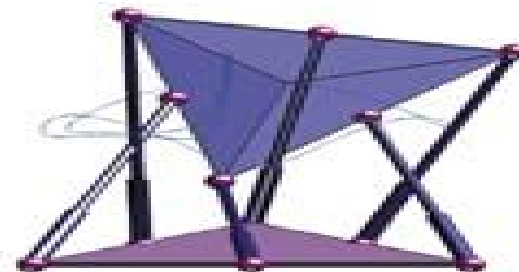
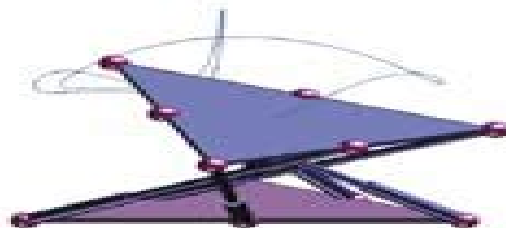
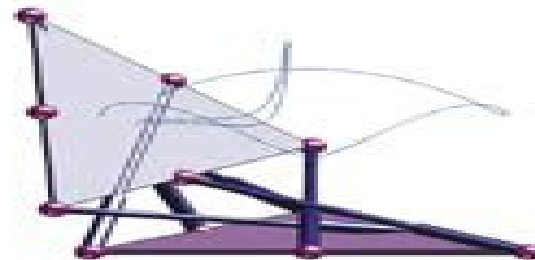


The Numerical Solution of Systems of Polynomials Arising in Engineering and Science



Andrew J. Sommese - Charles W. Wampler, II

Numerical Solution Of Systems Of Polynomials Arising In Engineering And Science

Lorenzo Robbiano, John Abbott



Numerical Solution Of Systems Of Polynomials Arising In Engineering And Science:

The Numerical Solution of Systems of Polynomials Arising in Engineering and Science Andrew John Sommese, Charles Weldon Wampler (II.), 2005 Written by the founders of the new and expanding field of numerical algebraic geometry this is the first book that uses an algebraic geometric approach to the numerical solution of polynomial systems and also the first one to treat numerical methods for finding positive dimensional solution sets The text covers the full theory from methods developed for isolated solutions in the 1980 s to the most recent research on positive dimensional sets **Numerically**

Solving Polynomial Systems with Bertini Daniel J. Bates, Jonathan D. Hauenstein, Andrew J. Sommese, Charles W. Wampler, 2013-11-08 This book is a guide to concepts and practice in numerical algebraic geometry the solution of systems of polynomial equations by numerical methods Through numerous examples the authors show how to apply the well received and widely used open source Bertini software package to compute solutions including a detailed manual on syntax and usage options The authors also maintain a complementary web page where readers can find supplementary materials and Bertini input files Numerically Solving Polynomial Systems with Bertini approaches numerical algebraic geometry from a user s point of view with numerous examples of how Bertini is applicable to polynomial systems It treats the fundamental task of solving a given polynomial system and describes the latest advances in the field including algorithms for intersecting and projecting algebraic sets methods for treating singular sets the nascent field of real numerical algebraic geometry and applications to large polynomial systems arising from differential equations Those who wish to solve polynomial systems can start gently by finding isolated solutions to small systems advance rapidly to using algorithms for finding positive dimensional solution sets curves surfaces etc and learn how to use parallel computers on large problems These techniques are of interest to engineers and scientists in fields where polynomial equations arise including robotics control theory economics physics numerical PDEs and computational chemistry Solving Polynomial Systems Using Continuation for Engineering and Scientific Problems Alexander Morgan, 2009-06-04 An elementary introduction to polynomial continuation Geospatial Algebraic Computations Joseph Awange, Béla Paláncz, 2016-01-29 Improved geospatial instrumentation and technology such as in laser scanning has now resulted in millions of data being collected e g point clouds It is in realization that such huge amount of data requires efficient and robust mathematical solutions that this third edition of the book extends the second edition by introducing three new chapters Robust parameter estimation Multiobjective optimization and Symbolic regression Furthermore the linear homotopy chapter is expanded to include nonlinear homotopy These disciplines are discussed first in the theoretical part of the book before illustrating their geospatial applications in the applications chapters where numerous numerical examples are presented The renewed electronic supplement contains these new theoretical and practical topics with the corresponding Mathematica statements and functions supporting their computations introduced and applied This third edition is renamed in light of these technological advancements **Combinatorial Algebraic Geometry** Gregory G.

