

Recent Trends on Nonlinear Filtering for Inverse Problems

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Communicated by Lorenzo Pareschi

Received on 03.26.2022. Accepted on 05.10.2022.

Abstract

Among the class of nonlinear particle filtering methods, the Ensemble Kalman Filter (EnKF) has gained recent attention for its use in solving inverse problems. We review the original method and discuss recent developments in particular in view of the limit for infinitely particles and extensions towards stability analysis and multi-objective optimization. We illustrate the performance of the method by using test inverse problems from the literature.

Keywords: Ensemble Kalman inversion, nonlinear filtering methods, inverse problems, multi-objective optimization, stability analysis

AMS subject classification: 65N21, 93E11, 35Q93, 37K35

1. Introduction

This review paper focuses on the Ensemble Kalman Filter applied to general inverse problems. In this context, some literature also uses the term Ensemble Kalman Inversion (EKI). Solving inverse problems or identification problems means determining parameters of a given model in order to obtain observable data. Due to the large range of applications, several approaches have been proposed in the literature to solve inverse problems. For instance, some well-known techniques rely on Bayesian formulation [1], but they can be extremely expensive. For this reason, efficient numerical schemes to solve the Bayesian inversion have been studied [2–4].

In this paper we are interested in solving inverse problems using a classical approach, i.e. relying on an optimization viewpoint, and in the numerical solution via the so-called particle methods. These can be divided into two classes of methods: the ones coming from particle swarm optimization, e.g. see [5] and the references therein, and the ensemble Kalman methods.

The EKI method belongs indeed to the class of particle methods and it is an iterative method for solving inverse problems. The method was originally introduced in [6] for unconstrained minimization problems, and recently extended also to the presence of different types of constraints [7–9]. The original EnKF has already been introduced more than ten years ago [10–13] as a discrete time method to estimate state variables and parameters of stochastic dynamical systems. The EKI method has become popular recently, because of the fact that it does not require derivatives of the underlying model for optimization but at the same time enjoys provable convergence results. Applications have been so far, in particular, in oceanography [14], reservoir modeling [15], weather forecasting [16], milling process [17], process control [18], geophysical applications [19–21], physics [22] and also machine learning [23–25]. The literature on Kalman filtering is very rich and we can not review this in detail here, but refer to the reference for further details. Our focus is on the reformulation of the EnKF for solving inverse problems as outlined below, in Section 1.2.

1.1. Formulation of the ensemble Kalman inversion

In order to present the mathematical formulation of the EKI method, we denote by $\mathcal{G} : X \rightarrow Y$ the given (nonlinear) forward operator between finite dimensional Hilbert spaces $X = \mathbb{R}^d$, $d \in \mathbb{N}$, and

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delegates was also highly gratifying showing the high level of interest in the subject This Proceeding provides the permanent record of what was presented They indicate the state of development at the time of writing of all aspects of this important topic and will be invaluable to all academicians and researchers in the field for that reason Finally it is appropriate that we record our thanks to our fellow members of the Technical Organizing Committee for encouraging participation from those areas We are also indebted to those who served as session chair and reviewers without their support the conference could not have been the success that it was We also acknowledge the authors themselves without whose expert input there would have been no conference Their efforts made a great contribution to its success

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Spatial Patterns L.A. Peletier, W.C. Troy, 2012-12-06 The study of spatial patterns in extended systems and their evolution with time poses challenging questions for physicists and mathematicians alike Waves on water pulses in optical fibers periodic structures in alloys folds in rock formations and cloud patterns in the sky patterns are omnipresent in the world around us Their variety and complexity make them a rich area of study In the study of these phenomena an important role is played by well chosen model equations which are often simpler than the full equations describing the physical or biological system but still capture its essential features Through a thorough analysis of these model equations one hopes to glean a better understanding of the underlying mechanisms that are responsible for the formation and evolution of complex patterns Classical model equations have typically been second order partial differential equations As an example we mention the widely studied Fisher Kolmogorov or Allen Cahn equation originally proposed in 1937 as a model for the interaction of dispersal and fitness in biological populations As another example we mention the Burgers equation proposed in 1939 to study the interaction of diffusion and nonlinear convection in an attempt to understand the phenomenon of turbulence Both of these are nonlinear second order diffusion equations **Partial Differential Equations and Mathematical Physics**

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Mathematical Reviews, 2004

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Equivariant Degree Theory Jorge Ize, Alfonso Vignoli, 2008-08-22 This book presents a new degree theory for maps which commute with a group of symmetries This degree is no longer a single integer but an element of the group of equivariant homotopy classes of maps between two spheres and depends on the orbit types of the spaces The authors develop completely the theory and applications of this degree in a self contained presentation starting with only elementary facts The first chapter explains the basic tools of representation theory homotopy theory and differential equations needed in the text Then the degree is defined and its main abstract properties are derived The next part is devoted to the study of equivariant homotopy groups of spheres and to the classification of equivariant maps in the case of abelian actions These groups are explicitly computed and the effects of symmetry breaking products and composition are thoroughly studied The last part deals with computations of the equivariant index of an isolated orbit and of an isolated loop of stationary points Here differential equations in a variety of situations are considered symmetry breaking forcing period doubling twisted orbits first integrals gradients etc Periodic solutions of Hamiltonian systems in particular spring pendulum systems are studied as well as Hopf bifurcation for all these situations

New Advances in Mechanisms, Mechanical Transmissions and Robotics Erwin-Christian Lovasz, Inocentiu Maniu, Ioan Doroftei, Mircea Ivanescu, Corina-Mihaela Gruescu, 2020-10-14 This volume gathers the proceedings of the Joint International Conference of the XIII International Conference on Mechanisms and Mechanical Transmissions MTM and the XXIV International Conference on Robotics Robotics held in Timi oara Romania It addresses the applications of mechanisms and transmissions in several modern technical fields such as mechatronics biomechanics machines micromachines robotics and apparatus In doing so it combines theoretical findings and experimental testing The book presents peer reviewed papers written by researchers specialized in mechanism analysis and synthesis dynamics of mechanisms and machines mechanical transmissions biomechanics precision mechanics mechatronics micromechanisms and microactuators computational and

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web sep 17 2022 figure 2 2 2 this is a picture of an inconsistent linear system the vector \mathbf{w} on the right hand side of the equation $x_1 \mathbf{v}_1 + x_2 \mathbf{v}_2 = \mathbf{w}$ is not in the span of $\mathbf{v}_1\ \mathbf{v}_2$ convince yourself of this by trying to solve the equation $x_1 \mathbf{v}_1 + x_2 \mathbf{v}_2 = \mathbf{w}$ by

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