

Katsu Yamane

# Simulating and Generating Motions of Human Figures



Springer

# Simulating And Generating Motions Of Human Figures

**Jun Yu,Dacheng Tao**



## **Simulating And Generating Motions Of Human Figures:**

**Simulating and Generating Motions of Human Figures** Katsu Yamane, 2004-01-15 This book focuses on two issues related to human figures realtime dynamics computation and interactive motion generation In spite of the growing interest in human figures as both physical robots and virtual characters standard algorithms and tools for their kinematics and dynamics computation have not been investigated very much Simulating and Generating Motions of Human Figures presents original algorithms to simulate analyze generate and control motions of human figures all focusing on realtime and interactive computation The book provides both practical methods for contact collision simulation essential for the simulation of humanoid robots and virtual characters and a general framework for online interactive motion generation of human figures based on the dynamics simulation algorithms Motion Planning in Medicine: Optimization and Simulation

Algorithms for Image-Guided Procedures Ron Alterovitz, Ken Goldberg, 2008-09-20 Written by Ron Alterovitz and Ken Goldberg this monograph combines ideas from robotics physically based modeling and operations research to develop new motion planning and optimization algorithms for image guided medical procedures **Simulating Humans** Norman I. Badler, Cary B. Phillips, Bonnie Lynn Webber, 1993-06-17 During the past decade high performance computer graphics have found application in an exciting and expanding range of new domains Among the most dramatic developments has been the incorporation of real time interactive manipulation and display for human figures Though actively pursued by several research groups the problem of providing a synthetic or surrogate human for engineers and designers already familiar with computer aided design techniques was most comprehensively solved by Norman Badler s computer graphics laboratory at the University of Pennsylvania The breadth of that effort as well as the details of its methodology and software environment are presented in this volume The book is intended for human factors engineers interested in understanding how a computer graphics surrogate human can augment their analyses of designed environments It will also inform design engineers of the state of the art in human figure modeling and hence of the human centered design central to the emergent concept of concurrent engineering In fulfilling these goals the book additionally documents for the entire computer graphics community a major research effort in the interactive control of articulated human figures **Computer Animation and Simulation**

'99 Nadia Magnenat-Thalmann, Daniel Thalmann, 2012-12-06 The 20 research papers in this volume demonstrate novel models and concepts in animation and graphics simulation Special emphasis is given on innovative approaches to Modelling Human Motion Models of Collision Detection and Perception Facial Animation and Communication Specific Animation Models Realistic Rendering for Animation and Behavioral Animation **Modern Machine Learning Techniques and Their Applications in Cartoon Animation Research** Jun Yu, Dacheng Tao, 2013-03-27 The integration of machine learning techniques and cartoon animation research is fast becoming a hot topic This book helps readers learn the latest machine learning techniques including patch alignment framework spectral clustering graph cuts and convex relaxation ensemble

manifold learning multiple kernel learning multiview subspace learning and multiview distance metric learning It then presents the applications of these modern machine learning techniques in cartoon animation research With these techniques users can efficiently utilize the cartoon materials to generate animations in areas such as virtual reality video games animation films and sport simulations

*Physics-Based Deformable Models* Dimitris N. Metaxas, 2012-12-06 Physics Based Deformable Models presents a systematic physics based framework for modeling rigid articulated and deformable objects their interactions with the physical world and the estimate of their shape and motion from visual data This book presents a large variety of methods and associated experiments in computer vision graphics and medical imaging that help the reader better to understand the presented material In addition special emphasis has been given to the development of techniques with interactive or close to real time performance Physics Based Deformable Models is suitable as a secondary text for graduate level courses in Computer Graphics Computational Physics Computer Vision Medical Imaging and Biomedical Engineering In addition this book is appropriate as a reference for researchers and practitioners in the above mentioned fields

Knowledge-Based Simulation Paul A. Fishwick, Richard B. Modjeski, 2012-12-06 Knowledge Based Simulation Methodology and Application represents a recent compilation of research material that reviews fundamental concepts of simulation methodology and knowledge based simulation applications Knowledge based simulation represents a new and exciting bridge area linking the fields of computer simulation and artificial intelligence This book will appeal to both theorists and practitioners who require simulation to solve complex problems A primary attraction of the book is its emphasis on both methodology and applications In this way the reader can explore new methods for encoding knowledge intensive information into a simulation model and new applications that utilize these methods

*Measuring, modelling and minimizing perceived motion incongruence for vehicle motion simulation* Diane Cleij, 2020-01-28 Humans always wanted to go faster and higher than their own legs could carry them This led them to invent numerous types of vehicles to move fast over land water and air As training how to handle such vehicles and testing new developments can be dangerous and costly vehicle motion simulators were invented Motion based simulators in particular combine visual and physical motion cues to provide occupants with a feeling of being in the real vehicle While visual cues are generally not limited in amplitude physical cues certainly are due to the limited simulator motion space A motion cueing algorithm MCA is used to map the vehicle motions onto the simulator motion space This mapping inherently creates mismatches between the visual and physical motion cues Due to imperfections in the human perceptual system not all visual physical cueing mismatches are perceived However if a mismatch is perceived it can impair the simulation realism and even cause simulator sickness For MCA design a good understanding of when mismatches are perceived and ways to prevent these from occurring are therefore essential In this thesis a data driven approach using continuous subjective measures of the time varying Perceived Motion Incongruence PMI is adopted PMI in this case refers to the effect that perceived mismatches between visual and physical motion cues have on

the resulting simulator realism The main goal of this thesis was to develop an MCA independent off line prediction method for time varying PMI during vehicle motion simulation with the aim of improving motion cueing quality To this end a complete roadmap describing how to measure and model PMI and how to apply such models to predict and minimize PMI in motion simulations is presented Results from several human in the loop experiments are used to demonstrate the potential of this novel approach

**Consciousness and Action Control** T. Andrew Poehlman, Ezequiel Morsella, 2014-11-03 The basic nuts and bolts underlying human behavior remain mysterious from a scientific point of view Everyday acts naming an object suppressing the urge to say something or grabbing a waiter's attention with a cappuccino please remain difficult to understand from a mechanistic standpoint Despite these challenges research has begun to illuminate not only the basic processes underlying human action production but the role of conscious processing in the control of behavior This Research Topic Consciousness and the Control of Action is devoted to surveying and synthesizing these developments from disparate fields of study

**Modeling, Simulation and Optimization of Bipedal Walking** Katja Mombaur, Karsten Berns, 2013-02-28 The model based investigation of motions of anthropomorphic systems is an important interdisciplinary research topic involving specialists from many fields such as Robotics Biomechanics Physiology Orthopedics Psychology Neurosciences Sports Computer Graphics and Applied Mathematics This book presents a study of basic locomotion forms such as walking and running is of particular interest due to the high demand on dynamic coordination actuator efficiency and balance control Mathematical models and numerical simulation and optimization techniques are explained in combination with experimental data which can help to better understand the basic underlying mechanisms of these motions and to improve them Example topics treated in this book are Modeling techniques for anthropomorphic bipedal walking systems Optimized walking motions for different objective functions Identification of objective functions from measurements Simulation and optimization approaches for humanoid robots Biologically inspired control algorithms for bipedal walking Generation and deformation of natural walking in computer graphics Imitation of human motions on humanoids Emotional body language during walking Simulation of biologically inspired actuators for bipedal walking machines Modeling and simulation techniques for the development of prostheses Functional electrical stimulation of walking

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