



# ROBOT SHAPING

AN EXPERIMENT IN BEHAVIOR ENGINEERING

MARCO DORIGO AND MARCO COLOMBETTI

# Robot Shaping An Experiment In Behavior Engineering

**Fornarelli, Girolamo**



## **Robot Shaping An Experiment In Behavior Engineering:**

**Robot Shaping** Marco Dorigo, Marco Colombetti, 1998 foreword by Lashon Booker To program an autonomous robot to act reliably in a dynamic environment is a complex task The dynamics of the environment are unpredictable and the robots sensors provide noisy input A learning autonomous robot one that can acquire knowledge through interaction with its environment and then adapt its behavior greatly simplifies the designer's work A learning robot need not be given all of the details of its environment and its sensors and actuators need not be finely tuned Robot Shaping is about designing and building learning autonomous robots The term shaping comes from experimental psychology where it describes the incremental training of animals The authors propose a new engineering discipline behavior engineering to provide the methodologies and tools for creating autonomous robots Their techniques are based on classifier systems a reinforcement learning architecture originated by John Holland to which they have added several new ideas such as mutesspec classifier system energy and dynamic population size In the book they present Behavior Analysis and Training BAT as an example of a behavior engineering methodology *Towards Autonomous Robotic Systems* Roderich Groß, Lyuba Alboul, Chris Melhuish, Mark Witkowski, Tony T. Prescott, Jacques Penders, 2011-08-19 This book constitutes the refereed proceedings of the 12th Annual Conference Towards Autonomous Robotics Systems TAROS 2011 held in Sheffield UK in August September 2011 The 32 revised full papers presented together with 29 two page abstracts were carefully reviewed and selected from 94 submissions Among the topics addressed are robot navigation robot learning human robot interaction robot control mobile robots reinforcement learning robot vehicles swarm robotic systems etc **Neurorobotics** Tiffany J. Hwu, Jeffrey L. Krichmar, 2022-11-29 An introduction to neurorobotics that presents approaches and design principles for developing intelligent autonomous systems grounded in biology and neuroscience Neurorobotics is an interdisciplinary field that draws on artificial intelligence cognitive sciences computer science engineering psychology neuroscience and robotics Because the brain is closely coupled to the body and situated in the environment neurorobots autonomous systems modeled after some aspect of the brain offer a powerful tool for studying neural function and may also be a means for developing autonomous systems with intelligence that rivals that of biological organisms This textbook introduces approaches and design principles for developing intelligent autonomous systems grounded in biology and neuroscience It is written for anyone interested in learning about this topic and can be used in cognitive robotics courses for students in psychology cognitive science and computer science Neurorobotics covers the background and foundations of the field with information on early neurorobots relevant principles of neuroscience learning rules and mechanisms and reinforcement learning and prediction neurorobot design principles grounded in neuroscience and principles of neuroscience research and examples of neurorobots for navigation developmental robotics and social robots presented with the cognitive science and neuroscience background that inspired them A supplementary website offers videos robot simulations and links to software repositories with neurorobot

examples     **The Logic of Adaptive Behavior** Martijn van Otterlo,2009 Markov decision processes have become the de facto standard in modeling and solving sequential decision making problems under uncertainty This book studies lifting Markov decision processes reinforcement learning and dynamic programming to the first order or relational setting     **The Art of Agent-oriented Modeling** Leon Sterling,Kuldar Taveter,2009 The Art of Agent Oriented Modeling is an introduction to agent oriented software development for students and for software developers who are interested in learning about new software engineering techniques Foreword     **Mobile Microrobotics** Metin Sitti,2017-06-16 The first textbook on micron scale mobile robotics introducing the fundamentals of design analysis fabrication and control and drawing on case studies of existing approaches Progress in micro and nano scale science and technology has created a demand for new microsystems for high impact applications in healthcare biotechnology manufacturing and mobile sensor networks The new robotics field of microrobotics has emerged to extend our interactions and explorations to sub millimeter scales This is the first textbook on micron scale mobile robotics introducing the fundamentals of design analysis fabrication and control and drawing on case studies of existing approaches The book covers the scaling laws that can be used to determine the dominant forces and effects at the micron scale models forces acting on microrobots including surface forces friction and viscous drag and describes such possible microfabrication techniques as photo lithography bulk micromachining and deep reactive ion etching It presents on board and remote sensing methods noting that remote sensors are currently more feasible studies possible on board microactuators discusses self propulsion methods that use self generated local gradients and fields or biological cells in liquid environments and describes remote microrobot actuation methods for use in limited spaces such as inside the human body It covers possible on board powering methods indispensable in future medical and other applications locomotion methods for robots on surfaces in liquids in air and on fluid air interfaces and the challenges of microrobot localization and control in particular multi robot control methods for magnetic microrobots Finally the book addresses current and future applications including noninvasive medical diagnosis and treatment environmental remediation and scientific tools

