

Nonsmooth Analysis and Control Theory

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Nonsmooth Analysis And Control Theory

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Nonsmooth Analysis and Control Theory Francis H. Clarke, Yuri S. Ledyaev, Ronald J. Stern, Peter R.

Wolenski, 2013-03-17 A clear and succinct presentation of the essentials of this subject together with some of its applications and a generous helping of interesting exercises Following an introductory chapter with a taste of what is to come the next three chapters constitute a course in nonsmooth analysis and identify a coherent and comprehensive approach to the subject leading to an efficient natural and powerful body of theory The whole is rounded off with a self contained introduction to the theory of control of ordinary differential equations The authors have incorporated a number of new results which clarify the relationships between the different schools of thought in the subject with the aim of making nonsmooth analysis accessible to a wider audience End of chapter problems offer scope for deeper understanding

Nonsmooth Analysis and Control

Theory Francis H. Clarke, Yuri S. Ledyaev, Ronald J. Stern, Peter R. Wolenski, 1997-12-19 A clear and succinct presentation of the essentials of this subject together with some of its applications and a generous helping of interesting exercises Following an introductory chapter with a taste of what is to come the next three chapters constitute a course in nonsmooth analysis and identify a coherent and comprehensive approach to the subject leading to an efficient natural and powerful body of theory The whole is rounded off with a self contained introduction to the theory of control of ordinary differential equations The authors have incorporated a number of new results which clarify the relationships between the different schools of thought in the subject with the aim of making nonsmooth analysis accessible to a wider audience End of chapter problems offer scope for deeper understanding

Nonsmooth Analysis and Control Theory Francis H. Clarke, Yuri S. Ledyaev, Ronald J. Stern, Peter R. Wolenski, 2008-01-10 In the last decades the subject of nonsmooth analysis has grown rapidly due to the recognition that nondifferentiable phenomena are more widespread and play a more important role than had been thought In recent years it has come to play a role in functional analysis optimization optimal design mechanics and plasticity differential equations control theory and increasingly in analysis This volume presents the essentials of the subject clearly and succinctly together with some of its applications and a generous supply of interesting exercises The book begins with an introductory chapter which gives the reader a sampling of what is to come while indicating at an early stage why the subject is of interest The next three chapters constitute a course in nonsmooth analysis and identify a coherent and comprehensive approach to the subject leading to an efficient natural yet powerful body of theory The last chapter as its name implies is a self contained introduction to the theory of control of ordinary differential equations End of chapter problems also offer scope for deeper understanding The authors have incorporated in the text a number of new results which clarify the relationships between the different schools of thought in the subject Their goal is to make nonsmooth analysis accessible to a wider audience In this spirit the book is written so as to be used by anyone who has taken a course in functional analysis

Optimal Control, Stabilization and Nonsmooth Analysis Marcio S. de Queiroz, Michael Malisoff, Peter Wolenski, 2004-04-20 This edited book

contains selected papers presented at the Louisiana Conference on Mathematical Control Theory MCT 03 which brought together over 35 prominent world experts in mathematical control theory and its applications The book forms a well integrated exploration of those areas of mathematical control theory in which nonsmooth analysis is having a major impact These include necessary and sufficient conditions in optimal control Lyapunov characterizations of stability input to state stability the construction of feedback mechanisms viscosity solutions of Hamilton Jacobi equations invariance approximation theory impulsive systems computational issues for nonlinear systems and other topics of interest to mathematicians and control engineers The book has a strong interdisciplinary component and was designed to facilitate the interaction between leading mathematical experts in nonsmooth analysis and engineers who are increasingly using nonsmooth analytic tools

Optimal Control, Stabilization and Nonsmooth Analysis Marcio S. de Queiroz, Michael Malisoff, Peter Wolenski, 2014-03-12 This edited book contains selected papers presented at the Louisiana Conference on Mathematical Control Theory MCT 03 which brought together over 35 prominent world experts in mathematical control theory and its applications The book forms a well integrated exploration of those areas of mathematical control theory in which nonsmooth analysis is having a major impact These include necessary and sufficient conditions in optimal control Lyapunov characterizations of stability input to state stability the construction of feedback mechanisms viscosity solutions of Hamilton Jacobi equations invariance approximation theory impulsive systems computational issues for nonlinear systems and other topics of interest to mathematicians and control engineers The book has a strong interdisciplinary component and was designed to facilitate the interaction between leading mathematical experts in nonsmooth analysis and engineers who are increasingly using nonsmooth analytic tools

Geometric Control and Nonsmooth Analysis Fabio Ancona, Henry Hermes, R. Tyrrell Rockafellar, 2008 The aim of this volume is to provide a synthetic account of past research to give an up to date guide to current intertwined developments of control theory and nonsmooth analysis and also to point to future research directions

Optimization and Nonsmooth Analysis Frank H. Clarke, 1990-01-01 This book has appeared in Russian translation and has been praised both for its lively exposition and its fundamental contributions The author first develops a general theory of nonsmooth analysis and geometry which together with a set of associated techniques has had a profound effect on several branches of analysis and optimization Clarke then applies these methods to obtain a powerful unified approach to the analysis of problems in optimal control and mathematical programming Examples are drawn from economics engineering mathematical physics and various branches of analysis in this reprint volume

