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Numerical Linear Algebra Techniques For Systems And Control

Panos J. Antsaklis, Anthony N. Michel



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Mathematical Systems Theory I Diederich Hinrichsen, Anthony J. Pritchard, 2011-08-03 This book presents the mathematical foundations of systems theory in a self contained comprehensive detailed and mathematically rigorous way It is devoted to the analysis of dynamical systems and combines features of a detailed introductory textbook with that of a reference source The book contains many examples and figures illustrating the text which help to bring out the intuitive ideas behind the mathematical constructions

Linear Systems Primer Panos J. Antsaklis, Anthony N. Michel, 2007-12-03 Based on a streamlined presentation of the

authors successful work Linear Systems this textbook provides an introduction to systems theory with an emphasis on control Initial chapters present necessary mathematical background material for a fundamental understanding of the dynamical behavior of systems Each chapter includes helpful chapter descriptions and guidelines for the reader as well as summaries notes references and exercises at the end The emphasis throughout is on time invariant systems both continuous and discrete time

Subspace Methods for System Identification Tohru Katayama,2005-10-11 An in depth introduction to subspace methods for system identification in discrete time linear systems thoroughly augmented with advanced and novel results this text is structured into three parts Part I deals with the mathematical preliminaries numerical linear algebra system theory stochastic processes and Kalman filtering Part II explains realization theory as applied to subspace identification Stochastic realization results based on spectral factorization and Riccati equations and on canonical correlation analysis for stationary processes are included Part III demonstrates the closed loop application of subspace identification methods Subspace Methods for System Identification is an excellent reference for researchers and a useful text for tutors and graduate students involved in control and signal processing courses It can be used for self study and will be of interest to applied scientists or engineers wishing to use advanced methods in modeling and identification of complex systems

The Control Systems Handbook William S. Levine,2018-10-03 At publication The Control Handbook immediately became the definitive resource that engineers working with modern control systems required Among its many accolades that first edition was cited by the AAP as the Best Engineering Handbook of 1996 Now 15 years later William Levine has once again compiled the most comprehensive and authoritative resource on control engineering He has fully reorganized the text to reflect the technical advances achieved since the last edition and has expanded its contents to include the multidisciplinary perspective that is making control engineering a critical component in so many fields Now expanded from one to three volumes The Control Handbook Second Edition organizes cutting edge contributions from more than 200 leading experts The third volume Control System Advanced Methods includes design and analysis methods for MIMO linear and LTI systems Kalman filters and observers hybrid systems and nonlinear systems It also covers advanced considerations regarding Stability Adaptive controls System identification Stochastic control Control of distributed parameter systems Networks and networked controls As with the first edition the new edition not only stands as a record of accomplishment in control engineering but provides researchers with the means to make further advances Progressively organized the first two volumes in the set include Control System Fundamentals Control System Applications

Approximation of Large-Scale Dynamical Systems Athanasios C. Antoulas,2009-06-25 Mathematical models are used to simulate and sometimes control the behavior of physical and artificial processes such as the weather and very large scale integration VLSI circuits The increasing need for accuracy has led to the development of highly complex models However in the presence of limited computational accuracy and storage capabilities model reduction system approximation is often necessary Approximation of Large Scale Dynamical Systems

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