Pyramidal Sys tems for Comp uter Vision (N ATO Asi Ser ies: Series F:

COVER COMING SOON

Virginio Cantoni, Stefano Levialdi

Pyramidal Systems for Computer Vision Virginio Cantoni, Stefano Levialdi, 2012-12-06 This book contains the proceedings of the NATO Advanced Research Workshop held in Maratea Italy May 5 9 1986 on Pyramidal Systems for Image Processing and Computer Vision We had 40 participants from 11 countries playing an active part in the workshop and all the leaders of groups that have produced a prototype pyramid machine or a design for such a machine were present Within the wide field of parallel architectures for image processing a new area was recently born and is growing healthily the area of pyramidally structured multiprocessing systems Essentially the processors are arranged in planes from a base to an apex each one of which is generally a reduced usually by a power of two version of the plane underneath these processors are horizontally interconnected within a plane and vertically connected with fathers on top planes and children on the plane below This arrangement has a number of interesting features all of which were amply discussed in our Workshop including the cellular array and hypercube versions of pyramids A number of projects in different parts of the world are reported as well as some interesting applications in computer vision tactile systems and numerical calculations Interactive Testing and Self-Assessment Dieudonne A. Leclercq, James E. Bruno, 2012-12-06 Assessment has long been recognized as a key feature in learning efficacy especially through formative evaluation Item banking the storage and classification of test items is an essential part of systematic assessment This volume is based on a NATO Advanced Research Workshop held as part of the Special Programme on Advanced Educational Technology The workshop brought together scholars from around the world to discuss and critically analyze the issues and problems associated with Subjective Probability Measurement SPM or the more generic research area called self assessment Recent advances in computer technology expert systems interactive video disks and hypermedia along with the developing sophistication of self assessment scoring systems based on SPM made this conference particularly important and timely The book is divided into three main parts The input item banking and hypermedia The process subjective probabilities The output teaching and learning feedbacks In summary although SPM is a difficult theoretical concept for most educators to comprehend the sophisticated nature of modern computer systems coupled with comprehensive formative and summative evaluation and self assessment systems make SPM transparent to the user

Intelligent Learning Environments and Knowledge Acquisition in Physics Andree Tiberghien, Heinz Mandl, 2012-12-06 The NATO workshop Knowledge acquisition in the domain of physics and intelligent learning environments was held in Lyon France July 8 12 1990 A total of 31 researchers from Europe France Germany Greece Italy Portugal and the U K the U S A and Japan worked together This proceedings volume contains most of the contributions to the workshop The papers show clearly the main directions of research in intelligent learning environments They display a variety of points of view depending on the researcher's own background even when a single domain of teaching namely physics is considered We acknowledge the assistance of Michael Baker who was responsible for

reviewing the English of the contributions February 1992 Andree Tiberghien Heinz Mandl Table of Contents Introduction 1 1 Teaching Situations and Physics Knowledge Introductory University Courses and Open Environment Approaches The Computer as a Multi role Mediator in Teaching Learning Physics 5 E Balzano P Guidoni M Moretti E Sassi G Squeglia Practical Work Aid Knowledge Representation in a Model Based AI System 21 J Courtois Simultaneous Processing of Different Problem Aspects in Expert Problem Solving An Analysis in the Domain of Physics on the Basis of Formal Theories of Commonsense Knowledge 35 A Hron Modelis An Artificial Intelligence System Which Models Thermodynamics Textbook Problems 47 G Tisseau 2 Different Approaches to Student Modelling Steps Towards the Formalisation of a Psychologic of Cognitive Tools for Learning Piet A.M. Kommers, David H. Jonassen, J. Terry Mayes, 2012-12-06 Motion 65 J Bliss J Hypermedia technology needs a creative approach from the outset in the design of software to facilitate human thinking and learning This book opens a discussion of the potential of hypermedia and related approaches to provide open exploratory learning environments The papers in the book are based on contributions to a NATO Advanced Research Workshop held in July1990 and are grouped into six sections Semantic networking as cognitive tools Expert systems as cognitive tools Hypertext as cognitive tools Collaborative communication tools Microworlds context dependent cognitive tools Implementing cognitive tools The book will be valuable for those who design implement and evaluate learning programs and who seek to escape from rigid tactics like programmed instruction and behavioristic approaches. The book presents principles for exploratory systems that go beyond existing metaphors of instruction and provokes the reader to think in a new way about the cognitive level of human computer interaction **Sensory Robotics for the Handling of Limp Materials** Paul M. Taylor, 2012-12-06 Limp materials are used in many economically impo tant industries such as garment manufacture shoe manufacture aerospace composites and automobiles seats and trim The use of sensors is essential for reliable robotic handling of these materials which are often based on naturally occurring substances such as cotton and leather The materials are limp and have non homogeneous mechanical properties which are often impossible to predict accurately The applications are very demanding for vision and tactile sensing and signal processing adaptive control systems planning and systems integration This book comprises the collection of papers presented at the NATO Advanced Research Workshop on Sensory Robotics for the Handling of Limp Materials held in October 1988 at II Ciocco Tuscany Italy The aim of the workshop was to examine the state of the art and determine what research is needed to provide the theoretical and technological tools for the successful application of sensory robotics to the handling of limp materials. The meeting also acted as the first ever forum for the interchange of knowledge between applications driven researchers and those researching into the provision of fundamental tools The participants were drawn from academia 20 industry 5 and other non university research organisations Multiple Criteria Decision Making and Risk Analysis Using Microcomputers Birsen Karpak, Stanley Zionts, 2013-06-29 Roughly nine years ago the two editors met for the first time in Amsterdam the Netherlands at the EURO III meeting