**RoboCup 2003: Robot Soccer World Cup VII** Daniel Polani,Brett Browning,Andrea Bonarini,Kazuo Yoshida,2004-09-02 This book constitutes the seventh official archival publication devoted to RoboCup It documents the achievements presented at the 7th Robot World Cup Soccer and Rescue Competition and Conferences held in Padua Italy in July 2003 The 39 revised full papers and 35 revised poster papers presented together with an overview and roadmap for the RoboCup initiative and 3 invited papers were carefully reviewed and selected from 125 symposium paper submissions This book is mandatory reading for the rapidly growing RoboCup community as well as a valuable source of reference and inspiration for R D professionals interested in robotics distributed artificial intelligence and multi agent systems

**Shepherding UxVs for Human-Swarm Teaming** Hussein A. Abbass,Robert A. Hunjet,2021-03-19 This book draws inspiration from natural shepherding whereby a farmer utilizes sheepdogs to herd sheep to inspire a scalable and inherently

human friendly approach to swarm control The book discusses advanced artificial intelligence AI approaches needed to design smart robotic shepherding agents capable of controlling biological swarms or robotic swarms of unmanned vehicles These smart shepherding agents are described with the techniques applicable to the control of Unmanned X Vehicles UxVs including air unmanned aerial vehicles or UAVs ground unmanned ground vehicles or UGVs underwater unmanned underwater vehicles or UUVs and on the surface of water unmanned surface vehicles or USVs This book proposes how smart shepherds could be designed and used to guide a swarm of UxVs to achieve a goal while ameliorating typical communication bandwidth issues that arise in the control of multi agent systems The book covers a wide range of topics ranging from the design of deep reinforcement learning models for shepherding a swarm transparency in swarm guidance and ontology guided learning to the design of smart swarm guidance methods for shepherding with UGVs and UAVs The book extends the discussion to human swarm teaming by looking into the real time analysis of human data during human swarm interaction the concept of trust for human swarm teaming and the design of activity recognition systems for shepherding Presents a comprehensive look at human swarm teaming Tackles artificial intelligence techniques for swarm guidance Provides artificial intelligence techniques for real time human performance analysis     Autonomous Bidding Agents Michael P. Wellman, Amy Greenwald, Peter Stone, 2007 E commerce increasingly provides opportunities for autonomous bidding agents computer programs that bid in electronic markets without direct human intervention Automated bidding strategies for an auction of a single good with a known valuation are fairly straightforward designing strategies for simultaneous auctions with interdependent valuations is a more complex undertaking This book presents algorithmic advances and strategy ideas within an integrated bidding agent architecture that have emerged from recent work in this fast growing area of research in academia and industry The authors analyze several novel bidding approaches that developed from the Trading Agent Competition TAC held annually since 2000 The benchmark challenge for competing agents to buy and sell multiple goods with interdependent valuations in simultaneous auctions of different types encourages competitors to apply innovative techniques to a common task The book traces the evolution of TAC and follows selected agents from conception through several competitions presenting and analyzing detailed algorithms developed for autonomous bidding Autonomous Bidding Agents provides the first integrated treatment of methods in this rapidly developing domain of AI The authors who introduced TAC and created some of its most successful agents offer both an overview of current research and new results Michael P Wellman is Professor of Computer Science and Engineering and member of the Artificial Intelligence Laboratory at the University of Michigan Ann Arbor Amy Greenwald is Assistant Professor of Computer Science at Brown University Peter Stone is Assistant Professor of Computer Sciences Alfred P Sloan Research Fellow and Director of the Learning Agents Group at the University of Texas Austin He is the recipient of the International Joint Conference on Artificial Intelligence IJCAI 2007 Computers and Thought Award     Nature Inspired Problem-Solving Methods in Knowledge Engineering José

