

Pyramidal Systems for Computer Vision

Edited by V. Cantoni and S. Levialdi

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Pyramidal Systems For Computer Vision Nato Asi Series F Computer And Systems Sciences Volume 25

Virginio Cantoni, Stefano Levialdi

Pyramidal Systems For Computer Vision Nato Asi Series F Computer And Systems Sciences Volume 25:

Pyramidal Systems for Computer Vision Virginio Cantoni, Stefano Levialdi, 2012-12-06 This book contains the proceedings of the NATO Advanced Research Workshop held in Maratea Italy May 5 9 1986 on Pyramidal Systems for Image Processing and Computer Vision We had 40 participants from 11 countries playing an active part in the workshop and all the leaders of groups that have produced a prototype pyramid machine or a design for such a machine were present Within the wide field of parallel architectures for image processing a new area was recently born and is growing healthily the area of pyramidally structured multiprocessing systems Essentially the processors are arranged in planes from a base to an apex each one of which is generally a reduced usually by a power of two version of the plane underneath these processors are horizontally interconnected within a plane and vertically connected with fathers on top planes and children on the plane below This arrangement has a number of interesting features all of which were amply discussed in our Workshop including the cellular array and hypercube versions of pyramids A number of projects in different parts of the world are reported as well as some interesting applications in computer vision tactile systems and numerical calculations Interactive Testing and Self-Assessment Dieudonne A. Leclercq, James E. Bruno, 2012-12-06 Assessment has long been recognized as a key feature in learning efficacy especially through formative evaluation Item banking the storage and classification of test items is an essential part of systematic assessment This volume is based on a NATO Advanced Research Workshop held as part of the Special Programme on Advanced Educational Technology The workshop brought together scholars from around the world to discuss and critically analyze the issues and problems associated with Subjective Probability Measurement SPM or the more generic research area called self assessment Recent advances in computer technology expert systems interactive video disks and hypermedia along with the developing sophistication of self assessment scoring systems based on SPM made this conference particularly important and timely The book is divided into three main parts The input item banking and hypermedia The process subjective probabilities The output teaching and learning feedbacks In summary although SPM is a difficult theoretical concept for most educators to comprehend the sophisticated nature of modern computer systems coupled with comprehensive formative and summative evaluation and self assessment systems make SPM transparent to the user

Intelligent Learning Environments and Knowledge Acquisition in Physics Andree Tiberghien, Heinz Mandl, 2012-12-06 The NATO workshop Knowledge acquisition in the domain of physics and intelligent learning environments was held in Lyon France July 8 12 1990 A total of 31 researchers from Europe France Germany Greece Italy Portugal and the U K the U S A and Japan worked together This proceedings volume contains most of the contributions to the workshop The papers show clearly the main directions of research in intelligent learning environments They display a variety of points of view depending on the researcher's own background even when a single domain of teaching namely physics is considered We acknowledge the assistance of Michael Baker who was responsible for