organized by the Association of European Operational Research Societies there As a result of our initial meeting the two of us planned and carried out a number of activities in the multiple criteria decision making area much of it supported by the North Atlantic Treaty Organization NATO The latest of these activities was a NATO Advanced Study Institute ASI on multiple criteria decision making and risk analysis using microcomputers The institute was held in Tarabya Istanbul TURKEY on June 28 July 8 1987 We received over 100 applications from professors and a few graduate students in 13 countries Roughly half of them were able to participate The ASI was a great success Substantial knowledge transfer and learning took place In addition to the planned presentations we had several panels and round table discussions Though we had planned these in advance we implemented them to fit the occasion and also organized a few special sessions on site to respond to participants Designing Hypermedia for Learning David H. Jonassen, Heinz Mandl, 2012-12-06 This most unusual book results interests from the NATO Advanced Research Work shop Designing Hypertext Hypermedia for Learning held in Rottenburg am Neckar FRO from July 3 8 1989 The idea for the workshop resulted from the burgeoning interest in hypertext combined with the frustrating lack of literature on leaming applications for hypertext There was little evidence in 1988 that hypertext could successfully support learning out comes A few projects were investigating hypertext for learning but few conclusions were available and little if any advice on how to design hyper text for learning applications was available Could hypertext support learning objectives What mental processing requirements are unique to learning outcomes How would the processing requirements of learning outcomes interact with unique user processing requirements of browsing and constructing hypertext Should hypertext information bases be restruc tured to accommodate learning outcomes Should the user interface be manipulated in order to support the task functionality of learning outcomes Does the hypertext structure reflect the intellectual requirements of learning outcomes What kinds of learning oriented hypertext systems were being developed and what kinds of assumptions were these systems making These and other questions demonstrated the need for this workshop The workshop included presentations hardware demonstrations sharing and browsing of hypertexts and much discussion about all of the above These were the experiences that you the reader of this book unfortunately did not experience

Sensor-Based Robots: Algorithms and Architectures C.S.George Lee, 2012-12-06 Most industrial robots today have little or no sensory capability Feedback is limited to information about joint positions combined with a few interlock and timing signals These robots can function only in an environment where the objects to be manipulated are precisely located in the proper position for the robot to grasp i e in a structured environment For many present industrial applications this level of performance has been adequate With the increasing demand for high performance sensor based robot manipulators in assembly tasks meeting this demand and challenge can only be achieved through the consideration of 1 efficient acquisition and processing of intemaVextemal sensory information 2 utilization and integration of sensory information from various sensors tactile force and vision to acquire knowledge in a changing environment 3 exploitation of inherent robotic parallel

algorithms and efficient VLSI architectures for robotic computations and finally 4 system integration into a working and functioning robotic system This is the intent of the Workshop on Sensor Based Robots Algorithms and Architectures to study the fundamental research issues and problems associated with sensor based robot manipulators and to propose approaches and solutions from various viewpoints in improving present day robot manipula tors in the areas of sensor fusion and integration sensory information processing and parallel algorithms and architectures for robotic computations and Spatial Modelling for Navigation Louis F. Pau, 2012-12-06 The successful implementation of applications in spatial reasoning requires paying attention to the representation of spatial data In particular an integrated and uniform treatment of different spatial features is necessary in order to enable the reasoning to proceed guickly Currently the most prevalent features are points rectangles lines regions surfaces and volumes As an example of a reasoning task consider a query of the form find all cities with population in excess of 5 000 in wheat growing regions within 10 miles of the Mississippi River Note that this query is quite complex It requires processing a line map for the river creating a corridor or buffer to find the area within 10 miles of the river a region map for the wheat and a point map for the cities Spatial reasoning is eased by spatially sorting the data i e a spatial index In this paper we show how hierarchical data structures can be used to facilitate this process They are based on the principle of recursive decomposition similar to divide and conquer methods In essence they are used primarily as devices to sort data of more than one dimension and different spatial types. The term quadtree is often used to describe this class of data structures In this paper we focus on recent developments in the use of quadtree methods We concentrate primarily on region data For a more extensive treatment of this subject see SameS4a SameSSb SameSc SameSga SameSgbi **Learning from Computers: Mathematics Education and Technology Christine** Keitel-Kreidt, Kenneth Ruthven, 2012-12-06 The NATO Advanced Research Workshop on Mathematics Education and Technology was held in Villard de Lans France between May 6 and 11 1993 Organised on the initiative of the BaCoMET Basic Components of Mathematics Education for Teachers group Christiansen Howson and Otte 1986 Bishop Mellin Olsen and van Dormolen 1991 the workshop formed part of a larger NATO programme on Advanced Educational Technology Some workshop members had already participated in earlier events in this series and were able to contribute insights from them similarly some members were to take part in later events The problematic for the workshop drew attention to important speculative developments in the applications of advanced information technology in mathematics education over the last decade notably intelligent tutoring geometric construction symbolic algebra and statistical analysis Over the same period more elementary forms of information technology had started to have a significant influence on teaching approaches and curriculum content notably arithmetic and graphic calculators standard computer tools such as spreadsheets and databases and computer assisted learning packages and computer microworlds specially designed for educational purposes

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