Avraham Feintuch

Robust Control Theory in Hilbert Space

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Robust Control Theory In Hilbert Space

Irena Lasiecka,Roberto Triggiani

Robust Control Theory In Hilbert Space:

Robust Control Theory in Hilbert Space Avraham Feintuch,1997-11-01   Algebras of Holomorphic Functions and Control Theory Amol Sasane,2013-04-10 Accessible undergraduate level text illustrates the role of algebras of holomorphic functions in the stabilization of a linear control system Concise self contained treatment avoids advanced mathematics 2009 edition   *Stabilization, Optimal and Robust Control* Aziz Belmiloudi,2008-08-17 Stabilization Optimal and Robust Control develops robust control of infinite dimensional dynamical systems derived from time dependent coupled PDEs associated with boundary value problems Rigorous analysis takes into account nonlinear system dynamics evolutionary and coupled PDE behaviour and the selection of function spaces in terms of solvability and model quality Mathematical foundations are provided so that the book remains accessible to the non control specialist Following chapters giving a general view of convex analysis and optimization and robust and optimal control problems arising in fluid mechanical biological and materials scientific systems are laid out in detail The combination of mathematical fundamentals with application of current interest will make this book of much interest to researchers and graduate students looking at complex problems in mathematics physics and biology as well as to control theorists   **Control Theory for Partial Differential Equations: Volume 1, Abstract Parabolic Systems** Irena Lasiecka,Roberto Triggiani,2000-02-13 Originally published in 2000 this is the first volume of a comprehensive two volume treatment of quadratic optimal control theory for partial differential equations over a finite or infinite time horizon and related differential integral and algebraic Riccati equations Both continuous theory and numerical approximation theory are included The authors use an abstract space operator theoretic approach which is based on semigroups methods and which is unifying across a few basic classes of evolution The various abstract frameworks are motivated by and ultimately directed to partial differential equations with boundary point control Volume 1 includes the abstract parabolic theory for the finite and infinite cases and corresponding PDE illustrations as well as various abstract hyperbolic settings in the finite case It presents numerous fascinating results These volumes will appeal to graduate students and researchers in pure and applied mathematics and theoretical engineering with an interest in optimal control problems   **CONTROL SYSTEMS, ROBOTICS AND AUTOMATION – Volume VIII** Heinz D. Unbehauen,2009-10-11 This Encyclopedia of Control Systems Robotics and Automation is a component of the global Encyclopedia of Life Support Systems EOLSS which is an integrated compendium of twenty one Encyclopedias This 22 volume set contains 240 chapters each of size 5000 30000 words with perspectives applications and extensive illustrations It is the only publication of its kind carrying state of the art knowledge in the fields of Control Systems Robotics and Automation and is aimed by virtue of the several applications at the following five major target audiences University and College Students Educators Professional Practitioners Research Personnel and Policy Analysts Managers and Decision Makers and NGOs   **Linear Operators and Linear Systems** Jonathan R. Partington,2004-03-15 Linear systems can be regarded as a causal shift invariant operator on a

Hilbert space of signals and by doing so this book presents an introduction to the common ground between operator theory and linear systems theory The book therefore includes material on pure mathematical topics such as Hardy spaces closed operators the gap metric semigroups shift invariant subspaces the commutant lifting theorem and almost periodic functions which would be entirely suitable for a course in functional analysis at the same time the book includes applications to partial differential equations to the stability and stabilization of linear systems to power signal spaces including some recent material not previously available in books and to delay systems treated from an input output point of view Suitable for students of analysis this book also acts as an introduction to a mathematical approach to systems and control for graduate students in departments of applied mathematics or engineering   **Well-Posed Linear Systems** Olof Staffans,2005-02-24 Many infinite dimensional linear systems can be modelled in a Hilbert space setting Others such as those dealing with heat transfer or population dynamics need to be set more generally in Banach spaces This is the first book dealing with well posed infinite dimensional linear systems with an input a state and an output in a Hilbert or Banach space setting It is also the first to describe the class of non well posed systems induced by system nodes The author shows how standard finite dimensional results from systems theory can be extended to these more general classes of systems and complements them with new results which have no finite dimensional counterpart Much of the material presented is original and many results have never appeared in book form before A comprehensive bibliography rounds off this work which will be indispensable to all working in systems theory operator theory delay equations and partial differential equations   Advanced methods for fault diagnosis and fault-tolerant control Steven X. Ding,2020-11-24 The major objective of this book is to introduce advanced design and online optimization methods for fault diagnosis and fault tolerant control from different aspects Under the aspect of system types fault diagnosis and fault tolerant issues are dealt with for linear time invariant and time varying systems as well as for nonlinear and distributed including networked systems From the methodological point of view both model based and data driven schemes are investigated To allow for a self contained study and enable an easy implementation in real applications the necessary knowledge as well as tools in mathematics and control theory are included in this book The main results with the fault diagnosis and fault tolerant schemes are presented in form of algorithms and demonstrated by means of benchmark case studies The intended audience of this book are process and control engineers engineering students and researchers with control engineering background   European Control Conference 1995 ,1995-09-05 Proceedings of the European Control Conference 1995 Rome Italy 5 8 September 1995   Control of Uncertain Systems: Modelling, Approximation, and Design Bruce A. Francis,2006-03-07 This Festschrift contains a collection of articles by friends co authors colleagues and former Ph D students of Keith Glover Professor of Engineering at the University of Cambridge on the occasion of his sixtieth birthday Professor Glover s scientific work spans a wide variety of topics the main themes being system identification model reduction and approximation robust controller synthesis and control of aircraft and engines The articles in this volume are a