Set-Valued, Convex, and Nonsmooth Analysis in Dynamics and Control Rafal K. Goebel, 2024-06-26 Set valued analysis convex analysis and nonsmooth analysis are relatively modern branches of mathematical analysis that have become increasingly relevant in current control theory and control engineering literature This book serves as a broad introduction to analytical tools in these fields and to their applications in dynamical and control systems and is the first to cover these topics with this scope and at this level Both

continuous time and discrete time multivalued dynamics modeled by differential and difference inclusions are considered Set Valued Convex and Nonsmooth Analysis in Dynamics and Control An Introduction is aimed at graduate students in control engineering and applied mathematics and researchers in control engineering who have no prior exposure to set valued convex and nonsmooth analysis The book will also be of interest to advanced undergraduate mathematics students and mathematicians with no prior exposure to the topic The expected mathematical background is a course on nonlinear differential equations dynamical systems and a course on real analysis Knowledge of some control theory is helpful but not essential

Liapunov Functions and Stability in Control Theory Andrea Bacciotti, Lionel Rosier, 2005-04-13 This book presents a modern and self contained treatment of the Liapunov method for stability analysis in the framework of mathematical nonlinear control theory A Particular focus is on the problem of the existence of Liapunov functions converse Liapunov theorems and their regularity whose interest is especially motivated by applications to automatic control Many recent results in this area have been collected and presented in a systematic way Some of them are given in extended unified versions and with new simpler proofs In the 2nd edition of this successful book several new sections were added and old sections have been improved e g about the Zubovs method Liapunov functions for discontinuous systems and cascaded systems Many new examples explanations and figures were added making this book accessible and well readable for engineers as well as mathematicians

Nonsmooth Analysis and Geometric Methods in Deterministic Optimal Control Boris S. Mordukhovich, Hector J. Sussmann, 2012-12-06 This IMA Volume in Mathematics and its Applications NONSMOOTH ANALYSIS AND GEOMETRIC METHODS IN DETERMINISTIC OPTIMAL CONTROL is based on the proceedings of a workshop that was an integral part of the 1992-93 IMA program on Control Theory The purpose of this workshop was to concentrate on powerful mathematical techniques that have been developed in deterministic optimal control theory after the basic foundations of the theory existence theorems maximum principle dynamic programming sufficiency theorems for sufficiently smooth fields of extremals were laid out in the 1960s These advanced techniques make it possible to derive much more detailed information about the structure of solutions than could be obtained in the past and they support new algorithmic approaches to the calculation of such solutions We thank Boris S Mordukhovich and Hector J Sussmann for organizing the workshop and editing the proceedings We also take this opportunity to thank the National Science Foundation and the Army Research Office whose financial support made the workshop possible

A vner Friedman Willard Miller Jr v PREFACE This volume contains the proceedings of the workshop on Nonsmooth Analysis and Geometric Methods in Deterministic Optimal Control held at the Institute for Mathematics and its Applications on February 8-17 1993 during a special year devoted to Control Theory and its Applications The workshop whose organizing committee consisted of V J urdjevic B S Mordukhovich R T Rockafellar and H J

Mathematics of Complexity and Dynamical Systems Robert A. Meyers, 2011-10-05 Mathematics of Complexity and Dynamical Systems is an authoritative reference to the basic tools and

concepts of complexity systems theory and dynamical systems from the perspective of pure and applied mathematics

Complex systems are systems that comprise many interacting parts with the ability to generate a new quality of collective behavior through self organization e g the spontaneous formation of temporal spatial or functional structures These systems are often characterized by extreme sensitivity to initial conditions as well as emergent behavior that are not readily predictable or even completely deterministic The more than 100 entries in this wide ranging single source work provide a comprehensive explication of the theory and applications of mathematical complexity covering ergodic theory fractals and multifractals dynamical systems perturbation theory solitons systems and control theory and related topics Mathematics of Complexity and Dynamical Systems is an essential reference for all those interested in mathematical complexity from undergraduate and graduate students up through professional researchers

Open Problems in Mathematical Systems and Control Theory Vincent D. Blondel, Eduardo D. Sontag, Mathukumalli Vidyasagar, Jan C. Willems, 2012-12-06 System and Control theory is one of the most exciting areas of contemporary engineering mathematics From the analysis of Watt s steam engine governor which enabled the Industrial Revolution to the design of controllers for consumer items chemical plants and modern aircraft the area has always drawn from a broad range of tools It has provided many challenges and possibilities for interaction between engineering and established areas of pure and applied mathematics This impressive volume collects a discussion of more than fifty open problems which touch upon a variety of subfields including chaotic observers nonlinear local controllability discrete event and hybrid systems neural network learning matrix inequalities Lyapunov exponents and many other issues Proposed and explained by leading researchers they are offered with the intention of generating further work as well as inspiration for many other similar problems which may naturally arise from them With extensive references this book will be a useful reference source as well as an excellent addendum to the textbooks in the area

