



Roboti Industriali

Ion Visa



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Camshaft Precision Florian Ion Petrescu, Rely Victoria Petrescu, 2012 In the first chapter the authors present an original method to calculate the efficiency of the cams mechanisms The second chapter presents an original method in determining a general dynamic and differential equation for the motion of machines and mechanisms particularized for the mechanisms with rotation cams and followers The third chapter presents an original method to determine the general dynamics of mechanisms with rotation cams and followers particularized to the plate translated follower First it presents the dynamics kinematics Then it solves the Lagrange equation and using an original dynamic model with one degree of freedom with variable internal amortization it makes the dynamic analysis The fourth chapter briefly presents an original method for determining the dynamics of mechanisms with rotation cam and translated follower with roll First one presents the dynamics kinematics Then one performs the dynamic analysis of a few models for some movement laws imposed on the follower by the designed cam profile The fifth chapter presents an original methods to determine the dynamic parameters at the classic distribution and a new method is presented in the sixth chapter The seventh chapter presents an original methods to determine the dynamic parameters at the camshaft with rotary cam and translated follower with roll **Distinguished**

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problem Based on the authors many years of research and on their extensive knowledge concerning the theory of mechanisms and bridging between geometry and mechanics this book offers a unique guide to mechanical engineers and engineering designers mathematicians as well as industrial and graphic designers and students in the above mentioned fields alike The Industrial Robot ,1981 Smart Cities, Green Technologies, and Intelligent Transport Systems Markus Helfert,Cornel Klein,Brian Donnellan,Oleg Gusikhin,2017-08-07 This book constitutes the thoroughly refereed post conference proceedings of the 5th International Conference on Smart Cities and Green ICT Systems SMARTGREENS 2016 and the Second International Conference on Vehicle Technology and Intelligent Transport Systems VEHITS 2016 held in Rome Italy in April 2016 The 11 full papers of SMARTGREENS 2016 presented were carefully reviewed and selected from 72 submissions VEHITS 2016 received 49 paper submissions from which 5 papers were selected and published in this book The papers reflect topics such as smart cities energy aware systems and technologies sustainable computing and communications sustainable transportation and smart mobility *Roboti industriali* Corneliu RADULESCU,1992

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