Real-Time Vision
for Human-Computer
Interaction

Real Time Vision For Human Computer Interaction

De-Shuang Huang,Kang-Hyun Jo,Ling Wang

Real Time Vision For Human Computer Interaction:

Real-Time Vision for Human-Computer Interaction Branislav Kisacanin,Vladimir Pavlovic,Thomas S. Huang,2005-12-06 200Ts Vision of Vision One of my formative childhood experiences was in 1968 stepping into the Uptown Theater on Connecticut Avenue in Washington DC one of the few movie theaters nationwide that projected in large screen cinerama I was there at the urging of a friend who said I simply must see the remarkable film whose run had started the previous week You won t understand it he said but that doesn t matter All I knew was that the film was about science fiction and had great special eflPects So I sat in the front row of the balcony munched my popcorn sat back and experienced what was widely touted as the ultimate trip 2001 A Space Odyssey My friend was right I didn t understand it but in some senses that didn t matter Even today after seeing the film 40 times I continue to discover its many subtle secrets I just had the sense that I had experienced a creation of the highest aesthetic order unique fresh awe inspiring Here was a film so distinctive that the first half hour had no words whatsoever the last half hour had no words either and nearly all the words in between were banal and irrelevant to the plot quips about security through Voiceprint identification how to make a phonecall from a space station government pension plans and so on **Real-Time Vision for Human-Computer Interaction** Branislav Kisacanin,Vladimir Pavlovic,Thomas S. Huang,2005-08-23 The need for natural and effective Human Computer Interaction HCI is increasingly important due to the prevalence of computers in human activities Computer vision and pattern recognition continue to play a dominant role in the HCI realm However computer vision methods often fail to become pervasive in the field due to the lack of real time robust algorithms and novel and convincing applications This state of the art contributed volume is comprised of articles by prominent experts in computer vision pattern recognition and HCI It is the first published text to capture the latest research in this rapidly advancing field with exclusive focus on real time algorithms and practical applications in diverse and numerous industries and it outlines further challenges in these areas Real Time Vision for Human Computer Interaction is an invaluable reference for HCI researchers in both academia and industry and a useful supplement for advanced level courses in HCI and Computer Vision **Computer Vision in Human-Computer Interaction** Nicu Sebe,Michael S. Lew,Thomas S. Huang,2005-09-30 Human Computer Interaction HCI lies at the crossroads of many scienti c areas including arti cial intelligence computer vision face recognition motion tracking etc In order for HCI systems to interact seamlessly with people they need to understand their environment through vision and auditory input Mo over HCI systems should learn how to adaptively respond depending on the situation The goal of this workshop was to bring together researchers from the eld of computer vision whose work is related to human computer interaction The selected articles for this workshop address a wide range of theoretical and plication issues in human computer interaction ranging from human robot teraction gesture recognition and body tracking to facial features analysis and human computer interaction systems This year 74 papers from 18 countries were submitted and 22 were accepted for

