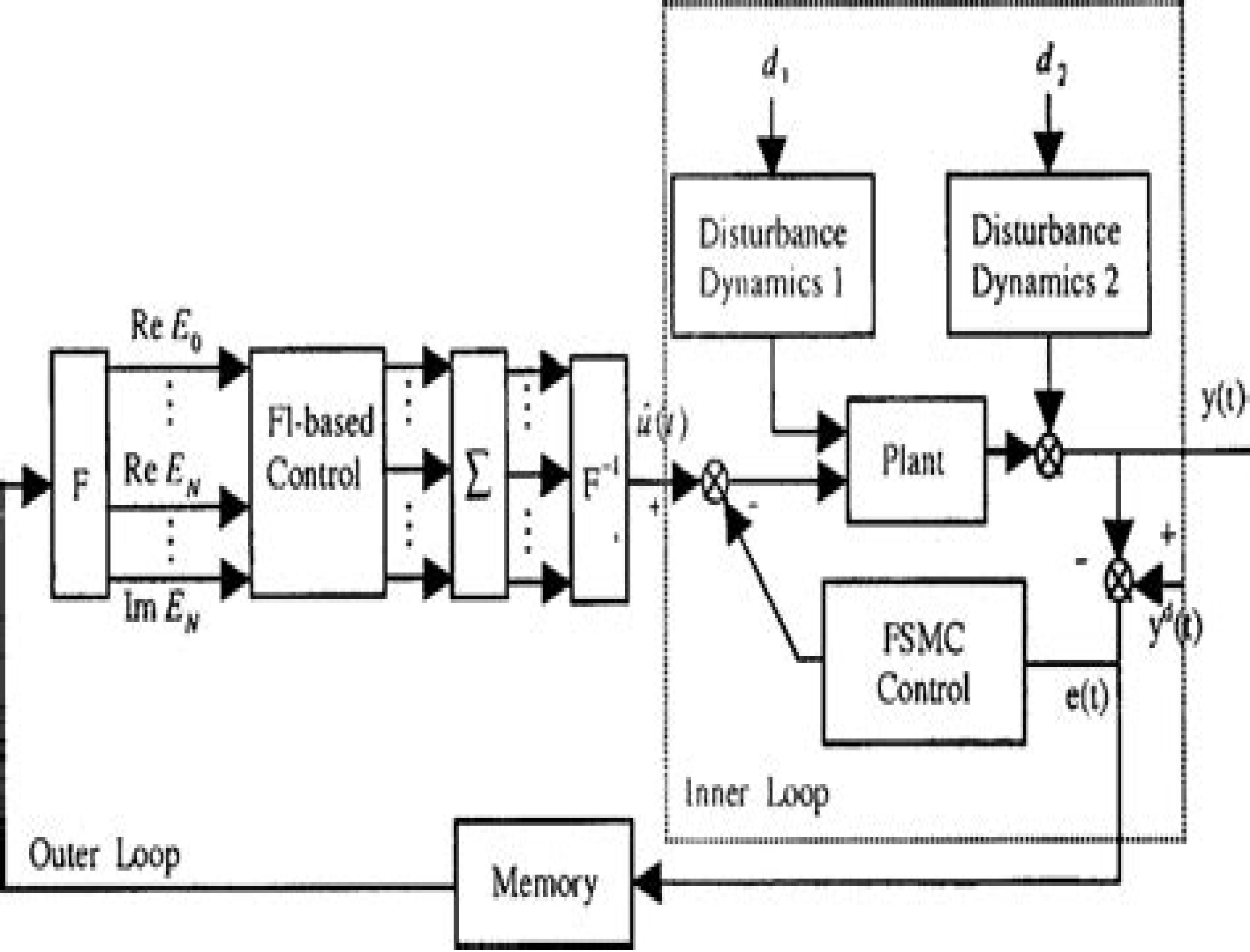




Nonlinear Adaptive Control

**Nikolai Michailovich Filatov, Heinz
Unbehauen**



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Nonlinear and Adaptive Control Design Miroslav Krstic, Ioannis Kanellakopoulos, Petar V. Kokotovic, 1995-06-14 Using a pedagogical style along with detailed proofs and illustrative examples this book opens a view to the largely unexplored area of nonlinear systems with uncertainties The focus is on adaptive nonlinear control results introduced with the new recursive design methodology adaptive backstepping Describes basic tools for nonadaptive backstepping design with state and output feedbacks **Nonlinear and Adaptive Control of Complex Systems** A.L. Fradkov, I.V. Miroshnik, V.O.

