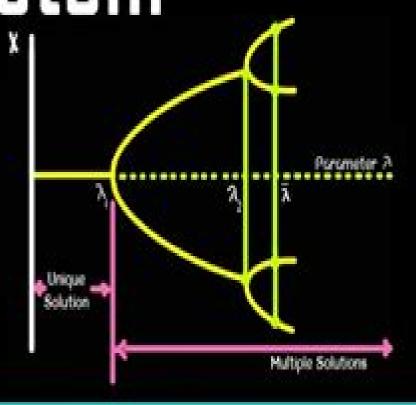
Introduction to Nonlinear Control System



Nonlinear Control Systems An Introduction

Alberto Isidori

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controllability and optimality and on the corresponding geometry associated with these topics Each chapter contains several examples and a variety of exercises Nonlinear Control Systems II Alberto Isidori, 2012-10-21 This eagerly awaited follow up to Nonlinear Control Systems incorporates recent advances in the design of feedback laws for the purpose of globally stabilizing nonlinear systems via state or output feedback. The author is one of the most prominent researchers in the Analysis and Design of Nonlinear Control Systems Daizhan Cheng, Xiaoming Hu, Tielong Shen, 2010 Analysis and Design of Nonlinear Control Systems provides a comprehensive and up to date introduction to nonlinear control systems including system analysis and major control design techniques **Operator-Based Nonlinear Control Systems** Mingcong Deng, 2014-01-15 Enables readers to master and apply the operator theoretic approach Control of nonlinear systems is a multidisciplinary field involving electrical engineering computer science and control engineering Specifically this book addresses uncertain nonlinearity Beginning with how real plants are modeled as operator based plants the author develops a systematic methodology that enables readers to understand a quantitative stability result a critical factor in any nonlinear control system's stability and performance Operator Based Nonlinear Control Systems Design and Applications focuses on the operator theoretic approach offering detailed examples on how to apply it to network controlled systems In addition to current research results the author explores future research directions and applications of the operator theoretic approach The book begins with an introduction that defines nonlinear systems Next it covers Robust right coprime factorization for nonlinear plants with uncertainties Robust stability of operator based nonlinear control systems Tracking issues and fault detection issues in nonlinear control systems Operator based nonlinear control systems with smart actuators Nonlinear feedback control for large scale systems using a distributed control system device Throughout the book discussions of actual applications help readers understand how the operator theoretic approach works in practice Operator Based Nonlinear Control Systems is recommended for students and professionals in control theory engineering and applied mathematics Working with this expertly written and organized book they will learn how to obtain robust right coprime factorization for modeled plants Moreover they will discover state of the technology research results on robust stability conditions as well as the latest system output tracking and fault detection issues that are challenging today's researchers Nonlinear Control Systems Horacio Márquez, 2003-04-25 Provides complete coverage of both the Lyapunov and Input Output stability theories ina readable concise manner Supplies an introduction to the popular backstepping approach to nonlinear control design Gives a thorough discussion of the concept of input to state stability Includes a discussion of the fundamentals of feedback linearization and related results Details complete coverage of the fundamentals of dissipative system's theory and its application in the so called L2gain control prooblem for the first time in an introductory level textbook Contains a thorough discussion of nonlinear observers a very important problem not commonly encountered in textbooksat this level An Instructor s Manual presenting detailed solutions to all the problems in the book is available from the Wiley editorial department

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Nonlinear Control Systems Design 1995 A.J. Krener, D.Q.

Mayne, 2016-01-22 The series of IFAC Symposia on Nonlinear Control Systems provides the ideal forum for leading researchers and practitioners who work in the field to discuss and evaluate the latest research and developments This publication contains the papers presented at the 3rd IFAC Symposium in the series which was held in Tahoe City California USA

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An Introduction to Nonlinearity in Control Systems Derek P. Atherton, 2011

Analysis and Synthesis of Nonlinear Control Systems Miguel Bernal, Antonio Sala, Zsófia Lendek, Thierry Marie Guerra, 2022-02-05 This book presents a modern perspective on the modelling analysis and synthesis ideas behind convex optimisation based control of nonlinear systems it embeds them in models with convex structures Analysis and Synthesis of Nonlinear Control Systems begins with an introduction to the topic and a discussion of the problems to be solved It then explores modelling via convex structures including quasi linear parameter varying Takagi Sugeno models and linear fractional transformation structures The authors cover stability analysis addressing Lyapunov functions and the stability of polynomial models as well as the performance and robustness of the models With detailed examples simulations and programming code this book will be useful to instructors researchers and graduate students interested in nonlinear control systems *Nonlinear Control Systems 2004* Frank Allgower, Michael Zeitz, 2005-02-02

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