reviewing the English of the contributions February 1992 Andree Tiberghien Heinz Mandl Table of Contents Introduction 1 1 Teaching Situations and Physics Knowledge Introductory University Courses and Open Environment Approaches The Computer as a Multi role Mediator in Teaching Learning Physics 5 E Balzano P Guidoni M Moretti E Sassi G Squeglia Practical Work Aid Knowledge Representation in a Model Based AI System 21 J Courtois Simultaneous Processing of Different Problem Aspects in Expert Problem Solving An Analysis in the Domain of Physics on the Basis of Formal Theories of Commonsense Knowledge 35 A Hron Modelis An Artificial Intelligence System Which Models Thermodynamics Textbook Problems 47 G Tisseau 2 Different Approaches to Student Modelling Steps Towards the Formalisation of a Psychologic of Cognitive Tools for Learning Piet A.M. Kommers, David H. Jonassen, J. Terry Mayes, 2012-12-06 Motion 65 J Bliss J Hypermedia technology needs a creative approach from the outset in the design of software to facilitate human thinking and learning This book opens a discussion of the potential of hypermedia and related approaches to provide open exploratory learning environments The papers in the book are based on contributions to a NATO Advanced Research Workshop held in July1990 and are grouped into six sections Semantic networking as cognitive tools Expert systems as cognitive tools Hypertext as cognitive tools Collaborative communication tools Microworlds context dependent cognitive tools Implementing cognitive tools The book will be valuable for those who design implement and evaluate learning programs and who seek to escape from rigid tactics like programmed instruction and behavioristic approaches The book presents principles for exploratory systems that go beyond existing metaphors of instruction and provokes the reader to think in a new way about the cognitive level of human computer interaction **Sensory Robotics for the Handling of Limp Materials** Paul M. Taylor, 2012-12-06 Limp materials are used in many economically impo tant industries such as garment manufacture shoe manufacture aerospace composites and automobiles seats and trim The use of sensors is essential for reliable robotic handling of these materials which are often based on naturally occurring substances such as cotton and leather The materials are limp and have non homogeneous mechanical properties which are often impossible to predict accurately The applications are very demanding for vision and tactile sensing and signal processing adaptive control systems planning and systems integration This book comprises the collection of papers presented at the NATO Advanced Research Workshop on Sensory Robotics for the Handling of Limp Materials held in October 1988 at II Ciocco Tuscany Italy The aim of the workshop was to examine the state of the art and determine what research is needed to provide the theoretical and technological tools for the successful application of sensory robotics to the handling of limp materials. The meeting also acted as the first ever forum for the interchange of knowledge between applications driven researchers and those researching into the provision of fundamental tools The participants were drawn from academia 20 industry 5 and other non university research organisations **Designing Hypermedia for Learning** David H. Jonassen, Heinz Mandl, 2012-12-06 This most unusual book results from the NATO Advanced Research Work shop Designing Hypertext Hypermedia for Learning held in Rottenburg am Neckar

FRO from July 3 8 1989 The idea for the workshop resulted from the burgeoning interest in hypertext combined with the frustrating lack of literature on leaming applications for hypertext There was little evidence in 1988 that hypertext could successfully support learning out comes A few projects were investigating hypertext for learning but few conclusions were available and little if any advice on how to design hyper text for learning applications was available Could hypertext support learning objectives What mental processing requirements are unique to learning outcomes How would the processing requirements of learning outcomes interact with unique user processing requirements of browsing and constructing hypertext Should hypertext information bases be restructured to accommodate learning outcomes Should the user interface be manipulated in order to support the task functionality of learning outcomes Does the hypertext structure reflect the intellectual requirements of learning outcomes What kinds of learning oriented hypertext systems were being developed and what kinds of assumptions were these systems making These and other questions demonstrated the need for this workshop. The workshop included presentations hardware demonstrations sharing and browsing of hypertexts and much discussion about all of the above These were the experiences that you the reader of this book unfortunately did not experience

Multiple Criteria Decision Making and Risk Analysis Using Microcomputers Birsen Karpak, Stanley Zionts, 2013-06-29 Roughly nine years ago the two editors met for the first time in Amsterdam the Netherlands at the EURO III meeting organized by the Association of European Operational Research Societies there As a result of our initial meeting the two of us planned and carried out a number of activities in the multiple criteria decision making area much of it supported by the North Atlantic Treaty Organization NATO The latest of these activities was a NATO Advanced Study Institute ASI on multiple criteria decision making and risk analysis using microcomputers. The institute was held in Tarabya Istanbul TURKEY on June 28 July 8 1987 We received over 100 applications from professors and a few graduate students in 13 countries Roughly half of them were able to participate The ASI was a great success Substantial knowledge transfer and learning took place In addition to the planned presentations we had several panels and round table discussions Though we had planned these in advance we implemented them to fit the occasion and also organized a few special sessions on site to respond to participants interests Sensor-Based Robots: Algorithms and Architectures C.S.George Lee, 2012-12-06 Most industrial robots today have little or no sensory capability Feedback is limited to information about joint positions combined with a few interlock and timing signals These robots can function only in an environment where the objects to be manipulated are precisely located in the proper position for the robot to grasp i e in a structured environment For many present industrial applications this level of performance has been adequate With the increasing demand for high performance sensor based robot manipulators in assembly tasks meeting this demand and challenge can only be achieved through the consideration of 1 efficient acquisition and processing of intemaVextemal sensory information 2 utilization and integration of sensory information from various sensors tactile force and vision to acquire knowledge in a changing

