

ONTOLOGICALLY  
CONTROLLED  
AUTONOMOUS  
SYSTEMS:  
PRINCIPLES,  
OPERATIONS AND  
ARCHITECTURE

GEORGE A. FODOR

KLUWER ACADEMIC PUBLISHERS

# Ontologically Controlled Autonomous Systems Principles Operations And Architecture

**George A. Fodor**



## **Ontologically Controlled Autonomous Systems Principles Operations And Architecture:**

**Ontologically Controlled Autonomous Systems: Principles, Operations, and Architecture** George A.

Fodor, 2013-11-27 Kevin M Passino When confronted with a control problem for complicated physical process a control engineer usually follows a predetermined design procedure This procedure often begins with the engineer seeking to understand the process and the primary control objectives A simple example of a control problem is an automobile cruise control that provides the automobile with the capability of regulating its own speed at a driver specified set point e g 55 mph One solution to the automotive cruise control problem involves adding an electronic controller that can sense the speed of the vehicle via the speedometer and actuate the throttle position so as to regulate the vehicle speed at the driver specified value Such speed regulation must be accurate even if there are road grade changes head winds or variations in the number of passengers in the automobile After gaining an intuitive understanding of the plant's dynamics and establishing the design objectives the control engineer typically solves the cruise control problem by using an established design procedure In particular this control engineering design methodology involves 1 Modeling understanding the plant 2 Construction of a controller to meet specifications such as stability rise time overshoot and steady state error 3 Analysis to make sure that the system will meet the performance objectives e g we might use mathematical simulation based or experimental analysis and 4 Iterating on the design until it is possible to commission the control system

**Aspects of Soft Computing, Intelligent Robotics and Control** János Fodor, 2009-10-13 Soft computing as a collection of techniques exploiting approximation and tolerance for imprecision and uncertainty in traditionally intractable problems has become very effective and popular especially because of the synergy derived from its components The integration of constituent technologies provides complementary methods that allow developing flexible computing tools and solving complex problems A wide area of natural applications of soft computing techniques consists of the control of dynamic systems including robots Loosely speaking control can be understood as driving a process to attain a desired goal Intelligent control can be seen as an extension of this concept to include autonomous human like interactions of a machine with the environment Intelligent robots can be characterized by the ability to operate in an uncertain changing environment with the help of appropriate sensing They have the power to autonomously plan and execute motion sequences to achieve a goal specified by a human user without detailed instructions In this volume leading specialists address various theoretical and practical aspects in soft computing intelligent robotics and control The problems discussed are taken from fuzzy systems neural networks interactive evolutionary computation intelligent mobile robotics and intelligent control of linear and nonlinear dynamic systems

**Ontologically Controlled Autonomous Systems** George A. Fodor, 1998 *Intelligent Information Technologies: Concepts, Methodologies, Tools, and Applications* Sugumaran, Vijayan, 2007-11-30 This set compiles more than 240 chapters from the world's leading experts to provide a foundational body of research to drive further evolution and innovation of these next

generation technologies and their applications of which scientific technological and commercial communities have only begun to scratch the surface      **Ubiquitous Computing: Design, Implementation and Usability** Theng, Yin-Leng, Duh, Henry B. L., 2008-05-31 Interactive systems in the mobile ubiquitous and virtual environments are at a stage of development where designers and developers are keen to find out more about design use and usability of these systems Ubiquitous Computing Design Implementation and Usability highlights the emergent usability theories techniques tools and best practices in these environments This book shows that usable and useful systems are able to be achieved in ways that will improve usability to enhance user experiences Research on the usability issues for young children teenagers adults and the elderly is presented with different techniques for the mobile ubiquitous and virtual environments      *Artificial Intelligence and Integrated Intelligent Information Systems* Xuan F. Zha, 2007-01-01 Researchers in the evolving fields of artificial intelligence and information systems are constantly presented with new challenges Artificial Intelligence and Integrated Intelligent Information Systems Emerging Technologies and Applications provides both researchers and professionals with the latest knowledge applied to customized logic systems agent based approaches to modeling and human based models Artificial Intelligence and Integrated Intelligent Information Systems Emerging Technologies and Applications presents the recent advances in multi mobile agent systems the product development process fuzzy logic systems neural networks and ambient intelligent environments among many other innovations in this exciting field      *Proceedings, IEEE Control Systems Society ... Symposium on Computer-Aided Control System Design (CACSD).* , 1999      Intelligent Information Technologies Vijayan Sugumaran, 2008 This collection compiles research to drive further evolution and innovation of these next generation technologies and their applications of which the scientific technological and commercial communities have only begun to scratch the surface It is an essential reference acquisition for any library seeking to cover the leading edge of technological innovations Provided by publisher      Annual Meeting of the North American Fuzzy Information Processing Society--NAFIPS. North American Fuzzy Information Processing Society. Annual Meeting, 2005      Forthcoming Books Rose Arny, 1998-04

