

# Lecture Notes in Control and Information Sciences

Edited by M. Thoma and A. Wyner

150

L.C.G.J.M. Habets

**Robust Stabilization  
in the Gap-topology**



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# Robust Stabilization In The Gap Topology Lecture Notes In Control And Information Sciences Vol 15

**Volker Ludwig Mehrmann**



## **Robust Stabilization In The Gap Topology Lecture Notes In Control And Information Sciences Vol 15:**

**Variable Structure and Lyapunov Control** Alan S. I. Zinober, 1994      **Differential and Algebraic Riccati**

**Equations with Application to Boundary/point Control Problems** Irena Lasiecka, Roberto Triggiani, 1991 This book provides in a unified framework an updated and rather comprehensive treatment centered on the theory of optimal control with quadratic cost functional for abstract linear systems with application to boundary point control problems for partial differential equations distributed parameter systems The book culminates with the analysis of differential and algebraic Riccati equations which arise in the pointwise feedback synthesis of the optimal pair It incorporates the critical topics of optimal irregularity of solutions to mixed problems for partial differential equations exact controllability and uniform feedback stabilization It covers the main results of the theory which has reached a considerable degree of maturity over the last few years as well as the authors' basic philosophy behind it Moreover it provides numerous illustrative examples of boundary point control problems for partial differential equations where the abstract theory applies However in line with the purpose of the manuscript many technical proofs are referred to in the literature Thus the manuscript should prove useful not only to mathematicians and theoretical scientists with expertise in partial differential equations operator theory numerical analysis control theory etc but also to those who simply wish to orient themselves with the scope and status of the theory presently available Both continuous theory and numerical approximation theory thereof are included      [92-4550 to 92-4631](#) , 1992      *The Modeling of Uncertainty in Control Systems* Roy S. Smith, 1994 This book is a collection of work arising from a NSF AFOSR sponsored workshop held at the University of California Santa Barbara 18-20th June 1992 Sixty-nine researchers from nine countries participated Twelve keynote essays give an overview of the field and speculate on future directions and nineteen technical papers delineate the state of the art in the field This book serves both as an introduction to the topic and as a reference on the current technical problems and approaches      **Simultaneous**

**Stabilization of Linear Systems** Vincent Blondel, 1994 Simultaneous Stabilization of Linear Systems is devoted to a single question from Linear Systems Theory When is it possible to find a controller that stabilizes a finite family of systems known as the Simultaneous Stabilization Question This question is satisfactorily solved when the number of systems is limited to two but is open for three or more systems This constitutes one of the important longstanding open problems in Linear Systems Theory Dr Blondel reviews partial answers and discusses partial answers with equivalent formulations of the problem Particular emphasis is placed on interlacement conditions The parity and the interlacing conditions are presented in a clear and unified framework The final chapter proves the latest research progress and shows that contrary to most of the questions in Linear Systems Theory there exists no necessary and sufficient conditions for simultaneous stabilization of three or more systems that involve only the coefficients of the systems and a combination of rational operations      *Analysis and Optimization of Systems* Ruth F. Curtain, 1993      **Advanced Methods in Adaptive Control for Industrial Applications**