Optimal Control Via Nonsmooth Analysis Philip Daniel Loewen, 1993 This book provides a complete and unified treatment of deterministic problems of dynamic optimization from the classical themes of the calculus of variations to the forefront of modern research in optimal control At the heart of the presentation is nonsmooth analysis a theory of local approximation developed over the last twenty years to provide useful first order information about sets and functions lying beyond the reach of classical analysis The book includes an intuitive and geometrically transparent approach to nonsmooth analysis serving not only to introduce the basic ideas but also to illuminate the calculations and derivations in the applied sections dealing with the calculus of variations and optimal control Written in a lively engaging style and stocked with numerous figures and practice problems this book offers an ideal introduction to this vigorous field of current research It is suitable as a graduate text for a one semester course in optimal control or as a manual for self study Each chapter closes with a list of references to ease the reader s transition from active learner to contributing researcher

Nonsmooth Optimization: Analysis And Algorithms With Applications To Optimal Control Marko M Makela, Pekka Neittaanmaki, 1992-05-07 This book is a self

contained elementary study for nonsmooth analysis and optimization and their use in solution of nonsmooth optimal control problems The first part of the book is concerned with nonsmooth differential calculus containing necessary tools for nonsmooth optimization The second part is devoted to the methods of nonsmooth optimization and their development A proximal bundle method for nonsmooth nonconvex optimization subject to nonsmooth constraints is constructed In the last part nonsmooth optimization is applied to problems arising from optimal control of systems covered by partial differential equations Several practical problems like process control and optimal shape design problems are considered **Unsolved Problems in Mathematical Systems and Control Theory** Vincent D. Blondel, Alexandre Megretski, 2009-04-11 This book provides clear presentations of more than sixty important unsolved problems in mathematical systems and control theory Each of the problems included here is proposed by a leading expert and set forth in an accessible manner Covering a wide range of areas the book will be an ideal reference for anyone interested in the latest developments in the field including specialists in applied mathematics engineering and computer science The book consists of ten parts representing various problem areas and each chapter sets forth a different problem presented by a researcher in the particular area and in the same way description of the problem motivation and history available results and bibliography It aims not only to encourage work on the included problems but also to suggest new ones and generate fresh research The reader will be able to submit solutions for possible inclusion on an online version of the book to be updated quarterly on the Princeton University Press website and thus also be able to access solutions updated information and partial solutions as they are developed

Contemporary Trends in Nonlinear Geometric Control Theory and Its Applications A. Anzaldo-Meneses, 2002 Concerns contemporary trends in nonlinear geometric control theory and its applications **Optimal Control Via Nonsmooth Analysis** Philip Daniel Loewen, This book provides a complete and unified treatment of deterministic problems of dynamic optimization from the classical themes of the calculus of variations to the forefront of modern research in optimal control At the heart of the presentation is nonsmooth analysis a theory of local approximation developed over the last twenty years to provide useful first order information about sets and functions lying beyond the reach of classical analysis The book includes an intuitive and geometrically transparent approach to nonsmooth analysis serving not only to introduce the basic ideas but also to illuminate the calculations and derivations in the applied sections dealing with the calculus of variations and optimal control Written in a lively engaging style and stocked with numerous figures and practice problems this book offers an ideal introduction to this vigorous field of current research It is suitable as a graduate text for a one semester course in optimal control or as a manual for self study Each chapter closes with a list of references to ease the reader's transition from active learner to contributing researcher This series is published by the AMS for the Centre de Recherches Mathématiques

Nonlinear Control Systems 2004 Frank Allgower, Michael Zeitz, 2005-02-02 **Geometric Control And Nonsmooth Analysis: In Honor Of The 73rd Birthday Of H Hermes And Of The 71st Birthday Of R T Rockafellar** Fabio

Ancona,Alberto Bressan,Piermarco Cannarsa,Francis H Clarke,Peter R Wolenski,2008-07-08 The aim of this volume is to provide a synthetic account of past research to give an up to date guide to current intertwined developments of control theory and nonsmooth analysis and also to point to future research directions *Analysis and Geometry in Control Theory and its Applications* Piernicola Bettiol,Piermarco Cannarsa,Giovanni Colombo,Monica Motta,Franco Rampazzo,2015-09-01 Since the 1950s control theory has established itself as a major mathematical discipline particularly suitable for application in a number of research fields including advanced engineering design economics and the medical sciences However since its emergence there has been a need to rethink and extend fields such as calculus of variations differential geometry and nonsmooth analysis which are closely tied to research on applications Today control theory is a rich source of basic abstract problems arising from applications and provides an important frame of reference for investigating purely mathematical issues In many fields of mathematics the huge and growing scope of activity has been accompanied by fragmentation into a multitude of narrow specialties However outstanding advances are often the result of the quest for unifying themes and a synthesis of different approaches Control theory and its applications are no exception Here the interaction between analysis and geometry has played a crucial role in the evolution of the field This book collects some recent results highlighting geometrical and analytical aspects and the possible connections between them Applications provide the background in the classical spirit of mutual interplay between abstract theory and problem solving practice

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