



Robot Programming

Cameron Hughes, Tracey Hughes



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Industrial Robots Programming J. Norberto Pires, 2007-04-03 Industrial Robots Programming focuses on designing and building robotic manufacturing cells and explores the capabilities of today's industrial equipment as well as the latest computer and software technologies. Special attention is given to the input devices and systems that create efficient human-machine interfaces and how they help non-technical personnel perform necessary programming control and supervision tasks. Drawing upon years of practical experience and using numerous examples and illustrative applications J. Norberto Pires covers robotics programming as it applies to the current industrial robotic equipment including manipulators control systems and programming environments. Software interfaces that can be used to develop distributed industrial manufacturing cells and techniques which can be used to build interfaces between robots and computers. Real world applications with examples designed and implemented recently in the lab. Industrial Robots Programming has been selected for indexing by Scopus. For more information about Industrial Robotics please find the author's Industrial Robotics collection at the iTunesU University of Coimbra channel. Robot Programming Joe Jones, Daniel Roth, 2004-01-02 Teaches the concepts of behavior based programming through text programming examples and a unique online simulator robot. Explains how to design new behaviors by manipulating old ones and adjusting programming. Does not assume reader familiarity with robotics or programming languages. Includes a section on designing your own behavior based system from scratch. *Robot Programming* Cameron Hughes, Tracey Hughes, 2016-05-02 Start programming robots NOW. Learn hands on through easy examples, visuals and code. This is a unique introduction to programming robots to execute tasks autonomously. Drawing on years of experience in artificial intelligence and robot programming, Cameron and Tracey Hughes introduce the reader to basic concepts of programming robots to execute tasks without the use of remote controls. *Robot Programming: A Guide to Controlling Autonomous Robots* takes the reader on an adventure through the eyes of Midamba, a lad who has been stranded on a desert island and must find a way to program robots to help him escape. In this guide you are presented with practical approaches and techniques to program robot sensors, motors, and translate your ideas into tasks a robot can execute autonomously. These techniques can be used on today's leading robot microcontrollers ARM9 and ARM7 and robot platforms including the wildly popular low cost Arduino platforms LEGO Mindstorms EV3, NXT and Wowee RS Media Robot for your hardware Maker/DIY projects. Along the way the reader will learn how to program robot sensors and motors, program a robot arm to perform a task, describe the robot's tasks and environments in a way that a robot can process using robot STRIPS, develop a RSV P Robot Scenario, Visual Planning used for designing the robot's tasks in an environment, program a robot to deal with the unexpected using robot SPACES, program robots safely using SARA, a Safe Autonomous Robot Application Architecture Approach, program robots using Arduino C/C++ and Java languages, use robot programming techniques with LEGO Mindstorms EV3, Arduino and other ARM7 and ARM9 based robots. *Programming Robots with ROS*

Morgan Quigley, Brian Gerkey, William D. Smart, 2015-11-16 Want to develop novel robot applications but don't know how to write a mapping or object recognition system You're not alone but you're certainly not without help By combining real world examples with valuable knowledge from the Robot Operating System ROS community this practical book provides a set of motivating recipes for solving specific robotics use cases Ideal for enthusiasts from students in robotics clubs to professional robotics scientists and engineers each recipe describes a complete solution using ROS open source libraries and tools You'll learn how to complete tasks described in the recipes as well as how to configure and recombine components for other tasks If you're familiar with Python you're ready to go Learn fundamentals including key ROS concepts tools and patterns Program robots that perform an increasingly complex set of behaviors using the powerful packages in ROS See how to easily add perception and navigation abilities to your robots Integrate your own sensors actuators software libraries and even a whole robot into the ROS ecosystem Learn tips and tricks for using ROS tools and community resources debugging robot behavior and using C in ROS

