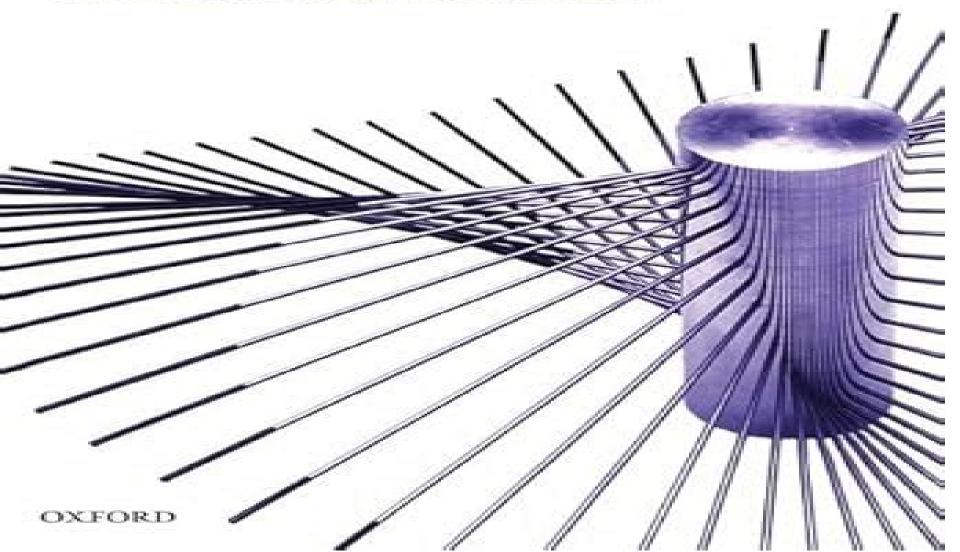
## ROBOTS AND SCREW THEORY

applications of kinematics and statics to robotics

### J. K. DAVIDSON | K. H. HUNT



# **Robots And Screw Theory Applications Of Kinematics And Statics To Robotics**

J Elliott

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