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V. I. Babitsky · A. V. Shipilov

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Resonant Robotic Systems V. I. Babitsky, Alexander Shipilov, 2012-09-22 Especially designed as self sustaining oscillating systems resonant robotic systems use the natural modes of oscillation of electromechanical modules for their movements In fact manipulator systems built on these principles demonstrate record breaking characteristics in performance The authors summarize the results and experience of research on and development of resonant robotic systems For the readers convenience a presentation of design concepts is followed by solutions to new dynamical and control problems The book is intended for designers researchers and graduate students Control of Resonant Robotic Systems M. Vaughan Roberts, 1991 Bioinspired Sensing, Actuation, and Control in Underwater Soft Robotic Systems Derek A. Paley, Norman M. Wereley, 2020-11-06 This book includes representative research from the state of the art in the emerging field of soft robotics with a special focus on bioinspired soft robotics for underwater applications Topics include novel materials sensors actuators and system design for distributed estimation and control of soft robotic appendages inspired by the octopus and seastar It summarizes the latest findings in an emerging field of bioinspired soft robotics for the underwater domain primarily drawing from but not limited to an ongoing research program in bioinspired autonomous systems sponsored by the Office of Naval Research The program has stimulated cross disciplinary research in biology material science computational mechanics and systems and control for the purpose of creating novel robotic appendages for maritime applications The book collects recent results in this area **Towards Autonomous Robotic Systems** M. Nazmul Huda, Mingfeng Wang, Tatiana Kalganova, 2024-12-29 This two volume set LNAI 15051 15052 constitutes the refereed proceedings from the 25th Annual Conference Towards Autonomous Robotic Systems TAROS 2024 held in London UK during August 21 23 2024 The 54 full papers and 11 short papers presented in these volumes were carefully reviewed and selected from 69 submissions The papers presented in these two volumes are organized in the following topical sections Part I Robotic Learning Mapping and Planning Robotic Modeling Sensing and Control Machine Vision Part II Human Robot Interaction Collaboration Locomotion and Manipulation Mechanism Design Soft Robotics Swarms and Multi Agent Systems Robot Systems for Rail Transit Applications Hui Liu, 2020-06-27 Robot Systems for Rail Transit Applications presents the latest advances in robotics and artificial intelligence for railway systems giving foundational principles and running through special problems in robot systems for rail transit State of the art research in robotics and railway systems is presented alongside a series of real world examples Eight chapters give definitions and characteristics of rail transit robot systems describe assembly and collaborative robots in manufacturing introduce automated guided vehicles and autonomous rail rapid transit demonstrate inspection robots cover trench robots and explain unmanned aerial vehicles This book offers an integrated and highly practical way to approach robotics and artificial intelligence in rail transit Introduces robot and artificial intelligence AI systems for rail transit applications Presents research alongside step by step coverage of real world cases Gives the theoretical foundations

underlying practical application Offers solutions for high speed railways from the latest work in robotics Shows how robotics and AI systems afford new and efficient methods in rail transit

World Congress on Medical Physics and Biomedical Engineering September 7 - 12, 2009 Munich, Germany Olaf Dössel, Wolfgang C. Schlegel, 2010-01-06 Present Your Research to the World The World Congress 2009 on Medical Physics and Biomedical Engineering the triennial scientific meeting of the IUPESM is the world's leading forum for presenting the results of current scientific work in health related physics and technologies to an international audience With more than 2 800 presentations it will be the biggest conference in the fields of Medical Physics and Biomedical Engineering in 2009 Medical physics biomedical engineering and bioengineering have been driving forces of innovation and progress in medicine and healthcare over the past two decades As new key technologies arise with significant potential to open new options in diagnostics and therapeutics it is a multidisciplinary task to evaluate their benefit for medicine and healthcare with respect to the quality of performance and therapeutic output Covering key aspects such as information and communication technologies micro and nanosystems optics and biotechnology the congress will serve as an inter and multidisciplinary platform that brings together people from basic research R D industry and medical application to discuss these issues As a major event for science medicine and technology the congress provides a comprehensive overview and in depth first hand information on new developments advanced technologies and current and future applications With this Final Program we would like to give you an overview of the dimension of the congress and invite you to join us in Munich Olaf Dössel Congress President Wolfgang C

Multibody Dynamics Josep M. Font-Llagunes, 2016-04-12 This book includes selected papers from the ECCOMAS Thematic Conference on Multibody Dynamics that took place in Barcelona Spain from June 29 to July 2 2015 By having its origin in analytical and continuum mechanics as well as in computer science and applied mathematics multibody dynamics provides a basis for analysis and virtual prototyping of innovative applications in many fields of contemporary engineering With the utilization of computational models and algorithms that classically belonged to different fields of applied science multibody dynamics delivers reliable simulation platforms for diverse highly developed industrial products such as vehicle and railway systems aeronautical and space vehicles robotic manipulators smart structures biomechanical systems and nanotechnologies

Scientific and Technical Aerospace Reports, 1992

Interventional Magnetic Resonance Imaging Thomas Kahn, Harald Busse, 2012-08-27 The idea of using the enormous potential of magnetic resonance imaging MRI not only for diagnostic but also for interventional purposes may seem obvious but it took major efforts by engineers physicists and clinicians to come up with dedicated interventional techniques and scanners and improvements are still ongoing Since the inception of interventional MRI in the mid 1990s the numbers of settings techniques and clinical applications have increased dramatically This state of the art book covers all aspects of interventional MRI The more technical contributions offer an overview of the fundamental ideas and concepts and present the available instrumentation The richly illustrated clinical

contributions ranging from MRI guided biopsies to completely MRI controlled therapies in various body regions provide detailed information on established and emerging applications and identify future trends and challenges *IUTAM Symposium on Vibration Control of Nonlinear Mechanisms and Structures* H. Ulbrich, W. Günthner, 2005-11-07 During the last decades the growth of micro electronics has reduced the cost of computing power to a level acceptable to industry and has made possible sophisticated control strategies suitable for many applications Vibration control is applied to all kinds of engineering systems to obtain the desired dynamic behavior improved accuracy and increased reliability during operation In this context one can think of applications related to the control of structures vibration isolation control of vehicle dynamics noise control control of machines and mechanisms and control of fluid structure interaction One could continue with this list for a long time Research in the field of vibration control is extremely comprehensive Problems that are typical for vibration control of nonlinear mechanisms and structures arise in the fields of modeling systems in such a way that the model is suitable for control design to choose appropriate actuator and sensor locations and to select the actuators and sensors The objective of the Symposium was to present and discuss methods that contribute to the solution of such problems and to demonstrate the state of the art in the field shown by typical examples The intention was to evaluate the limits of performance that can be achieved by controlling the dynamics and to point out gaps in present research and give links for areas of future research Mainly it brought together leading experts from quite different areas presenting their points of view

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