Learn Robotics Programming Danny Staple, 2021-02-12 Design build and program AI driven robots from scratch using Python and Raspberry Pi while mastering real world robotics concepts sensor integration and camera based vision systems Key Features Learn hands on robotics by wiring coding and troubleshooting real hardware Integrate sensors cameras and voice agents to make your robot intelligent Follow a structured path from Python basics to browser based robot control Book Description We live in an age where the most complex or repetitive tasks are automated Smart robots have the potential to revolutionize how we perform all kinds of tasks with high accuracy and efficiency With this second edition of Learn Robotics Programming you'll see how a combination of the Raspberry Pi and Python can be a great starting point for robot programming The book starts by introducing you to the basic structure of a robot and shows you how to design build and program it As you make your way through the book you'll add different outputs and sensors learn robot building skills and write code to add autonomous behavior using sensors and a camera You'll also be able to upgrade your robot with Wi-Fi connectivity to control it using a smartphone Finally you'll understand how you can apply the skills that you've learned to visualize lay out build and code your future robot building projects By the end of this book you'll have built an interesting robot that can perform basic artificial intelligence operations and be well versed in programming robots and creating complex robotics projects using what you've learned What you will learn Leverage the features of the Raspberry Pi OS Discover how to configure a Raspberry Pi to build an AI enabled robot Interface motors and sensors with a Raspberry Pi Code your robot to develop engaging and intelligent robot behavior Explore AI behavior such as speech recognition and visual processing Find out how you can control AI robots with a mobile phone over Wi-Fi Understand how to choose the right parts and assemble your robot Who this book is for This book is intended for robotics enthusiasts hobbyists and aspiring programmers with a basic understanding of Python who are interested in building intelligent AI enabled robots using Raspberry Pi It is ideal for learners who prefer a practical hands on approach

Robot Programming by Demonstration

Sylvain Calinon,2009-08-24 Recent advances in RbD have identified a number of key issues for ensuring a generic approach to the transfer of skills across various agents and contexts This book focuses on the two generic questions of what to imitate and how to imitate and proposes active teaching methods *Logic/Object-Oriented Concurrent Robot Programming and Performance Aspects* Alfried Pollmann,2020-10-12 No detailed description available for Logic Object Oriented Concurrent Robot Programming and Performance Aspects *A Concise Introduction to Robot Programming with ROS 2* Francisco Martín Rico,2025-07-04 A Concise Introduction to Robot Programming with ROS2 provides the reader with the concepts and tools necessary to bring a robot to life through programming It will equip the reader with the skills necessary to undertake projects with ROS2 the new version of ROS It is not necessary to have previous experience with ROS2 as it will describe its concepts tools and methodologies from the beginning Uses the two programming languages officially supported in ROS 2 C++ mainly and Python Approaches ROS 2 from three different but complementary dimensions the Community Computation Graph and the Workspace Includes a complete simulated robot development and testing strategies Behavior Trees and Nav2 description setup and use A GitHub repository with code to assist readers It will appeal to motivated engineering students engineers and professionals working with robot programming *Theory of Automatic Robot Assembly and Programming* Bartholomew O. Nnaji,1993 Machines will gradually become programmed using computers which have the knowledge of how the objects in the world relate to one another This book capitalizes on the fact that products which are manufactured can be designed on the computer and that information about the product such as its physical shape provide powerful information to reason about how to develop the process plan for their manufacture This book explores the whole aspect of using the principles of how parts behave naturally to automatically generate programs that govern how to produce them The last decade saw tremendous work on how machines can be programmed to perform a variety of tasks automatically Robotics has witnessed the most work on programming techniques But it was not until the emergence of the advanced CAD system as a proper source of information representation about objects which are to be manipulated by the robot that it became viable for automated processors to generate robot programs without human interface It became possible for objects to be described and for principles about how they interact in the world to be developed The functions which the features designed into the objects serve for the objects can be adequately represented and used in reasoning about the manufacturing of the parts using the robot This book describes the necessary principles which must be developed for a robot to generate its own programs with the knowledge of the world in the CAD system *A New Programming Approach for Robot-based Flexible Inspection systems* William Brice Tekouo Moutchiho,2019-03-27

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