Smith,Bernd Sturmfels,2017-11-17 This volume consolidates selected articles from the 2016 Apprenticeship Program at the Fields Institute part of the larger program on Combinatorial Algebraic Geometry that ran from July through December of 2016 Written primarily by junior mathematicians the articles cover a range of topics in combinatorial algebraic geometry including curves surfaces Grassmannians convexity abelian varieties and moduli spaces This book bridges the gap between graduate courses and cutting edge research by connecting historical sources computation explicit examples and new results

Future Vision and Trends on Shapes, Geometry and Algebra Raffaele de Amicis,Giuseppe Conti,2014-06-13 Mathematical algorithms are a fundamental component of Computer Aided Design and Manufacturing CAD CAM systems This book provides a bridge between algebraic geometry and geometric modelling algorithms formulated within a computer science framework Apart from the algebraic geometry topics covered the entire book is based on the unifying concept of using algebraic techniques properly specialized to solve geometric problems to seriously improve accuracy robustness and efficiency of CAD systems It provides new approaches as well as industrial applications to deform surfaces when animating virtual characters to automatically compare images of handwritten signatures and to improve control of NC machines This book further introduces a noteworthy representation based on 2D contours which is essential to model the metal sheet in industrial processes It additionally reviews applications of numerical algebraic geometry to differential equations systems with multiple solutions and bifurcations Future Vision and Trends on Shapes Geometry and Algebra is aimed specialists in the area of mathematics and computer science on the one hand and on the other hand at those who want to become familiar with the practical application of algebraic geometry and geometric modelling such as students researchers and doctorates

Algorithms in Algebraic Geometry Alicia Dickenstein, Frank-Olaf Schreyer, Andrew J. Sommese, 2010-07-10 In the last decade there has been a burgeoning of activity in the design and implementation of algorithms for algebraic geometric computation The workshop on Algorithms in Algebraic Geometry that was held in the framework of the IMA Annual Program Year in Applications of Algebraic Geometry by the Institute for Mathematics and Its Applications on September 2006 is one tangible indication of the interest This volume of articles captures some of the spirit of the IMA workshop *Approximate Commutative Algebra* Lorenzo Robbiano, John Abbott, 2009-09-18 Approximate Commutative Algebra is an emerging field of research which endeavours to bridge the gap between traditional exact Computational Commutative Algebra and approximate numerical computation The last 50 years have seen enormous progress in the realm of exact Computational Commutative Algebra and given the importance of polynomials in scientific modelling it is very natural to want to extend these ideas to handle approximate empirical data deriving from physical measurements of phenomena in the real world In this volume nine contributions from established researchers describe various approaches to tackling a variety of problems arising in Approximate Commutative Algebra Topological and Statistical Methods for Complex Data Janine

Bennett, Fabien Vivodtzev, Valerio Pascucci, 2014-11-19 This book contains papers presented at the Workshop on the Analysis

of Large scale High Dimensional and Multi Variate Data Using Topology and Statistics held in Le Barp France June 2013 It features the work of some of the most prominent and recognized leaders in the field who examine challenges as well as detail solutions to the analysis of extreme scale data The book presents new methods that leverage the mutual strengths of both topological and statistical techniques to support the management analysis and visualization of complex data It covers both theory and application and provides readers with an overview of important key concepts and the latest research trends Coverage in the book includes multi variate and or high dimensional analysis techniques feature based statistical methods combinatorial algorithms scalable statistics algorithms scalar and vector field topology and multi scale representations In addition the book details algorithms that are broadly applicable and can be used by application scientists to glean insight from a wide range of complex data sets

