controlling even simple actions Modularity as a functional element both structural and computational of a control architecture might be the key organizational principle that the central nervous system employs for achieving versatility and adaptability in motor control Recent investigations of muscle synergies motor primitives compositionality basic action concepts and related work in machine learning have contributed to advance at different levels our understanding of the modular architecture underlying rich motor behaviors However the existence and nature of the modules in the control

architecture is far from settled For instance regularity and low dimensionality in the motor output are often taken as an indication of modularity but could they simply be a byproduct of optimization and task constraints Moreover what are the relationships between modules at different levels such as muscle synergies kinematic invariants and basic action concepts One important reason for the new interest in understanding modularity in motor control from different viewpoints is the impressive development in cognitive robotics In comparison to animals and humans the motor skills of today s best robots are limited and inflexible However robot technology is maturing to the point at which it can start approximating a reasonable spectrum of isolated perceptual cognitive and motor capabilities These advances allow researchers to explore how these motor sensory and cognitive functions might be integrated into meaningful architectures and to test their functional limits Such systems provide a new test bed to explore different concepts of modularity and to address the interaction between motor and cognitive processes experimentally Thus the goal of this Research Topic is to review compare and debate theoretical and experimental investigations of the modular organization of the motor control system at different levels By bringing together researchers seeking to understand the building blocks for coordinating many muscles for planning endpoint and joint trajectories and for representing motor and behavioral actions in memory we aim at promoting new interactions between often disconnected research areas and approaches and at providing a broad perspective on the idea of modularity in motor control We welcome original research methodological theoretical review and perspective contributions from behavioral system and computational motor neuroscience research cognitive psychology and cognitive robotics

Balance, Gait, and Falls ,2018-11-24 Balance Gait and Falls Volume 159 presents the latest information on sensorimotor anatomy sensory integration gravity and verticality standing balance balance perturbations voluntary stepping and gait initiation gait and gait adaptability disorders of balance and gait that result from aging and neurological diseases. The book provides a brief overview of age related changes in the structure and function of sensorimotor and central processes with sections specifically devoted to Parkinson s disease parkinsonism cerebellar ataxia stroke corticobasal degeneration multiple sclerosis Huntington s disease dystonia tremor Alzheimer s disease frontotemporal dementia cerebral palsy polio motor neuron disease brainstem lesions spinal lesions peripheral nerve disease and psychogenic conditions. Diseases covered have a common structure comprising background and epidemiology pathology balance disorders gait disorders falls therapies including fall prevention and future directions Covers all aspects of basic and clinical research on disorders of balance and gait in neurological disease Presents a multidisciplinary review of balance and gait physiology the epidemiology and natural history of balance and gait impairments in aging and a broad range of neurological diseases Addresses impairments of balance and gait for basic and clinical researchers in neuroscience human movement science physiotherapy and exercise physiology Human Movement and Motor Control in the Natural Environment Peter A Federolf, Maurice Mohr, Thorsten Stein, Gert-Jan Pepping, Steven van Andel, Gillian Weir, 2023-06-08 The basic understanding

