

# Lecture Notes in Computer Science

1998

Reinhard Klette · Shmuel Peleg  
Gerald Sommer (Eds.)

## Robot Vision

International Workshop RobViz 2000  
Auckland, New Zealand, February 2000  
Proceedings



Springer

**Robot Vision International Workshop Robvis 2001**  
**Auckland New Zealand February 1618 2001 Proceedings**

**Gerald Sommer, Reinhard Klette**



## **Robot Vision International Workshop Robvis 2001 Auckland New Zealand February 16-18 2001 Proceedings:**

**Robot Vision** Reinhard Klette, Shmuel Peleg, Gerald Sommer, 2003-06-29 This book constitutes the refereed proceedings of the International Workshop on Robot Vision RobVis 2001 held in Auckland New Zealand in February 2001. The 17 revised full papers presented together with 17 posters were carefully reviewed and selected from 52 submissions. The papers and posters are organized in topical sections on active perception, computer vision, robotics, and video, computational stereo, robotic vision, and image acquisition.

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**Robot Vision** International Workshop on Robot Vision, 2001

**Robot Vision** Gerald Sommer, Reinhard Klette, 2008-01-29 In 1986 B. K. P. Horn published a book entitled *Robot Vision* which actually discussed a wider field of subjects, basically addressing the field of computer vision but introducing robot vision as a technical term. Since then the interaction between computer vision and research on mobile systems, often called robots, e.g. in an industrial context but also including vehicles such as cars, wheelchairs, tower cranes, and so forth, established a diverse area of research today known as robot vision. Robot vision or more general robotics is a fast growing discipline already taught as a dedicated teaching program at university level. The term robot vision addresses any autonomous behavior of a technical system supported by visual sensoric information. While robot vision focusses on the vision process, visual robotics is more directed toward control and automatization. In practice, however, both fields strongly interact. Robot Vision 2008 was the second international workshop, counting a 2001 workshop with identical name as the first in this series. Both workshops were organized in close cooperation between researchers from New Zealand and Germany and took place at The University of Auckland, New Zealand. Participants of the 2008 workshop came from Europe, USA, South America, the Middle East, the Far East, Australia, and of course from New Zealand.

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**Table of Contents Robot Vision International Workshop Robvis 2001 Auckland New Zealand February 1618 2001 Proceedings**

1. Understanding the eBook Robot Vision International Workshop Robvis 2001 Auckland New Zealand February 1618 2001 Proceedings
  - The Rise of Digital Reading Robot Vision International Workshop Robvis 2001 Auckland New Zealand February 1618 2001 Proceedings
  - Advantages of eBooks Over Traditional Books
2. Identifying Robot Vision International Workshop Robvis 2001 Auckland New Zealand February 1618 2001 Proceedings
  - Exploring Different Genres
  - Considering Fiction vs. Non-Fiction
  - Determining Your Reading Goals

3. Choosing the Right eBook Platform
  - Popular eBook Platforms
  - Features to Look for in an Robot Vision International Workshop Robvis 2001 Auckland New Zealand February 1618 2001 Proceedings
  - User-Friendly Interface
4. Exploring eBook Recommendations from Robot Vision International Workshop Robvis 2001 Auckland New Zealand February 1618 2001 Proceedings
  - Personalized Recommendations
  - Robot Vision International Workshop Robvis 2001 Auckland New Zealand February 1618 2001 Proceedings User Reviews and Ratings
  - Robot Vision International Workshop Robvis 2001 Auckland New Zealand February 1618 2001 Proceedings and Bestseller Lists
5. Accessing Robot Vision International Workshop Robvis 2001 Auckland New Zealand February 1618 2001 Proceedings Free and Paid eBooks
  - Robot Vision International Workshop Robvis 2001 Auckland New Zealand February 1618 2001 Proceedings Public Domain eBooks
  - Robot Vision International Workshop Robvis 2001 Auckland New Zealand February 1618 2001 Proceedings eBook Subscription Services
  - Robot Vision International Workshop Robvis 2001 Auckland New Zealand February 1618 2001 Proceedings Budget-Friendly Options
6. Navigating Robot Vision International Workshop Robvis 2001 Auckland New Zealand February 1618 2001 Proceedings eBook Formats
  - ePub, PDF, MOBI, and More
  - Robot Vision International Workshop Robvis 2001 Auckland New Zealand February 1618 2001 Proceedings Compatibility with Devices
  - Robot Vision International Workshop Robvis 2001 Auckland New Zealand February 1618 2001 Proceedings Enhanced eBook Features
7. Enhancing Your Reading Experience
  - Adjustable Fonts and Text Sizes of Robot Vision International Workshop Robvis 2001 Auckland New Zealand February 1618 2001 Proceedings

- Highlighting and Note-Taking Robot Vision International Workshop Robvis 2001 Auckland New Zealand February 1618 2001 Proceedings
- Interactive Elements Robot Vision International Workshop Robvis 2001 Auckland New Zealand February 1618 2001 Proceedings
- 8. Staying Engaged with Robot Vision International Workshop Robvis 2001 Auckland New Zealand February 1618 2001 Proceedings
  - Joining Online Reading Communities
  - Participating in Virtual Book Clubs
  - Following Authors and Publishers Robot Vision International Workshop Robvis 2001 Auckland New Zealand February 1618 2001 Proceedings
- 9. Balancing eBooks and Physical Books Robot Vision International Workshop Robvis 2001 Auckland New Zealand February 1618 2001 Proceedings
  - Benefits of a Digital Library
  - Creating a Diverse Reading Collection Robot Vision International Workshop Robvis 2001 Auckland New Zealand February 1618 2001 Proceedings
- 10. Overcoming Reading Challenges
  - Dealing with Digital Eye Strain
  - Minimizing Distractions
  - Managing Screen Time
- 11. Cultivating a Reading Routine Robot Vision International Workshop Robvis 2001 Auckland New Zealand February 1618 2001 Proceedings
  - Setting Reading Goals Robot Vision International Workshop Robvis 2001 Auckland New Zealand February 1618 2001 Proceedings
  - Carving Out Dedicated Reading Time
- 12. Sourcing Reliable Information of Robot Vision International Workshop Robvis 2001 Auckland New Zealand February 1618 2001 Proceedings
  - Fact-Checking eBook Content of Robot Vision International Workshop Robvis 2001 Auckland New Zealand February 1618 2001 Proceedings
  - Distinguishing Credible Sources
- 13. Promoting Lifelong Learning

- Utilizing eBooks for Skill Development
- Exploring Educational eBooks

14. Embracing eBook Trends

- Integration of Multimedia Elements
- Interactive and Gamified eBooks

## **Robot Vision International Workshop Robvis 2001 Auckland New Zealand February 1618 2001 Proceedings Introduction**

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