Interactions of Classical and Numerical Algebraic Geometry Daniel James Bates, 2009-09-16 This volume contains the proceedings of the conference on Interactions of Classical and Numerical Algebraic Geometry held May 22-24 2008 at the University of Notre Dame in honor of the achievements of Professor Andrew J Sommese While classical algebraic geometry has been studied for hundreds of years numerical algebraic geometry has only recently been developed Due in large part to the work of Andrew Sommese and his collaborators the intersection of these two fields is now ripe for rapid advancement The primary goal of both the conference and this volume is to foster the interaction between researchers interested in classical algebraic geometry and those interested in numerical methods The topics in this book include but are not limited to various new results in complex algebraic geometry a primer on Seshadri constants analyses and presentations of existing and novel numerical homotopy methods for solving polynomial systems a numerical method for computing the dimensions of the cohomology of twists of ideal sheaves and the application of algebraic methods in kinematics and phylogenetics

Mathematical Software - ICMS 2020 Anna Maria Bigatti, Jacques Carette, James H. Davenport, Michael Joswig, Timo de Wolff, 2020-07-07 This book constitutes the proceedings of the 7th International Conference on Mathematical Software ICMS 2020 held in Braunschweig Germany in July 2020 The 48 papers included in this volume were carefully reviewed and selected from 58 submissions The program of the 2020 meeting consisted of 20 topical sessions each of which providing an overview of the challenges achievements and progress in a environment of mathematical software research development and use

The New Palgrave Dictionary of Economics, 2016-05-18 The award winning The New Palgrave Dictionary of Economics 2nd edition is now available as a dynamic online resource Consisting of over 1 900 articles written by leading figures in the field including Nobel prize winners this is the definitive scholarly reference work for a new generation of economists Regularly updated This product is a subscription based product

21st Century Kinematics J. Michael McCarthy, 2012-08-04 21st Century Kinematics focuses on algebraic problems in the analysis and synthesis of mechanisms and robots compliant mechanisms cable driven systems and protein kinematics The specialist contributors provide the background for a series of presentations at the 2012 NSF Workshop The

text shows how the analysis and design of innovative mechanical systems yield increasingly complex systems of polynomials characteristic of those systems. In doing so it takes advantage of increasingly sophisticated computational tools developed for numerical algebraic geometry and demonstrates the now routine derivation of polynomial systems dwarfing the landmark problems of even the recent past. The 21st Century Kinematics workshop echoes the NSF supported 1963 Yale Mechanisms Teachers Conference that taught a generation of university educators the fundamental principles of kinematic theory. As such these proceedings will provide admirable supporting theory for a graduate course in modern kinematics and should be of considerable interest to researchers in mechanical design, robotics or protein kinematics or who have a broader interest in algebraic geometry and its applications.

Nonlinear Computational Geometry Ioannis Z. Emiris, Frank Sottile, Thorsten Theobald, 2009-10-28. An original motivation for algebraic geometry was to understand curves and surfaces in three dimensions. Recent theoretical and technological advances in areas such as robotics, computer vision, computer aided geometric design and molecular biology together with the increased availability of computational resources have brought these original questions once more into the forefront of research. One particular challenge is to combine applicable methods from algebraic geometry with proven techniques from piecewise linear computational geometry such as Voronoi diagrams and hyperplane arrangements to develop tools for treating curved objects. These research efforts may be summarized under the term nonlinear computational geometry. This volume grew out of an IMA workshop on Nonlinear Computational Geometry in May/June 2007 organized by I. Z. Emiris, R. Goldman, F. Sottile, T. Theobald which gathered leading experts in this emerging field. The research and expository articles in the volume are intended to provide an overview of nonlinear computational geometry. Since the topic involves computational geometry, algebraic geometry and geometric modeling the volume has contributions from all of these areas. By addressing a broad range of issues from purely theoretical and algorithmic problems to implementation and practical applications this volume conveys the spirit of the IMA workshop.