tribute to Professor Glover s seminal work in these areas   Mathematical Control Theory Eduardo D. Sontag,2013-11-21 Mathematics is playing an ever more important role in the physical and biologi cal sciences provoking a blurring of boundaries between scientific disciplines and a resurgence of interest in the modern as well as the classical techniques of applied mathematics This renewal of interest both in research and teaching has led to the establishment of the series Texts in Applied Mathematics TAM The development of new courses is a natural consequence of a high level of excitement on the research frontier as newer techniques such as numerical and symbolic computer systems dynamical systems and chaos mix with and rein force the traditional methods of applied mathematics Thus the purpose of this textbook series is to meet the current and future needs of these advances and to encourage the teaching of new courses TAM will publish textbooks suitable for use in advanced undergraduate and beginning graduate courses and will complement the Applied Mathematics Sci ences AMS series which will focus on advanced textbooks and research level monographs v Preface to the Second Edition The most significant differences between this edition and the first are as follows Additional chapters and sections have been written dealing with nonlinear controllability via Lie algebraic methods variational and numerical approaches to nonlinear control including a brief introduction to the Calculus of Variations and the Minimum Principle time optimal control of linear systems feedback linearization single input case nonlinear optimal feedback controllability of recurrent nets and controllability of linear systems with bounded controls   **Structural Methods in the Study of Complex Systems** Elena Zattoni,Anna Maria Perdon,Giuseppe Conte,2019-06-27 Structural Methods in the Study of Complex Systems helps the reader respond to the challenge of mastering complexity in systems and control The book details the fundamental control problems arising from complex dynamical systems and shows how they can be tackled effectively by means of methods developed from graph theory differential algebra and geometric approaches These structural methods produce abstractions that fit a wide variety of applications by taking advantage of their intrinsic focus on the essential characteristics of dynamical systems their geometric perspective and visual representation and their algebraic formalization and ability to generate algorithmic frameworks to complement the theoretical treatment The original work and latest achievements of the contributors expanding on material presented at a workshop organized to coincide with the 2018 European Control Conference will assist systems and control scientists interested in developing theoretical and computational tools to solve analysis and synthesis problems involving complex dynamical systems The contributions provide a comprehensive picture of available results along with a stimulating view of possible directions for future investigations in the field Emphasis is placed on methods with solid computational background and on specific engineering applications so that readers from both theoretical and practical backgrounds will find this collection of use   *Unsolved Problems in Mathematical Systems and Control Theory* Vincent D. Blondel,Alexandre Megretski,2009-04-11 This book provides clear presentations of more than sixty important unsolved problems in mathematical systems and control theory Each of the problems included here is proposed by

a leading expert and set forth in an accessible manner Covering a wide range of areas the book will be an ideal reference for anyone interested in the latest developments in the field including specialists in applied mathematics engineering and computer science The book consists of ten parts representing various problem areas and each chapter sets forth a different problem presented by a researcher in the particular area and in the same way description of the problem motivation and history available results and bibliography It aims not only to encourage work on the included problems but also to suggest new ones and generate fresh research The reader will be able to submit solutions for possible inclusion on an online version of the book to be updated quarterly on the Princeton University Press website and thus also be able to access solutions updated information and partial solutions as they are developed Interpolation and Realization Theory with Applications to Control Theory Vladimir Bolotnikov,Sanne ter Horst,André C.M. Ran,Victor Vinnikov,2019-04-08 This volume is devoted to Joseph A Joe Ball s contributions to operator theory and its applications and in celebration of his seventieth birthday Joe Ball s career spans over four and a half decades starting with his work on model theory and related topics for non contractions and operators on multiply connected domains Later on more applied operator theory themes appeared in his work involving factorization and interpolation for operator valued functions with extensive applications in system and control theory He has worked on nonlinear control time varying systems and more recently on multidimensional systems and noncommutative H theory on the unit ball and polydisk and more general domains and these are only the main themes in his vast oeuvre Fourteen research papers constitute the core of this volume written by mathematicians who have collaborated with Joe or have been influenced by his vast mathematical work A curriculum vitae a publicationslist and a list of Joe Ball s PhD students are included in this volume as well as personal reminiscences by colleagues and friends Contributions by Yu M Arlinskii S Hassi M Augat J W Helton I Klep S McCullough S Balasubramanian U Wijesooriya N Cohen Q Fang S Gorai J Sarkar G J Groenewald S ter Horst J Jaftha A C M Ran M A Kaashoek F van Schagen A Kheifets Z A Lykova N J Young A E Ajibo R T W Martin A Ramanantoanina M J Y Ou H J Woerdeman A van der Schaft A Tannenbaum T T Georgiou J O Deasy and L Norton