presentation at the workshop after being reviewed by at least 3 members of the Program Committee We had therefore a very competitive acceptance rate of less than 30% and as a consequence we had a very high quality workshop Wewouldliketo thankallmembersofthe ProgramCommitteefor their help in ensuring the quality of the papers accepted for publication We are grateful to Dr Jian Wang for giving the keynote address In addition we wish to thank the organizers of the 10th IEEE International Conference on Computer Vision and our sponsors University of Amsterdam Leiden Institute of Advanced Computer Science and the University of Illinois at Urbana Champaign for support in setting up our workshop   Human Computer Interaction Kikuo Asai,2008-10-01 The book consists of 20 chapters each addressing a certain aspect of human computer interaction Each chapter gives the reader background information on a subject and proposes an original solution This should serve as a valuable tool for professionals in this interdisciplinary field Hopefully readers will contribute their own discoveries and improvements innovative ideas and concepts as well as novel applications and business models related to the field of human computer interaction It is our wish that the reader consider not only what our authors have written and the experimentation they have described but also the examples they have set   **Human-computer Interaction** Zoran Zivkovic,2013   **Computer Vision in Human-Computer Interaction** Thomas S. Huang,Nicu Sebe,Michael S. Lew,Vladimir Pavlovic,Mathias Kölsch,Aphrodite Galata,Branislav Kisacanin,2006-05-04 This book constitutes the refereed proceedings of the International Workshop on Human Computer Interaction HCI ECCV 2006 The 11 revised full papers presented were carefully reviewed and selected from 27 submissions The papers address a wide range of theoretical and application issues in human computer interaction ranging from face analysis gesture and emotion recognition and event detection to various applications in those fields   Computer Vision in Human-Computer Interaction Thomas S. Huang,2006-05-09 This book constitutes the refereed proceedings of the International Workshop on Human Computer Interaction HCI ECCV 2006 The 11 revised full papers presented were carefully reviewed and selected from 27 submissions The papers address a wide range of theoretical and application issues in human computer interaction ranging from face analysis gesture and emotion recognition and event detection to various applications in those fields   Intelligent Computing Methodologies De-Shuang Huang,Kang-Hyun Jo,Ling Wang,2014-07-05 This book in conjunction with the volumes LNCS 8588 and LNBI 8590 constitutes the refereed proceedings of the 10th International Conference on Intelligent Computing ICIC 2014 held in Taiyuan China in August 2014 The 85 papers of this volume were carefully reviewed and selected from numerous submissions The papers are organized in topical sections such as soft computing artificial bee colony algorithms unsupervised learning kernel methods and supporting vector machines machine learning fuzzy theory and algorithms image processing intelligent computing in computer vision intelligent computing in communication networks intelligent image document retrievals intelligent data analysis and prediction intelligent agent and Web applications intelligent fault diagnosis knowledge representation reasoning knowledge discovery and data mining natural language processing and computational

linguistics next gen sequencing and metagenomics intelligent computing in scheduling and engineering optimization advanced modeling control and optimization techniques for complex engineering systems complex networks and their applications time series forecasting and analysis using artificial neural networks computer human interaction using multiple visual cues and intelligent computing biometric system and security for intelligent computing **Consumer Depth Cameras for Computer Vision** Andrea Fossati,Juergen Gall,Helmut Grabner,Xiaofeng Ren,Kurt Konolige,2012-10-03 The potential of consumer depth cameras extends well beyond entertainment and gaming to real world commercial applications This authoritative text reviews the scope and impact of this rapidly growing field describing the most promising Kinect based research activities discussing significant current challenges and showcasing exciting applications Features presents contributions from an international selection of preeminent authorities in their fields from both academic and corporate research addresses the classic problem of multi view geometry of how to correlate images from different viewpoints to simultaneously estimate camera poses and world points examines human pose estimation using video rate depth images for gaming motion capture 3D human body scans and hand pose recognition for sign language parsing provides a review of approaches to various recognition problems including category and instance learning of objects and human activity recognition with a Foreword by Dr Jamie Shotton **Humanoid Robots** Armando Carlos De Pina Filho,2007-06-01 For many years the human being has been trying in all ways to recreate the complex mechanisms that form the human body Such task is extremely complicated and the results are not totally satisfactory However with increasing technological advances based on theoretical and experimental researches man gets in a way to copy or to imitate some systems of the human body These researches not only intended to create humanoid robots great part of them constituting autonomous systems but also in some way to offer a higher knowledge of the systems that form the human body objectifying possible applications in the technology of rehabilitation of human beings gathering in a whole studies related not only to Robotics but also to Biomechanics Biomimmetics Cybernetics among other areas This book presents a series of researches inspired by this ideal carried through by various researchers worldwide looking for to analyze and to discuss diverse subjects related to humanoid robots The presented contributions explore aspects about robotic hands learning language vision and locomotion **Computer Vision** Roberto Cipolla,Sebastiano Battiato,Giovanni Maria Farinella,2010-05-11 Computer vision is the science and technology of making machines that see It is concerned with the theory design and implementation of algorithms that can automatically process visual data to recognize objects track and recover their shape and spatial layout The International Computer Vision Summer School ICVSS was established in 2007 to provide both an objective and clear overview and an in depth analysis of the state of the art research in Computer Vision The courses are delivered by world renowned experts in the field from both academia and industry and cover both theoretical and practical aspects of real Computer Vision problems The school is organized every year by University of Cambridge Computer Vision and Robotics

