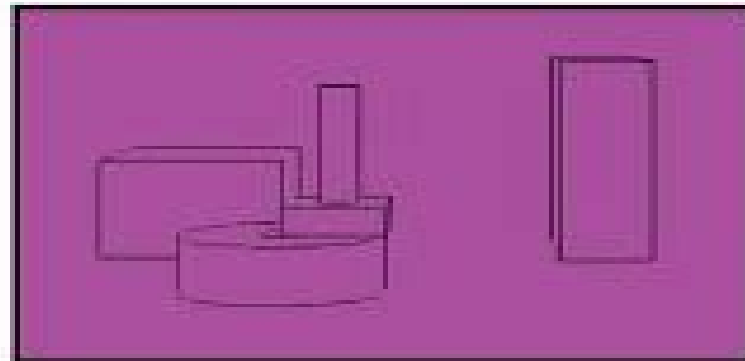

Machine Learning of Robot Assembly Plans

Alberto Maria Segre



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Ryszard S. Michalski, George Tecuci



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Machine Learning of Robot Assembly Plans Alberto Maria Segre, 2012-12-06 The study of artificial intelligence AI is indeed a strange pursuit Unlike most other disciplines few AI researchers even agree on a mutually acceptable definition of their chosen field of study Some see AI as a sub field of computer science others see AI as a computationally oriented branch of psychology or linguistics while still others see it as a bag of tricks to be applied to an entire spectrum of diverse domains This lack of unified purpose among the AI community makes this a very exciting time for AI research new and diverse projects are springing up literally every day As one might imagine however this diversity also leads to genuine difficulties in assessing the significance and validity of AI research These difficulties are an indication that AI has not yet matured as a science it is still at the point where people are attempting to lay down hopefully sound foundations Ritchie and Hanna 1 posit the following categorization as an aid in assessing the validity of an AI research endeavor 1 The project could introduce in outline a novel or partly novel idea or set of ideas 2 The project could elaborate the details of some approach Starting with the kind of idea in 1 the research could criticize it or fill in further details 3 The project could be an AI experiment where a theory as in 1 and 2 is applied to some domain Such experiments are usually computer programs that implement a particular theory

Machine Learning Methods for Planning Steven Minton, 2014-05-12 Machine Learning Methods for Planning provides information pertinent to learning methods for planning and scheduling This book covers a wide variety of learning methods and learning architectures including analogical case based decision tree explanation based and reinforcement learning Organized into 15 chapters this book begins with an overview of planning and scheduling and describes some representative learning systems that have been developed for these tasks This text then describes a learning apprentice for calendar management Other chapters consider the problem of temporal credit assignment and describe tractable classes of problems for which optimal plans can be derived This book discusses as well how reactive integrated systems give rise to new requirements and opportunities for machine learning The final chapter deals with a method for learning problem decompositions which is based on an idealized model of efficiency for problem reduction search This book is a valuable resource for production managers planners scientists and research workers

Machine Learning Ryszard S. Michalski, George Tecuci, 1994-02-09 Multistrategy learning is one of the newest and most promising research directions in the development of machine learning systems The objectives of research in this area are to study trade offs between different learning strategies and to develop learning systems that employ multiple types of inference or computational paradigms in a learning process Multistrategy systems offer significant advantages over monostrategy systems They are more flexible in the type of input they can learn from and the type of knowledge they can acquire As a consequence multistrategy systems have the potential to be applicable to a wide range of practical problems This volume is the first book in this fast growing field It contains a selection of contributions by leading researchers specializing in this area See below for earlier volumes in the

series Machine Learning Yves Kodratoff, Ryszard S. Michalski, 2014-06-28 Machine Learning An Artificial Intelligence Approach Volume III presents a sample of machine learning research representative of the period between 1986 and 1989 The book is organized into six parts Part One introduces some general issues in the field of machine learning Part Two presents some new developments in the area of empirical learning methods such as flexible learning concepts the Protos learning apprentice system and the WITT system which implements a form of conceptual clustering Part Three gives an account of various analytical learning methods and how analytic learning can be applied to various specific problems Part Four describes efforts to integrate different learning strategies These include the UNIMEM system which empirically discovers similarities among examples and the DISCIPLE multistrategy system which is capable of learning with imperfect background knowledge Part Five provides an overview of research in the area of subsymbolic learning methods Part Six presents two types of formal approaches to machine learning The first is an improvement over Mitchell's version space method the second technique deals with the learning problem faced by a robot in an unfamiliar deterministic finite state environment **Recent Advances in Robot Learning** Judy A. Franklin, Tom M. Mitchell, Sebastian Thrun, 2012-12-06