Mira, José R. Álvarez, 2007-06-23 The second of a two volume set this book constitutes the refereed proceedings of the Second International Work Conference on the Interplay between Natural and Artificial Computation IWINAC 2007 held in La Manga del Mar Menor Spain in June 2007 It contains all the contributions connected with biologically inspired methods and techniques for solving AI and knowledge engineering problems in different application domains **Encyclopedia of Artificial Intelligence** Rabuñal Dopico, Juan Ramón, Dorado, Julian, Pazos, Alejandro, 2008-07-31 This book is a comprehensive and in depth reference to the most recent developments in the field covering theoretical developments techniques technologies among others Provided by publisher **Mechanics of Robotic Manipulation** Matthew T. Mason, 2001-06-08 The science and engineering of robotic manipulation Manipulation refers to a variety of physical changes made to the world around us Mechanics of Robotic Manipulation addresses one form of robotic manipulation moving objects and the various processes involved grasping carrying pushing dropping throwing and so on Unlike most books on the subject it focuses on manipulation rather than manipulators This attention to processes rather than devices allows a more fundamental approach leading to results that apply to a broad range of devices not just robotic arms The book draws both on classical mechanics and on classical planning which introduces the element of imperfect information The book does not propose a specific solution to the problem of manipulation but rather outlines a path of inquiry **Swarm Intelligence for Electric and Electronic Engineering** Fornarelli, Girolamo, 2012-12-31 With growing developments in artificial intelligence and focus on swarm behaviors algorithms have been utilized in solving a variety of problems in the field of engineering This approach has been specifically suited to face the challenges in electric and electronic engineering Swarm Intelligence for Electric and Electronic Engineering provides an exchange of knowledge on the advances discoveries and improvements of swarm intelligence in electric and electronic engineering This comprehensive collection aims to bring together new swarm based algorithms as well as approaches to complex problems and various real world applications **Autonomous Robots** George A. Bekey, 2005 An introduction to the science and practice of autonomous robots that reviews over 300 current systems and examines the underlying technology **The Developmental Organization of Robot Behavior** Roderic A. Grupen, 2023-03-14 A comprehensive introduction to the mathematical foundations of movement and actuation that apply equally to animals and machines This textbook offers a computational framework for the sensorimotor stage of development as applied to robotics Much work in developmental robotics is based on ad hoc examples without a full computational basis This book s comprehensive and complete treatment fills the gap drawing on the principal mechanisms of development in the first year of life to introduce what is essentially an operating system for developing robots The goal is to apply principles of development to robot systems that not only achieve new levels of performance but also provide evidence for scientific theories of human development Artificial Intelligence, Evolutionary Computing and Metaheuristics Xin-She Yang, 2012-07-27 Alan Turing pioneered many research areas such as artificial intelligence computability heuristics and

pattern formation Nowadays at the information age it is hard to imagine how the world would be without computers and the Internet Without Turing's work especially the core concept of Turing Machine at the heart of every computer mobile phone and microchip today so many things on which we are so dependent would be impossible 2012 is the Alan Turing year a centenary celebration of the life and work of Alan Turing To celebrate Turing's legacy and follow the footsteps of this brilliant mind we take this golden opportunity to review the latest developments in areas of artificial intelligence evolutionary computation and metaheuristics and all these areas can be traced back to Turing's pioneer work Topics include Turing test Turing machine artificial intelligence cryptography software testing image processing neural networks nature inspired algorithms such as bat algorithm and cuckoo search and multiobjective optimization and many applications These reviews and chapters not only provide a timely snapshot of the state of art developments but also provide inspiration for young researchers to carry out potentially ground breaking research in the active diverse research areas in artificial intelligence cryptography machine learning evolutionary computation and nature inspired metaheuristics This edited book can serve as a timely reference for graduates researchers and engineers in artificial intelligence computer sciences computational intelligence soft computing optimization and applied sciences