Group and University of Catania Image Processing Lab Different topics are covered each year A summary of the past Computer Vision Summer Schools can be found at http www dmi unict it icvss This edited volume contains a selection of articles covering some of the talks and tutorials held during the first two editions of the school on topics such as Recognition Registration and Reconstruction The chapters provide an in depth overview of these challenging areas with key references to the existing literature **Vision Systems** Goro Obinata,Ashish Dutta,2007-06-01 Computer Vision is the most important key in developing autonomous navigation systems for interaction with the environment It also leads us to marvel at the functioning of our own vision system In this book we have collected the latest applications of vision research from around the world It contains both the conventional research areas like mobile robot navigation and map building and more recent applications such as micro vision etc The fist seven chapters contain the newer applications of vision like micro vision grasping using vision behavior based perception inspection of railways and humanitarian demining The later chapters deal with applications of vision in mobile robot navigation camera calibration object detection in vision search map building etc

Intelligent Robotics and Applications Jeschke Sabina,Honghai Liu,Daniel Schilberg,2011-11-29 The two volume set LNAI 7101 and 7102 constitute the refereed proceedings of the 4th International Conference on Intelligent Robotics and Applications ICIRA 2011 held in Aachen Germany in November 2011 The 122 revised full papers presented were thoroughly reviewed and selected from numerous submissions They are organized in topical sections on progress in indoor UAV robotics intelligence industrial robots rehabilitation robotics mechanisms and their applications multi robot systems robot mechanism and design parallel kinematics parallel kinematics machines and parallel robotics handling and manipulation tangibility in human machine interaction navigation and localization of mobile robot a body for the brain embodied intelligence in bio inspired robotics intelligent visual systems self optimising production systems computational intelligence robot control systems human robot interaction manipulators and applications stability dynamics and interpolation evolutionary robotics bio inspired robotics and image processing applications *Universal Access in Ambient Intelligence Environments* Constantine Stephanidis,Michael Pieper,2007-08-23 This book constitutes the refereed proceedings of the 9th ERCIM Workshop on User Interfaces for All focusing on Universal Access in Ambient Intelligence Environments held in K nigswinter Germany in September 2006 It covers interaction platforms and techniques for ambient intelligence user and context awareness inclusive design and evaluation as well as access to information education and entertainment *Analysis and Modelling of Faces and Gestures* Wenyi Zhao,Shaogang Gong,Xiaou Tang,2005-10-26 During the last 30 years face recognition and related problems such as face detection tracking and facial expression recognition have attracted researchers from both the engineering and psychology communities In addition extensive research has been carried out to study hand and body gestures The understanding of how humans perceive these important cues has significant scientific value and extensive applications For example human computer interaction visual surveillance and smart video indexing are active application areas Aiming