 Representation and Control of Infinite Dimensional Systems Alain Bensoussan,Giuseppe Da Prato,Michel C. Delfour,Sanjoy K. Mitter,2007-04-05 This unified revised second edition of a two volume set is a self contained account of quadratic cost optimal control for a large class of infinite dimensional systems The original editions received outstanding reviews yet this new edition is more concise and self contained New material has been added to reflect the growth in the field over the past decade There is a unique chapter on semigroup theory of linear operators that brings together advanced concepts and techniques which are usually treated independently The material on delay systems and structural operators has not yet appeared anywhere in book form **Systems, Approximation, Singular Integral Operators, and Related Topics** Alexander A. Borichev,Nikolai K. Nikolski,2012-12-06 This book is devoted to some topical problems and applications of operator theory and its interplay with modern complex analysis It consists of 20 selected survey papers that represent

updated mainly plenary addresses to the IWOTA 2000 conference held at Bordeaux from June 13 to 16 2000 The main subjects of the volume include spectral analysis of periodic differential operators and delay equations stabilizing controllers Fourier multipliers multivariable operator theory model theory commutant lifting theorems coisometric realizations Hankel operators and forms operator algebras the Bellman function approach in singular integrals and harmonic analysis singular integral operators and integral representations approximation in holomorphic spaces These subjects are unified by the common operator theoretic approach and the systematic use of modern function theory techniques *Advances in Computer, Communication, Control and Automation* Yanwen Wu,2011-11-20 The volume includes a set of selected papers extended and revised from the 2011 International Conference on Computer Communication Control and Automation 3CA 2011 2011 International Conference on Computer Communication Control and Automation 3CA 2011 has been held in Zhuhai China November 19 20 2011 This volume topics covered include signal and Image processing speech and audio Processing video processing and analysis artificial intelligence computing and intelligent systems machine learning sensor and neural networks knowledge discovery and data mining fuzzy mathematics and Applications knowledge based systems hybrid systems modeling and design risk analysis and management system modeling and simulation We hope that researchers graduate students and other interested readers benefit scientifically from the proceedings and also find it stimulating in the process **Indefinite-Quadratic Estimation and Control** Babak Hassibi,Ali H. Sayed,Thomas Kailath,1999-01-01 This monograph presents a unified mathematical framework for a wide range of problems in estimation and control The authors discuss the two most commonly used methodologies the stochastic H approach and the deterministic worst case H infinity approach Despite the fundamental differences in the philosophies of these two approaches the authors have discovered that if indefinite metric spaces are considered they can be treated in the same way and are essentially the same The benefits and consequences of this unification are pursued in detail with discussions of how to generalize well known results from H theory to H infinity setting as well as new results and insight the development of new algorithms and applications to adaptive signal processing The authors deliberately have placed primary emphasis on estimation problems which enable one to solve all the relevant control problems in detail They also deal mostly with discrete time systems since these are the ones most important in current applications *Recent Advances in Intelligent Engineering* Levente Kovács,Tamás Haidegger,Anikó Szakál,2019-03-15 This book gathers contributions on fuzzy neural control intelligent and non linear control dynamic systems and cyber physical systems It presents the latest theoretical and practical results including numerous applications of computational intelligence in various disciplines such as engineering medicine technology and the environment The book is dedicated to Imre J Rudas on his seventieth birthday *Elements of Applied Bifurcation Theory* Yuri Kuznetsov,1998-09-18 Providing readers with a solid basis in dynamical systems theory as well as explicit procedures for application of general mathematical results to particular problems the focus here is on efficient numerical implementations of the developed

techniques The book is designed for advanced undergraduates or graduates in applied mathematics as well as for Ph D students and researchers in physics biology engineering and economics who use dynamical systems as model tools in their studies A moderate mathematical background is assumed and whenever possible only elementary mathematical tools are used This new edition preserves the structure of the first while updating the context to incorporate recent theoretical developments in particular new and improved numerical methods for bifurcation analysis

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