Polynomial Optimization, Moments, and Applications Michal Kočvara, Bernard Mourrain, Cordian Riener, 2023-12-27. Polynomial optimization is a fascinating field of study that has revolutionized the way we approach nonlinear problems described by polynomial constraints. The applications of this field range from production planning processes to transportation, energy consumption and resource control. This introductory book explores the latest research developments in polynomial optimization presenting the results of cutting edge interdisciplinary work conducted by the European network POEMA. For the past four years experts from various fields including algebraists, geometers, computer scientists and industrial actors have collaborated in this network to create new methods that go beyond traditional paradigms of mathematical optimization. By exploiting new advances in algebra and convex geometry these innovative approaches have resulted in significant scientific and technological advancements. This book aims to make these exciting developments accessible to a wider audience by gathering high quality chapters on these hot topics. Aimed at both aspiring and established researchers as well as industry

professionals this book will be an invaluable resource for anyone interested in polynomial optimization and its potential for real world applications **Stochastic Models, Information Theory, and Lie Groups, Volume 1** Gregory S.

Chirikjian,2009-09-02 This unique two volume set presents the subjects of stochastic processes information theory and Lie groups in a unified setting thereby building bridges between fields that are rarely studied by the same people Unlike the many excellent formal treatments available for each of these subjects individually the emphasis in both of these volumes is on the use of stochastic geometric and group theoretic concepts in the modeling of physical phenomena Stochastic Models Information Theory and Lie Groups will be of interest to advanced undergraduate and graduate students researchers and practitioners working in applied mathematics the physical sciences and engineering Extensive exercises and motivating examples make the work suitable as a textbook for use in courses that emphasize applied stochastic processes or differential geometry **Matrix Methods in the Design Analysis of Mechanisms and Multibody Systems** John J. Uicker,Bahram

Ravani,Pradip N. Sheth,2013-04-15 This book is an integrated approach to kinematic and dynamic analysis The matrix techniques presented are general and fully applicable to two or three dimensional systems They lend themselves to programming and digital computation and can act as the basis of a usable tool for designers Techniques have broad applicability to the design analysis of all multibody mechanical systems The more powerful and more flexible the approach and the less specialisation and reprogramming required for each application the better The matrix methods presented have been developed using these ideas as primary goals Matrix methods can be applied by hand to such problems as the slider crank mechanism but this is not the intent of this text and often the rigor required for such an attempt becomes quite burdensome in comparison with other techniques The matrix methods have been extensively tested both in the classroom and in the world of engineering industry Computational Kinematics Federico Thomas,Alba Perez Gracia,2013-10-17

Computational kinematics is an enthralling area of science with a rich spectrum of problems at the junction of mechanics robotics computer science mathematics and computer graphics The covered topics include design and optimization of cable driven robots analysis of parallel manipulators motion planning numerical methods for mechanism calibration and optimization geometric approaches to mechanism analysis and design synthesis of mechanisms kinematical issues in biomechanics construction of novel mechanical devices as well as detection and treatment of singularities The results should be of interest for practicing and research engineers as well as Ph D students from the fields of mechanical and electrical engineering computer science and computer graphics *Computer Algebra in Scientific Computing* Vladimir P.

Gerdt,Wolfram Koepf,Werner M. Seiler,Evgenii V. Vorozhtsov,2017-09-07 This book constitutes the proceedings of the 19th International Workshop on Computer Algebra in Scientific Computing CASC 2017 held in Beijing China in September 2017 The 28 full papers presented in this volume were carefully reviewed and selected from 33 submissions They deal with cutting edge research in all major disciplines of Computer Algebra Advances in Reconfigurable Mechanisms and Robots II Xilun

Ding,Xianwen Kong,Jian S. Dai,2015-11-23 This book presents the most recent advances in the research and applications of reconfigurable mechanisms and robots It collects 93 independently reviewed papers presented at the Third ASME IFToMM International Conference on Reconfigurable Mechanisms and Robots ReMAR 2015 held in Beijing China 20 22 July 2015 The conference papers are organized into seven parts to cover the reconfiguration theory topology kinematics and design of reconfigurable mechanisms including reconfigurable parallel mechanisms The most recent results on reconfigurable robots are presented including their analysis design simulation and control Bio inspired mechanisms are also explored in the challenging fields of rehabilitation and minimally invasive surgery This book further addresses deployable mechanisms and origami inspired mechanisms and showcases a wide range of successful applications of reconfigurable mechanisms and robots Advances in Reconfigurable Mechanisms and Robots II should be of interest for researchers engineers and postgraduate students in mechanical engineering electrical engineering computer science and mathematics

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