towards putting such amazing perception capability onto computer systems researchers have made substantial progress However technological challenges still exist in many aspects Following a format similar to the IEEE International Workshop on Analysis and Modeling of Faces and Gestures AMFG 2003 this one day workshop AMFG 2005 provided a focused international forum to bring together well known researchers and research groups to review the status of recognition analysis and modeling of faces and gestures to discuss the challenges that we are facing and to explore future directions Overall 30 papers were selected from 90 submitted manuscripts The topics of these papers range from feature representation robust recognition learning and 3D modeling to psychology In addition two invited talks were given by Prof Kanade and Dr Phillips The technical program was organized into four oral sessions and two poster sessions This workshop would not have been possible without the timely reviews provided by the members of the Technical Program Committee under a tight schedule October 2005 Wenyi Zhao Shaogang Gong Xiaoou Tang   Visual Analysis of Behaviour Shaogang Gong,Tao Xiang,2011-05-26 This book presents a comprehensive treatment of visual analysis of behaviour from computational modelling and algorithm design perspectives Topics covers learning group activity models unsupervised behaviour profiling hierarchical behaviour discovery learning behavioural context modelling rare behaviours and man in the loop active learning examines multi camera behaviour correlation person re identification and connecting the dots for abnormal behaviour detection discusses Bayesian information criterion Bayesian networks bag of words representation canonical correlation analysis dynamic Bayesian networks Gaussian mixtures and Gibbs sampling investigates hidden conditional random fields hidden Markov models human silhouette shapes latent Dirichlet allocation local binary patterns locality preserving projection and Markov processes explores probabilistic graphical models probabilistic topic models space time interest points spectral clustering and support vector machines   **Future of Intelligent and Extelligent Health Environment** R.G. Bushko,2005-11-28 The technology on our body in our body and all around us enhances our health and well being from conception to death This environment is emerging now with intelligent caring machines cyborgs wireless embedded continuous computing healthwear sensors healthons nanomedicine adaptive process control mathematical modeling and common sense systems The human body and the world in which it functions is a continuously changing complex adaptive system We are able to collect more and more data about it but the real challenge is to infer local dynamics from that data Intelligent Caring Biomechatronic Creatures and Healthmaticians mathematicians serving human health have a better chance of inferring the dynamics that needs to be understood than human physicians Humans can only process comfortably three dimensions while computers can see infinite number of dimensions We will need to trust the distributed network of healthons Intelligent Caring Creatures and NURSES New Unified Resource System Engineers to create Health Extelligence We need new vocabulary to push forward in a new way For instance healthons are tools combining prevention with diagnosis and treatment based on continuous monitoring and analyzing of our vital signs and biochemistry The Healthon

Era is just beginning We are closer and closer to the world with healthons on your body in your body and all around you where not a doctor but your primary care healthmatician warns you about an approaching headache and where NURSE programs your intelligent caring creatures so they can talk to your cells and stop disease in its tracks **Smart Cameras** Ahmed Nabil Belbachir,2009-10-20 A smart camera is an integrated machine vision system which in addition to image capture circuitry includes a processor which can extract information from images without need for an external processing unit and interface devices used to make results available to other devices This book provides content on smart cameras for an interdisciplinary audience of professionals and students in embedded systems image processing and camera technology It serves as a self contained single source reference for material otherwise found only in sources such as conference proceedings journal articles or product data sheets Coverage includes the 50 year chronology of smart cameras their technical evolution the state of the art and numerous applications such as surveillance and monitoring robotics and transportation *Robot Vision* Reinhard Klette,Shmuel Peleg,Gerald Sommer,2003-06-29 This book constitutes the refereed proceedings of the International Workshop on Robot Vision RobVis 2001 held in Auckland New Zealand in February 2001 The 17 revised full papers presented together with 17 posters were carefully reviewed and selected from 52 submissions The papers and posters are organized in topical sections on active perception computer vision robotics and video computational stereo robotic vision and image acquisition **Emerging Trends in IoT and Computing Technologies** Suman Lata Tripathi,Devendra Agarwal,Anita Pal,Yusuf Perwej,2024-08-29 Second International Conference on Emerging Trends in IOT and Computing Technologies ICEICT 2023 is organised with a vision to address the various issues to promote the creation of intelligent solution for the future It is expected that researchers will bring new prospects for collaboration across disciplines and gain ideas facilitating novel concepts Second International Conference of Emerging Trends in IoT and Computer Technologies ICEICT 2023 is an inventive event organised in Goel Institute of Technology and Management Lucknow India with motive to make available an open International forum for the researches academicians technocrats scientist engineers industrialist and students around the globe to exchange their innovations and share the research outcomes which may lead the young researchers academicians and industrialist to contribute to the global society The conference ICEICT 2023 is being organised at Goel Institute of Technology and Management Lucknow Uttar Pradesh during 12 13 January 2024 It will feature world class keynote speakers special sessions along with the regular oral paper presentations The conference welcomes paper submissions from researcher practitioners academicians and students will cover numerous tracks in the field of Computer Science and Engineering and associated research areas

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