

Lecture Notes in Artificial Intelligence 1724

Subseries of Lecture Notes in Computer Science

**Henrik I. Christensen Horst Bunke
Hartmut Noltemeier (Eds.)**

Sensor Based Intelligent Robots

**International Workshop
Dagstuhl Castle, Germany, September/October 1998
Selected Papers**



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Sensor Based Intelligent Robots International Workshop
Dagstuhl Castle Germany September 28october 2 1998
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Sensor Based Intelligent Robots Gregory D. Hager, Henrik I. Christensen, Horst Bunke, Rolf Klein, 2003-08-06 Robotics is a highly interdisciplinary research topic that requires integration of methods for mechanics control engineering signal processing planning graphics human computer interaction real time systems applied mathematics and software engineering to enable construction of fully operational systems The diversity of topics needed to design implement and deploy such systems implies that it is almost impossible for individual teams to provide the needed critical mass for such endeavors To facilitate interaction and progress on sensor based intelligent robotics interdisciplinary workshops are necessary through which depth discussion can be used for cross dissemination between different disciplines The Dagstuhl foundation has organized a number of workshops on Modeling and Integration of Sensor Based Intelligent Robot Systems The Dagstuhl seminars take place over a

full week in a beautiful setting in the Saarland in Germany The setting provides an ideal environment for in depth presentations and rich interaction between the participants This volume contains papers presented during the fourth workshop held tober 15 20 2000 All papers were submitted by workshop attendees and were reviewed by at least one reviewer We wish to thank all of the reviewers for their invaluable help in making this a high quality selection of papers We gratefully acknowledge the support of the Schloss Dagstuhl Foundation and the sta at Springer Verlag Without their support the production of this volume would not have been possible

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Modeling and Planning for Sensor-based Intelligent Robot Systems Robert Bolles, Horst Bunke, Henrik I. Christensen, Hartmut Noltemeier, 1998

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Intelligent Robots and Systems Volker Graefe, 1995 Of the 300 papers presented during IROS 94 48 were selected because they are particularly significant and characteristic for the present state of the technology of intelligent robots and systems This book contains the selected papers in a revised and expanded form Robotics and intelligent systems constitute a very wide and truly interdisciplinary field The papers have been grouped into the following categories Sensing and Perception Learning and Planning Manipulation Telerobotics and Space Robotics Multiple Robots Legged Locomotion Mobile Robot Systems Robotics in Medicine Other additional fields covered include control navigation and simulation Since many researchers in robotics are now apparently interested in some combination of learning mobile robots and robot vision most of the articles included relate to at least one of these fields

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