Kevin Warwick, 1991      **The Autonomous Linear Quadratic Control Problem** Volker Ludwig Mehrmann, 1991 A survey is given on the state of the art in theory and numerical solution of general autonomous linear quadratic optimal control problems continuous and discrete with differential algebraic equation constraints It incorporates the newest developments on differential algebraic equations Riccati equations and invariant subspace problems In particular it gives a decision chart of numerical methods that can be used to determine the right numerical method according to special properties of the problem The book closes a gap between mathematical theory numerical solution and engineering application The mathematical tools are kept as basic as possible in order to address the different groups of readers mathematicians and engineers      **Numerical Operations with Polynomial Matrices** Peter Stefanidis, Andrzej Piotr Papliński, Michael John Gibbard, 1992      Optimization-Based Computer-Aided Modelling and Design IFIP TC 7.6 Working Group. Working Conference, 1992 The working conference dealt with recent developments in the field of modelling and optimization and with knowledge based decision support systems This contributed to the realization of the aims of the working group 7.6 which are to promote theoretical research in the field of optimization including mathematical programming and optimal control to encourage the development of sophisticated knowledge based systems in which refined optimization models and algorithms are used to contribute to the exchange and dissemination of information and collective experience among the interested groups and individuals to support the practical application of such systems in control engineering industry economy etc A selection of papers is included into this proceedings volume since they reflect the current state of research in areas of interest to the field of KB DDS and or they are the value for the dissemination and exchange of information related to research topics of interest and or they describe relevant practical experience related to designing building implementing and using KB DSS      **Positioning Systems** Christopher R. Drane, 1992 Positioning systems measure the location of one or more objects As well most imaging systems inherently perform a positioning function Positioning systems can be applied in various forms of transport such as general and space aviation or automobiles but also in geodetic surveying The aim of this monograph is to establish a general method for the mathematical analysis of positioning systems and to demonstrate the utility of this characterization The basic approach uses information theory differential geometry rate distortion theory and chaos as well as integrating the more conventional methods of analysis based on estimation and detection theory This approach allows the derivation of performance limits estimates of optimal configuration reasoning about classes of systems direct comparison between positioning and communication systems and estimates of the source information rate of moving objects The book should be of interest to any researcher seeking to gain a better understanding of a positioning or imaging system      *Foundations of Adaptive Control* P. V. Kokotovic, 1991-06-24 The 1990 Grainger Lectures delivered at the University of Illinois Urbana Champaign September 28 October 1 1990 were devoted to a critical reexamination of the foundations of adaptive control In this volume the lectures are expanded by most recent developments and solutions for some

long standing open problems Concepts and approaches presented are both novel and of fundamental importance for adaptive control research in the 1990s The papers in Part I present unifications reappraisals and new results on tunability convergence and robustness of adaptive linear control whereas the papers in Part II formulate new problems in adaptive control of nonlinear systems and solve them without any linear constraints imposed on the nonlinearities Dynamic Games in Economic Analysis Raimo P. Härmäläinen, Harri Kalevi Ehtamo, 1991 **Robust Stabilization in the Gap-topology** Luc C.G.J.M. Habets, 1991-02-08 The author presents a topological approach to the problem of robustness of dynamic feedback control First the gap topology is introduced as a distance measure between systems In this topology stability of the closed loop system is a robust property Furthermore it is possible to solve the problem of optimally robust control in this setting The book can be divided into two parts The first chapters form an introduction to the topological approach towards robust stabilization Although of theoretical nature only general mathematical knowledge is required from the reader The second part is devoted to compensator design Several algorithms for computing an optimally robust controller in the gap topology are presented and worked out Therefore we hope that the book will not only be of interest to theoreticians but that also practitioners will benefit from it Experimental Robotics, 1993 *Implicit Linear Systems* J.Dwight Aplevich, 1991-03-20 These notes are an introduction to implicit models of linear dynamical systems with applications to modelling control system design and identification intended for control system engineers at the beginning graduate level Because they are non oriented the models are particularly useful where causality is unknown or may change They are implicit in all variables and closed under the algebraic operations and hence are useful for computer aided analysis and design They possess the vector matrix conceptual simplicity and computational feasibility of state space equations together with the generality of matrix fraction descriptions and admit of canonical forms for which the joint identification of system parameters and dynamic variables is linear The notes simplify generalize and complement much recent work on singular or descriptor models but do not duplicate it Sections are included on realizations canonical forms minimal representations algebraic design applications quadratic optimization identification large scale systems and extensions to multi dimensional and time varying systems

*11th International Conference on Analysis and Optimization of Systems* Guy Cohen, Jean-Pierre Quadrat, 1994 The conference coorganized by INRIA and Ecole des Mines de Paris focuses on Discrete Event Systems DES and is aimed at engineers scientists and mathematicians working in the fields of Automatic Control Operations Research and Statistics who are interested in the modelling analysis and optimization of DES Various methods such as Automata theory Petri nets etc are proposed to describe and analyze such systems Comparison of these different mathematical approaches and the global confrontation of theoretical approaches with applications in manufacturing telecommunications parallel computing transportation etc are the goals of the conference *Subject Guide to Books in Print*, 1993 **Differential Games** Raimo P. Härmäläinen, 1991 **Forthcoming Books** Rose Arny, 1991

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