Nikiforov, 2013-06-29 This volume presents a theoretical framework and control methodology for a class of complex dynamical systems characterised by high state space dimension multiple inputs and outputs significant nonlinearity parametric uncertainty and unmodeled dynamics A unique feature of the authors approach is the combination of rigorous concepts and methods of nonlinear control invariant and attracting submanifolds Lyapunov functions exact linearisation passification with approximate decomposition results based on singular perturbations and decentralisation Some results published previously in the Russian literature and not well known in the West are brought to light Basic concepts of modern nonlinear control and motivating examples are given Audience This book will be useful for researchers engineers university lecturers and postgraduate students specialising in the fields of applied mathematics and engineering such as automatic control robotics and control of vibrations **Nonlinear And Adaptive Control: Tools And Algorithms For The User**

Alessandro Astolfi, 2005-12-15 This book summarizes the main results achieved in a four year European Project on nonlinear and adaptive control The project involves leading researchers from top notch institutions Imperial College London Prof A Astolfi Lund University Prof A Rantzer Supélec Paris Prof R Ortega University of Technology of Compiègne Prof R Lozano Grenoble Polytechnic Prof C Canudas de Wit University of Twente Prof A van der Schaft Politecnico di Milano Prof S Bittanti and Polytechnic University of Valencia Prof P Albertos The book also provides an introduction to theoretical advances in nonlinear and adaptive control and an overview of novel applications of advanced control theory particularly topics on the control of partially known systems under actuated systems and bioreactors a **Nonlinear and Adaptive Control** Alan S.I.

Zinober, David H. Owens, 2002-09-12 The objective of the EU Nonlinear Control Network Workshop was to bring together scientists who are already active in nonlinear control and young researchers working in this field This book presents selectively invited contributions from the workshop some describing state of the art subjects that already have a status of maturity while others propose promising future directions in nonlinear control Amongst others following topics of nonlinear and adaptive control are included adaptive and robust control applications in physical systems distributed parameter systems disturbance attenuation dynamic feedback optimal control sliding mode control and tracking and motion planning

Adaptive Dual Control Nikolai Michailovich Filatov, Heinz Unbehauen, 2004-04-20 This monograph demonstrates how the performance of various well known adaptive controllers can be improved significantly using the dual effect The modifications

to incorporate dual control are realized separately and independently of the main adaptive controller without complicating the algorithms. A new bicriterial approach for dual control is developed and applied to various types of popular linear and nonlinear adaptive controllers. Practical applications of the designed controllers to several real time problems are presented. This monograph is the first book providing a complete exposition on the dual control problem from the inception in the early 1960s to the present state of the art aiming at students and researchers in adaptive control as well as design engineers in industry.

Nonlinear and Adaptive Control Systems Zhengtao Ding, 2013 **Nonlinear and Adaptive Control Systems** Zhengtao Ding, 2013-04-04

Nonlinear and Adaptive Control Systems treats nonlinear control and adaptive control in a unified framework presenting the major results at a moderate mathematical level suitable for MSc students and engineers with undergraduate degrees.

Nonlinear Adaptive Control with Application to Flexible Structures Ouassima Akhrif, 1989

Nonlinear Adaptive Control Systems with Storage Naresh K. Sinha, 1964 Some Problems in Nonlinear Adaptive Control Pawel Podsiadlo, 1994

Robustness and Performance of Nonlinear Adaptive Control Systems Youping Zhang, 1996 *Nonlinear Adaptive Control of Highly Maneuverable High Performance Aircraft* Sul Cho, 1993

This thesis presents an effective control design methodology using a one step ahead prediction adaptive control law and an adaptive control law based on a Lyapunov function. These control laws were applied to a highly maneuverable high performance aircraft in particular a modified F/A-18. An adaptive controller is developed to maneuver an aircraft at a high angle of attack even if the aircraft is required to fly over a highly nonlinear flight regime. The adaptive controller presented in this thesis is based on linear, bilinear and nonlinear prediction models with input constraints. It is shown that the linear, bilinear and nonlinear adaptive controllers can be constructed to minimize the given cost function or Lyapunov function with respect to the control input at each step. The control is calculated such that the system follows the reference trajectory and such that the control signal remains within its constraints. From several simulation results the nonlinear controller is better than the linear controller. A nonlinear adaptive control law based on a Lyapunov function is designed such that control inputs are smoother than for the one step ahead prediction adaptive controller.

