

Robust Nonlinear Control Design

State-Space and
Lyapunov Techniques

Randy A. Freeman
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Robust Nonlinear Control Design State Space And Lyapunov Techniques Systems And Control Foundations And Applications

Jean-Michel Coron



Robust Nonlinear Control Design State Space And Lyapunov Techniques Systems And Control Foundations And Applications:

Robust Nonlinear Control Design Randy A. Freeman, Petar V. Kokotovic, 1996 *Robust Nonlinear Control Design* Randy A. Freeman, Petar V. Kokotovic, 2009-05-21 The purpose of the book is to summarize Lyapunov design techniques for nonlinear systems and to raise important issues concerning large signal robustness and performance The authors have been the first to address some of these issues and they report their findings in this text For example they identify two potential sources of excessive control effort in Lyapunov design techniques and show how such effort can be greatly reduced The researcher who wishes to enter the field of robust nonlinear control could use this book as a source of new research topics For those already active in the field the book may serve as a reference to a recent body of significant work Finally the design engineer faced with a nonlinear control problem will benefit from the techniques presented here *Robust Nonlinear Control Design* Randy A. Freeman, Petar V. Kokotović, 1996-01-01 ***Robust Nonlinear Control Design*** Randy A. Freeman, Petar Kokotovic, 1966 *Set-Theoretic Methods in Control* Franco Blanchini, Stefano Miani, 2015-07-02 The second edition of this monograph describes the set theoretic approach for the control and analysis of dynamic systems both from a theoretical and practical standpoint This approach is linked to fundamental control problems such as Lyapunov stability analysis and stabilization optimal control control under constraints persistent disturbance rejection and uncertain systems analysis and synthesis Completely self contained this book provides a solid foundation of mathematical techniques and applications extensive references to the relevant literature and numerous avenues for further theoretical study All the material from the first edition has been updated to reflect the most recent developments in the field and a new chapter on switching systems has been added Each chapter contains examples case studies and exercises to allow for a better understanding of theoretical concepts by practical application The mathematical language is kept to the minimum level necessary for the adequate formulation and statement of the main concepts yet allowing for a detailed exposition of the numerical algorithms for the solution of the proposed problems Set Theoretic Methods in Control will appeal to both researchers and practitioners in control engineering and applied mathematics It is also well suited as a textbook for graduate students in these areas Praise for the First Edition This is an excellent book full of new ideas and collecting a lot of diverse material related to set theoretic methods It can be recommended to a wide control community audience B T Polyak Mathematical Reviews This book is an outstanding monograph of a recent research trend in control It reflects the vast experience of the authors as well as their noticeable contributions to the development of this field It is highly recommended to PhD students and researchers working in control engineering or applied mathematics The material can also be used for graduate courses in these areas Octavian Pastravanu Zentralblatt MATH *Introduction to Nonlinear Control* Christopher M. Kellett, Philipp Braun, 2023-06-27 An introductory text on the analysis control and estimation of nonlinear systems

appropriate for advanced undergraduate and graduate students This self contained and accessible introduction to the concepts and techniques used for nonlinear feedback systems offers a holistic treatment suitable for use in both advanced undergraduate and graduate courses students need only some familiarity with differential equations and linear algebra to understand the material presented The text begins with an overview of stability and Lyapunov methods for nonlinear systems with Lyapunov's second method revisited throughout the book as a connective thread Other introductory chapters cover linear systems frequency domain methods and discrete time systems Building on this background material the book provides a broad introduction to the basic ideas underpinning major themes of research in nonlinear control including input to state stability sliding mode control adaptive control feedback linearization and robust output regulation Chapters also cover observer design and estimation for nonlinear systems The text is notable for its coverage of nonlinear model predictive control and its introduction to the use of linear matrix inequalities and semidefinite programming coupled with their use in modern antiwindup designs First text on nonlinear control appropriate for undergraduates Suitable both for students preparing for rigorous graduate study and for those entering technical fields outside of academia Unique in its coverage of recent research topics Pedagogical features including extensive chapter summaries examples and appendixes with definitions results and MATLAB applications

Control and Nonlinearity Jean-Michel Coron, 2007 This book presents methods to study the controllability and the stabilization of nonlinear control systems in finite and infinite dimensions The emphasis is put on specific phenomena due to nonlinearities In particular many examples are given where nonlinearities turn out to be essential to get controllability or stabilization Various methods are presented to study the controllability or to construct stabilizing feedback laws The power of these methods is illustrated by numerous examples coming from such areas as celestial mechanics fluid mechanics and quantum mechanics The book is addressed to graduate students in mathematics or control theory and to mathematicians or engineers with an interest in nonlinear control systems governed by ordinary or partial differential equations

Non-linear Control for Underactuated Mechanical Systems Isabelle Fantoni, Rogelio Lozano, 2012-12-06 This book deals with the application of modern control theory to some important underactuated mechanical systems from the inverted pendulum to the helicopter model It will help readers gain experience in the modelling of mechanical systems and familiarize with new control methods for non linear systems

Uncertainty in Complex Networked Systems Tamer Başar, 2018-12-14 The chapters in this volume and the volume itself celebrate the life and research of Roberto Tempo a leader in the study of complex networked systems their analysis and control under uncertainty and robust designs Contributors include authorities on uncertainty in systems robustness networked and network systems social networks distributed and randomized algorithms and multi agent systems all fields that Roberto Tempo made vital contributions to Additionally at least one author of each chapter was a research collaborator of Roberto Tempo's This volume is structured in three parts The first covers robustness and includes topics like time invariant uncertainties robust static

output feedback design and the uncertainty quartet The second part is focused on randomization and probabilistic methods which covers topics such as compressive sensing and stochastic optimization Finally the third part deals with distributed systems and algorithms and explores matters involving mathematical sociology fault diagnoses and PageRank computation Each chapter presents exposition provides new results and identifies fruitful future directions in research This book will serve as a valuable reference volume to researchers interested in uncertainty complexity robustness optimization algorithms and networked systems

Theory And Algorithms For Cooperative Systems Panos M Pardalos, Robert Murphey, Don Grundel, 2004-08-23 Over the past several years cooperative control and optimization have increasingly played a larger and more important role in many aspects of military sciences biology communications robotics and decision making At the same time cooperative systems are notoriously difficult to model analyze and solve while intuitively understood they are not axiomatically defined in any commonly accepted manner The works in this volume provide outstanding insights into this very complex area of research They are the result of invited papers and selected presentations at the Fourth Annual Conference on Cooperative Control and Optimization held in Destin Florida November 2003 This book has been selected for coverage in Index to Scientific Technical Proceedings ISTP ISI Proceedings Index to Scientific Technical Proceedings ISTP CDROM version ISI Proceedings CC Proceedings Engineering Physical Sciences

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