of human movement and control of human movement stems largely from laboratory measurements where human movement can be quantified with high precision and accuracy but where the artificial environment compromises ecological validity A good example for this issue was demonstrated in a recent investigation specifically that the walking gait pattern of healthy individuals in a laboratory changed as a function of how many researchers were present during the experiment Observations like these underscore that study volunteers adapt their behavior to the specific laboratory environment and warrant the question of how well we can transfer our lab based understanding of gait patterns and the underlying neuromuscular control system to walking during daily living Another research area where lab based movement assessments have led to conflicting findings is the field of sports injury prevention Many neuromuscular training programs have been shown to be effective in reducing the sport injury rate in athletes by 30 50% or more in a variety of different multi directional sports Nevertheless lab based assessments of the same athletes who completed those training programs were often not able to detect improvements in motor control of sport specific movements or a reduction in joint loading two factors thought to be closely linked with sport injury risk This disconnect suggests that lab based assessments of movement and motor control are often poor indicators of player behavior during real game scenarios and may limit our ability to screen athletes for injury risk or monitor their progress in rehabilitation These examples highlight that we should strive for the assessment and investigation of human movement and motor control in natural environments i e where individuals patients athletes or other groups of interest perform explore and interact under real world conditions Climbing and Walking Robots Karsten Berns, Rudiger Dillmann.2001-11-28 Recent advances in robot technology from around the world Climbing and Walking Robots From Biology to Industrial Applications is a collection of papers presented at the 2001 CLAWAR conference Featuring current work from leading robotics labs around the globe this book presents the latest in robotics across industries and suggests directions for future research Topics include design methodology bipedal locomotion fluid actuators sensor systems control architecture and simulation and more Relevant to mechanical engineers and robotics specialists in both industry and academia these papers showcase the field s latest technological advances Fundamental Neuroscience Larry Squire, James L. Roberts, Nicholas C. Spitzer, Michael J. Zigmond, Darwin Berg, Floyd E. Bloom, Sascha du Lac, Anirvan Ghosh, Larry R. Squire, Susan K. McConnell, 2002-11-19 With over 300 training programs in neuroscience currently in existence demand is great for a comprehensive textbook that both introduces graduate students to the full range of neuroscience from molecular biology to clinical science but also assists instructors in offering an in depth course in neuroscience to advanced undergraduates The second edition of Fundamental Neuroscience accomplishes all this and more The thoroughly revised text features over 25% new material including completely new chapters illustrations and a CD ROM containing all the figures from the text More concise and manageable than the previous edition this book has been retooled to better serve its audience in the neuroscience and medical communities Key Features Logically organized into 7 sections with uniform editing of the

content for a one voice feel throughout all 54 chapters Includes numerous text boxes with concise detailed descriptions of specific experiments disorders methodological approaches and concepts Well illustrated with over 850 full color figures also included on the accompanying CD ROM Neuromechanics and Control of Physical Behavior: from Experimental and Computational Formulations to Bio-inspired Technologies Massimo Sartori, Francisco J. Valero-Cuevas, Alfred C. Schouten, Matthew Tresch, Yoshihiko Nakamura, Manish Sreenivasa, 2019-08-15 The term neuromechanics defines an integrative approach that combines the neuromuscular control and the biomechanical aspects of physical behavior in humans and animals Crucial to this approach is a detailed description and modeling of the interaction between the nervous system and the controlled biomechanical plant Only then do we have the broader context within which to understand evolution movement mechanics neural control energetics disability and rehabilitation In addition to enabling new basic science directions understanding the interrelations between movement neural and mechanical function should also be leveraged for the development of personalized wearable technologies to augment or restore the motor capabilities of healthy or impaired individuals Similarly this understanding will empower us to revisit current approaches to the design and control of robotic and humanoid systems to produce truly versatile human like physical behavior and adaptation in real world environments This Research Topic is therefore poised at an opportune moment to promote understanding of apparently disparate topics into a coherent focus Acute and chronic changes in postural control in response to different physiological states and external environmental conditions Nejc Sarabon, Jan Babic, Urs Granacher, Thierry Paillard, 2023-04-04 Control and Learning Markus Latash, Francis Lestienne, 2006-05-31 The purpose of the current volume is two fold First The second chapter is co authored by Rosenbaum it presents a series of review papers rejecting the re Cohen Meulenbroek and Vaughan The authors cent progress in the area of neural control of posture dress in this chapter another central issue of motor and movement Parts I and II Second it focuses on control that of creating motor plans Inline with tissues of changes in motor patterns and neurological orizing by David Rosenbaum and his colleagues this structures involved in their production with learning chapter develops the idea of end state comfort as an development and aging Parts III and IV organizing criterion for the formation motor plans The chapters in this volume were written by speak The chapter also highlights the role of mental rep ers at the Fourth meeting Progress in Motor Con sentation in motor control trol that took place in Caen France in 2003 As Chapter 3 focuses on issues of postural control Stroke Recovery and Rehabilitation Richard Harvey, Richard F. Macko, Joel Stein, Carolee Winstein, Richard D. Zorowitz, 2008-11-20 A Doody's Core Title 2012 Stroke Recovery and Rehabilitation is the new gold standard comprehensive guide to the management of stroke patients Beginning with detailed information on risk factors epidemiology prevention and neurophysiology the book details the acute and long term treatment of all stroke related impairments and complications Additional sections discuss psychological issues outcomes community reintegration and new research Written by dozens of acknowledged leaders in the field and containing hundreds

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