**The British National Bibliography** Arthur James Wells, 1999      **Service Oriented, Holonic and Multi-agent Manufacturing Systems for Industry of the Future** Theodor Borangiu, Damien Trentesaux, Paulo Leitão, Christoph Legat, 2025-08-03 This book centres on methods and tools for data sharing in a secure way and on value adding application of artificial intelligence AI in industrial production and logistics for the transformation to data driven industry of the future The scientific theme of the book is Industrial Artificial Intelligence in the Data driven Industry of the Future Models Architectures and Applications which is focused on exploring the intricacies of cross enterprise data sharing and the strategic use of AI within manufacturing systems An important analysis is offered to reveal the interconnections between research regulation and standardization of artificial intelligence and digital twins in Industry 4.0 from an European perspective The novelty of this approach consists in analysing the ethical risks associated with the use of generative AI techniques in industrial systems

and their short medium and long term impact on performance and human well being protection The general scope of the book is to foster innovation in smart and sustainable manufacturing and logistics systems and in this context to promote concepts methods and solutions for the digital transformation of manufacturing through service orientation in holonic and agent based control with distributed intelligence The book s readership is comprised by researchers and engineers working in the value chain of products and processes including material sourcing production consumption and disposal recycling processes who develop digital control solutions in the Industry of the Future vision The book also addresses to master and Ph D students enrolled in engineering sciences programs

**American Book Publishing Record** ,1997      **Service Science, Management, and Engineering:** Gang Xiong,Zhong Liu,Xiwei Liu,Fenghua Zhu,Dong Shen,2012-04-12 The Intelligent Systems Series comprises titles that present state of the art knowledge and the latest advances in intelligent systems Its scope includes theoretical studies design methods and real world implementations and applications Service Science Management and Engineering presents the latest issues and development in service science Both theory and applications issues are covered in this book which integrates a variety of disciplines including engineering management and information systems These topics are each related to service science from various perspectives and the book is supported throughout by applications and case studies that showcase best practice and provide insight and guidelines to assist in building successful service systems Presents the latest research on service science management and engineering from both theory and applications perspectives Includes coverage of applications in high growth sectors along with real world frameworks and design techniques Applications and case studies showcase best practices and provide insights and guidelines to those building and managing service systems

**Automation and Control** Aleksandar Rodic,2009-12-01 The present edited book is a collection of 18 chapters written by internationally recognized experts and well known professionals of the field Chapters contribute to diverse facets of automation and control The volume is organized in four parts according to the main subjects regarding the recent advances in this field of engineering The first thematic part of the book is devoted to automation This includes solving of assembly line balancing problem and design of software architecture for cognitive assembling in production systems The second part of the book concerns different aspects of modelling and control This includes a study on modelling pollutant emission of diesel engine development of a PLC program obtained from DEVS model control networks for digital home automatic control of temperature and flow in heat exchanger and non linear analysis and design of phase locked loops The third part addresses issues of parameter estimation and filter design including methods for parameters estimation control and design of the wave digital filters The fourth part presents new results in the intelligent control This includes building a neural PDF strategy for hydroelectric satation simulator intelligent network system for process control neural generalized predictive control for industrial processes intelligent system for forecasting diagnosis and decision making based on neural networks and self organizing maps development of a smart semantic middleware for the Internet development of

appropriate AI methods in fault tolerant control building expert system in rotary railcar dumpers expert system for plant asset management and building of a image retrieval system in heterogeneous database The content of this thematic book admirably reflects the complementary aspects of theory and practice which have taken place in the last years Certainly the content of this book will serve as a valuable overview of theoretical and practical methods in control and automation to those who deal with engineering and research in this field of activities      Cumulative Book Index ,1998 A world list of books in the English language      **Subject Guide to Books in Print** ,1991      *Cooperating Robots for Flexible Manufacturing* Sotiris Makris,2020-09-30 This book consolidates the current state of knowledge on implementing cooperating robot based systems to increase the flexibility of manufacturing systems It is based on the concrete experiences of experts practitioners and engineers in implementing cooperating robot systems for more flexible manufacturing systems Thanks to the great variety of manufacturing systems that we had the opportunity to study a remarkable collection of methods and tools has emerged The aim of the book is to share this experience with academia and industry practitioners seeking to improve manufacturing practice While there are various books on teaching principles for robotics this book offers a unique opportunity to dive into the practical aspects of implementing complex real world robotic applications As it is used in this book the term cooperating robots refers to robots that either cooperate with one another or with people The book investigates various aspects of cooperation in the context of implementing flexible manufacturing systems Accordingly manufacturing systems are the main focus in the discussion on implementing such robotic systems The book begins with a brief introduction to the concept of manufacturing systems followed by a discussion of flexibility Aspects of designing such systems e g material flow logistics processing times shop floor footprint and design of flexible handling systems are subsequently covered In closing the book addresses key issues in operating such systems which concern e g decision making autonomy cooperation communication task scheduling motion generation and distribution of control between different devices Reviewing the state of the art and presenting the latest innovations the book offers a valuable asset for a broad readership      Human-Robot Interaction Paolo Barattini,Federico Vicentini,Gurvinder Singh Virk,Tamas Haidegger,2019-04-12 Human Robot Interaction Safety Standardization and Benchmarking provides a comprehensive introduction to the new scenarios emerging where humans and robots interact in various environments and applications on a daily basis The focus is on the current status and foreseeable implications of robot safety approaching these issues from the standardization and benchmarking perspectives Featuring contributions from leading experts the book presents state of the art research and includes real world applications and use cases It explores the key leading sectors robotics service robotics and medical robotics and elaborates on the safety approaches that are being developed for effective human robot interaction including physical robot human contacts collaboration in task execution workspace sharing human aware motion planning and exploring the landscape of relevant standards and guidelines Features Presenting a comprehensive introduction to human robot interaction in a number of

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