Recent Advances in Robot Learning contains seven papers on robot learning written by leading researchers in the field As the selection of papers illustrates the field of robot learning is both active and diverse A variety of machine learning methods ranging from inductive logic programming to reinforcement learning is being applied to many subproblems in robot perception and control often with objectives as diverse as parameter calibration and concept formulation While no unified robot learning framework has yet emerged to cover the variety of problems and approaches described in these papers and other publications a clear set of shared issues underlies many robot learning problems Machine learning when applied to robotics is situated it is embedded into a real world system that tightly integrates perception decision making and execution Since robot learning involves decision making there is an inherent active learning issue Robotic domains are usually complex yet the expense of using actual robotic hardware often prohibits the collection of large amounts of training data Most robotic systems are real time systems Decisions must be made within critical or practical time constraints These characteristics present challenges and constraints to the learning system Since these characteristics are shared by other important real world application domains robotics is a highly attractive area for research on machine learning On the other hand machine learning is also highly attractive to robotics There is a great variety of open problems in robotics that defy a static hand coded solution Recent Advances in Robot Learning is an edited volume of peer reviewed original research comprising seven invited contributions by leading researchers This research work has also been published as a special issue of Machine Learning Volume 23 Numbers 2 and 3 **Intelligent Robots - Sensing, Modeling And Planning** Bob Bolles, Horst Bunke, Hartmut Noltemeier, 1997-12-04 Rapid advances in sensors computers and algorithms continue to fuel dramatic improvements in intelligent robots In addition robot vehicles are starting to appear in a number of applications For example

they have been installed in public settings to perform such tasks as delivering items in hospitals and cleaning floors in supermarkets recently two small robot vehicles were launched to explore Mars This book presents the latest advances in the principal fields that contribute to robotics It contains contributions written by leading experts addressing topics such as Path and Motion Planning Navigation and Sensing Vision and Object Recognition Environment Modeling and others *Innovative Approaches to Planning, Scheduling and Control* Katia P. Sycara,1990

Advances in Intelligent Autonomous Systems S.G. Tzafestas,2012-12-06 The field of Intelligent Autonomous Systems IAS has attracted over the years the attention of numerous research and industrial groups and has by now arrived at an advanced level of development The results have been achieved through the synergetic use of concepts techniques and technologies drawn from electrical and mechanical engineering control engineering systems science computer science and management science Currently the majority of working systems in practice are of the semi autonomous type needing some level of human intervention Therefore much effort is presently devoted in academic research and industrial environments towards further increasing the level of autonomy This book provides a collection of essays which cover the latest research in the IAS field and present a rich set of results accompanied by detailed descriptions of the relevant concepts tools techniques and hardware software designs The book contains twenty three chapters grouped in the following parts Part 1 General concepts architectures and technologies Part 2 Mobile walking and snake like robots Part 3 Applications PART 1 involves the first seven chapters which deal with generic issues Chapter 1 by S G Tzafestas provides some background material accompanied by a description of two research IAS prototypes namely a car disassembly robotic system and a semi autonomous autonomous robotic wheelchair Chapter 2 by G Bolmsjo M Olsson and K Brink presents a generic event based control system structure for the control of a robotic workcell including its implementation where the autonomous operation is achieved via reactive replanning and configurable corrections

Machine Learning: ECML'97 Maarten van Someren, Gerhard Widmer,1997-04-09 This book constitutes the refereed proceedings of the Ninth European Conference on Machine Learning ECML 97 held in Prague Czech Republic in April 1997 This volume presents 26 revised full papers selected from a total of 73 submissions Also included are an abstract and two papers corresponding to the invited talks as well as descriptions from four satellite workshops The volume covers the whole spectrum of current machine learning issues

Handbook of Expert Systems Applications in Manufacturing Structures and rules A. Mital,S. Anand,2013-03-08 This book is aimed at both researchers and practitioners and provides a collection of expert systems in manufacturing and production engineering along with their knowledge base and rules We believe that inclusion of the knowledge base and associated rules is essential if practitioners are to derive full benefit from these expert systems This unique book is the result of our belief and the efforts of our distinguished colleagues who subscribe to this philosophy A total of 15 different expert systems are included in this book These expert systems are preceded by an introductory chapter written by Kuo Preface XVII Mital and Anand The expert system rules are included on a

floppy disk in ASCII and can be easily accessed These rules and the description of the expert system s structure should assist the users in customizing these systems Overall the expert systems included in this volume cover a fairly wide variety of manufacturing and production engineering topics

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