

**ONTOLOGICALLY
CONTROLLED
AUTONOMOUS
SYSTEMS:
PRINCIPLES,
OPERATIONS AND
ARCHITECTURE**

GEORGE A. FODOR

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Ontologically Controlled Autonomous Systems Principles Operations And Architecture

Theng, Yin-Leng, Duh, Henry B. L.



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Ontologically Controlled Autonomous Systems: Principles, Operations, and Architecture George A. Fodor, 1998

Ontologically Controlled Autonomous Systems Principles Operations and Architecture presents the main principles operations and architecture involved in the design of a novel type of supervisory controller called an ontological controller An ontological controller can be used to supervise any type of controller however its intended applications are industrial strength complex autonomous control systems using advanced programmable controllers Ontologically Controlled Autonomous Systems Principles Operations and Architecture presents for the first time a complete formal framework and results for ontological control All results presented in the book originate from the practical industrial experience of the author The intended readers for Ontologically Controlled Autonomous Systems Principles Operations and Architecture are professional and students working in industrial control discrete control discrete event systems artificial intelligence autonomous systems programmable logic control design robotics real time planning safety critical systems Petri nets and PLC standards such as IEC1131

Ontologically Controlled Autonomous Systems: Principles, Operations, and Architecture George A. Fodor, 2013-11-27 Kevin M Passino When confronted with a control problem for complicated physical process a control engineer usually follows a predetermined design procedure This procedure often begins with the engineer seeking to understand the process and the primary control objectives A simple example of a control problem is an automobile cruise control that provides the automobile with the capability of regulating its own speed at a driver specified set point e g 55 mph One solution to the automotive cruise control problem involves adding an electronic controller that can sense the speed of the vehicle via the speedometer and actuate the throttle position so as to regulate the vehicle speed at the driver specified value Such speed regulation must be accurate even if there are road grade changes head winds or variations in the number of passengers in the automobile After gaining an intuitive understanding of the plant s dynamics and establishing the design objectives the control engineer typically solves the cruise control problem by using an established design procedure In particular this control engineering design methodology involves 1 Modeling understanding the plant 2 Construction of a controller to meet specifications such as stability rise time overshoot and steady state error 3 Analysis to make sure that the system will meet the performance objectives e g we might use mathematical simulation based or experimental analysis and 4 Iterating on the design until it is possible to commission the control system

Aspects of Soft Computing, Intelligent Robotics and Control János Fodor, 2009-10-13 Soft computing as a collection of techniques exploiting approximation and tolerance for imprecision and uncertainty in traditionally intractable problems has become very effective and popular especially because of the synergy derived from its components The integration of constituent technologies provides complementary methods that allow developing flexible computing tools and solving complex problems A wide area of natural applications of soft computing techniques consists of the control of dynamic systems including robots Loosely speaking

control can be understood as driving a process to attain a desired goal Intelligent control can be seen as an extension of this concept to include autonomous human like interactions of a machine with the environment Intelligent robots can be characterized by the ability to operate in an uncertain changing environment with the help of appropriate sensing They have the power to autonomously plan and execute motion sequences to achieve a goal specified by a human user without detailed instructions In this volume leading specialists address various theoretical and practical aspects in soft computing intelligent robotics and control The problems discussed are taken from fuzzy systems neural networks interactive evolutionary computation intelligent mobile robotics and intelligent control of linear and nonlinear dynamic systems *Ontologically*

Controlled Autonomous Systems George A. Fodor,1998

Ubiquitous Computing: Design, Implementation and

Usability Theng, Yin-Leng,Duh, Henry B. L.,2008-05-31 Interactive systems in the mobile ubiquitous and virtual environments are at a stage of development where designers and developers are keen to find out more about design use and usability of these systems Ubiquitous Computing Design Implementation and Usability highlights the emergent usability theories techniques tools and best practices in these environments This book shows that usable and useful systems are able to be achieved in ways that will improve usability to enhance user experiences Research on the usability issues for young children teenagers adults and the elderly is presented with different techniques for the mobile ubiquitous and virtual environments **Intelligent Information Technologies: Concepts, Methodologies, Tools, and Applications**

Sugumaran, Vijayan,2007-11-30 This set compiles more than 240 chapters from the world s leading experts to provide a foundational body of research to drive further evolution and innovation of these next generation technologies and their applications of which scientific technological and commercial communities have only begun to scratch the surface

Artificial Intelligence and Integrated Intelligent Information Systems Xuan F. Zha,2007-01-01 Researchers in the evolving fields of artificial intelligence and information systems are constantly presented with new challenges Artificial Intelligence and Integrated Intelligent Information Systems Emerging Technologies and Applications provides both researchers and professionals with the latest knowledge applied to customized logic systems agent based approaches to modeling and human based models Artificial Intelligence and Integrated Intelligent Information Systems Emerging Technologies and Applications presents the recent advances in multi mobile agent systems the product development process fuzzy logic systems neural networks and ambient intelligent environments among many other innovations in this exciting field *Proceedings, IEEE Control Systems Society ... Symposium on Computer-Aided Control System Design (CACSD).*

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