Model Free Adaptive Control Zhongsheng Hou, Shangtai Jin, 2013-09-24

Model Free Adaptive Control Theory and Applications summarizes theory and applications of model free adaptive control (MFAC). MFAC is a novel adaptive control method for the unknown discrete time nonlinear systems with time varying parameters and time varying structure and the design and analysis of MFAC merely depend on the measured input and output.

Nonlinear Adaptive Control and Applications in Power Systems Lin Jiang, University of Liverpool, 2001

Adaptive Control Systems Gang Feng, Rogelio Lozano, 1999-05-10

Adaptive control is no longer just an important theoretical field of study but is also providing solutions to real world problems. Adaptive techniques will transform the world of control. The leading world practitioners of adaptive control have contributed to this handbook which is the most important work yet in this field. Not only are techniques described in theory but detailed control algorithms are given making

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Periodic Nonlinear Adaptive Control of Rapidly Time-varying Linear Systems Joel David Simard, 2018 In adaptive control the goal is to deal with systems that have unknown and or time varying parameters Most techniques are proven for the case in which any time variation is slow with results for systems with fast time variations limited to those for which the time variation is of a known form or for which the plant has stable zero dynamics Here we propose a new adaptive controller design methodology for which the time variation can be rapid While the plant is allowed to have unstable zero dynamics it must satisfy several structural conditions which have been proven to be necessary in the literature we also impose some mild regularity conditions The proposed controller is nonlinear and periodic and in each period the parameter values are estimated and an appropriate stabilizing control signal is applied Under the technical assumptions that the plant is relative degree one and that the plant uncertainty is in terms of a single scalar variable it is proven that the closed loop system is stable under fast parameter variations with persistent jumps

Identification and Adaptive Control for Nonlinear Systems and Applications Jianhua Zhang, Yang Li, Qiang Chen, 2022-03-15 Identification and Adaptive Control for Nonlinear Systems and Applications Applied Mathematics in Control Engineering introduces nonlinear systems concepts system analysis system control methods and applications in various fields The major contribution of the book includes 1 The basic concepts of nonlinear systems stability analysis and nonlinear systems control method 2 The stability analysis of complex nonlinear system with adaptive neural networks control 3 The nonlinear systems adaptive sliding mode controller design of complex nonlinear systems 4 Some industrial application The book gives an introduction to basic nonlinear systems architectures for adaptive control methods Emphasis is placed on the mathematical analysis of these systems on methods of controlling them for adaptive control and on their application to practical engineering problems in such areas as aircraft path planning This book enables audience to understand the basic architectures of control science and engineering and to master classical and advanced design method for nonlinear system Introduces nonlinear systems concepts system analysis system control methods and applications in various fields Presents basic concepts of nonlinear systems stability analysis and nonlinear systems control method Offers practical examples

Delay Compensation for Nonlinear, Adaptive, and PDE Systems Miroslav Krstic, 2010-01-23 Some of the most common dynamic phenomena that arise in engineering practice actuator and sensor delays fall outside the scope of standard finite dimensional system theory The first attempt at infinite

dimensional feedback design in the field of control systems the Smith predictor has remained limited to linear finite dimensional plants over the last five decades Shedding light on new opportunities in predictor feedback this book significantly broadens the set of techniques available to a mathematician or engineer working on delay systems The book is a collection of tools and techniques that make predictor feedback ideas applicable to nonlinear systems systems modeled by PDEs systems with highly uncertain or completely unknown input output delays and systems whose actuator or sensor dynamics are modeled by more general hyperbolic or parabolic PDEs rather than by pure delay Numerous examples and a detailed treatment of individual classes of problems will help the reader master the techniques Delay Compensation for Nonlinear Adaptive and PDE Systems is an excellent reference guide for graduate students researchers and professionals in mathematics systems control as well as chemical mechanical electrical computer aerospace and civil structural engineering Parts of the book may be used in graduate courses on general distributed parameter systems linear delay systems PDEs nonlinear control state estimator and observers adaptive control robust control or linear time varying systems Nonlinear Adaptive Control of Electro-mechanical Systems Degang Chen,1992 Nonlinear Adaptive Control Design with Applications,2005

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