Strategic Negotiation in Multiagent Environments Sarit Kraus, 2001 A model for strategic negotiation for intelligent agents

**Layered Learning in Multiagent Systems** Peter Stone, 2000-03-03 This book looks at multiagent systems that consist of teams of autonomous agents acting in real time noisy collaborative and adversarial environments This book looks at multiagent systems that consist of teams of autonomous agents acting in real time noisy collaborative and adversarial environments The book makes four main contributions to the fields of machine learning and multiagent systems First it describes an architecture within which a flexible team structure allows member agents to decompose a task into flexible roles and to switch roles while acting Second it presents layered learning a general purpose machine learning method for complex domains in which learning a mapping directly from agents sensors to their actuators is intractable with existing machine learning methods Third the book introduces a new multiagent reinforcement learning algorithm team partitioned opaque transition reinforcement learning TPOT RL designed for domains in which agents cannot necessarily observe the state changes caused by other agents actions The final contribution is a fully functioning multiagent system that incorporates learning in a real time noisy domain with teammates and adversaries a computer simulated robotic soccer team Peter Stone's work is the basis for the CMUnited Robotic Soccer Team which has dominated recent RoboCup competitions RoboCup not only helps roboticists to prove their theories in a realistic situation but has drawn considerable public and professional attention to the field of intelligent robotics The CMUnited team won the 1999 Stockholm simulator competition outscoring its opponents by the rather impressive cumulative score of 110 0

Springer Handbook of Robotics Bruno Siciliano, Oussama Khatib, 2016-07-27 The second edition of this handbook provides a state of the art overview on the various aspects in the rapidly developing field of robotics Reaching for the human frontier robotics is

vigorously engaged in the growing challenges of new emerging domains Interacting exploring and working with humans the new generation of robots will increasingly touch people and their lives The credible prospect of practical robots among humans is the result of the scientific endeavour of a half a century of robotic developments that established robotics as a modern scientific discipline The ongoing vibrant expansion and strong growth of the field during the last decade has fueled this second edition of the Springer Handbook of Robotics The first edition of the handbook soon became a landmark in robotics publishing and won the American Association of Publishers PROSE Award for Excellence in Physical Sciences Mathematics as well as the organization s Award for Engineering Technology The second edition of the handbook edited by two internationally renowned scientists with the support of an outstanding team of seven part editors and more than 200 authors continues to be an authoritative reference for robotics researchers newcomers to the field and scholars from related disciplines The contents have been restructured to achieve four main objectives the enlargement of foundational topics for robotics the enlightenment of design of various types of robotic systems the extension of the treatment on robots moving in the environment and the enrichment of advanced robotics applications Further to an extensive update fifteen new chapters have been introduced on emerging topics and a new generation of authors have joined the handbook s team A novel addition to the second edition is a comprehensive collection of multimedia references to more than 700 videos which bring valuable insight into the contents The videos can be viewed directly augmented into the text with a smartphone or tablet using a unique and specially designed app Springer Handbook of Robotics Multimedia Extension Portal <http://handbookofrobotics.org>

**Reasoning about Rational Agents** Michael Wooldridge, 2003-01-01 This book focuses on the belief desire intention BDI model of rational agents which recognizes the primacy of beliefs desires and intentions in rational action One goal of modern computer science is to engineer computer programs that can act as autonomous rational agents software that can independently make good decisions about what actions to perform on our behalf and execute those actions Applications range from small programs that intelligently search the Web buying and selling goods via electronic commerce to autonomous space probes This book focuses on the belief desire intention BDI model of rational agents which recognizes the primacy of beliefs desires and intentions in rational action The BDI model has three distinct strengths an underlying philosophy based on practical reasoning in humans a software architecture that is implementable in real systems and a family of logics that support a formal theory of rational agency The book introduces a BDI logic called LORA Logic of Rational Agents In addition to the BDI component LORA contains a temporal component which allows one to represent the dynamics of how agents and their environments change over time and an action component which allows one to represent the actions that agents perform and the effects of the actions The book shows how LORA can be used to capture many components of a theory of rational agency including such notions as communication and cooperation



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