environment 3 exploitation of inherent robotic parallel algorithms and efficient VLSI architectures for robotic computations and finally 4 system integration into a working and functioning robotic system This is the intent of the Workshop on Sensor Based Robots Algorithms and Architectures to study the fundamental research issues and problems associated with sensor based robot manipulators and to propose approaches and solutions from various viewpoints in improving present day robot manipula tors in the areas of sensor fusion and integration sensory information processing and parallel algorithms and architectures for robotic computations Mapping and Spatial Modelling for Navigation Louis F. Pau, 2012-12-06 The successful implementation of applications in spatial reasoning requires paying attention to the representation of spatial data In particular an integrated and uniform treatment of different spatial features is necessary in order to enable the reasoning to proceed quickly Currently the most prevalent features are points rectangles lines regions surfaces and volumes As an example of a reasoning task consider a query of the form find all cities with population in excess of 5 000 in wheat growing regions within 10 miles of the Mississippi River Note that this query is quite complex It requires processing a line map for the river creating a corridor or buffer to find the area within 10 miles of the river a region map for the wheat and a point map for the cities Spatial reasoning is eased by spatially sorting the data i e a spatial index In this paper we show how hierarchical data structures can be used to facilitate this process They are based on the principle of recursive decomposition similar to divide and conquer methods In essence they are used primarily as devices to sort data of more than one dimension and different spatial types The term quadtree is often used to describe this class of data structures In this paper we focus on recent developments in the use of quadtree methods We concentrate primarily on region data For a more extensive treatment of this subject see SameS4a SameSSa SameSSb SameSSc SameSga SameSgbj **Learning from Computers:** Mathematics Education and Technology Christine Keitel-Kreidt, Kenneth Ruthven, 2012-12-06 The NATO Advanced Research Workshop on Mathematics Education and Technology was held in Villard de Lans France between May 6 and 11 1993 Organised on the initiative of the BaCoMET Basic Components of Mathematics Education for Teachers group Christiansen Howson and Otte 1986 Bishop Mellin Olsen and van Dormolen 1991 the workshop formed part of a larger NATO programme on Advanced Educational Technology Some workshop members had already participated in earlier events in this series and were able to contribute insights from them similarly some members were to take part in later events The problematic for the workshop drew attention to important speculative developments in the applications of advanced information technology in mathematics education over the last decade notably intelligent tutoring geometric construction symbolic algebra and statistical analysis Over the same period more elementary forms of information technology had started to have a significant influence on teaching approaches and curriculum content notably arithmetic and graphic calculators standard computer tools such as spreadsheets and databases and computer assisted learning packages and computer microworlds specially designed for educational purposes **Sensors and Sensory Systems for Advanced Robots** Paolo

Dario, Centro E. Piaggio, 2012-12-06 This volume contains papers presented at the NATO Advanced Research Workshop ARW on Sensors and Sensory Systems for Advanced Robots which was held in Maratea Italy during the week Apri I 28 May 3 1986 Participants in the ARW who came from eleven NATO and two non NATO countries represented an international I assortment of d i st i ngu i shed research centers in industry government and academia Purpose of the Workshop was to rev i ew the state of the art of sensing for advanced robots to discuss basic concepts and new ideas on the use of sensors for robot control and to provide recommendations for future research in this area There IS an almost unanimous consensus among invest i gators in the fie I d of robot i cs that the add i t i on of sensory capabi I ities represents the natural evolution of present industrial robots as wei I as the necessary premise to the development of advanced robots for nonindustrial app I i cat ions However a number of conceptua I and techn i ca I problems sti I I challenge the practical implementation and widespread application of sensor based robot control techn i gues Cruc i a I among those prob I ems is the ava i lab iii ty of adequate sensors Mathematical Models for Decision Support Harvey J. Greenberg, Gautam Mitra, Freerk A. Lootsma, Marcel J. Rijckaert, Hans J. Zimmermann, 2012-12-06 It is quite an onerous task to edit the proceedings of a two week long institute with learned contributors from many parts of the world All the same the editorial team has found the process of refereeing and reviewing the contributions worthwhile and completing the volume has proven to be a satisfying task In setting up the institute we had considered models and methods taken from a number of different disciplines As a result the whole institute preparing for it attending it and editing the proceedings proved to be an intense learning experience for us Here I speak on behalf of the committee and the editorial team By the time the institute took place the papers were delivered and the delegates exchanged their views the structure of the topics covered and their relative positioning appeared in a different light In editing the volume I felt compelled to introduce a new structure in grouping the papers The contents of this volume are organised in eight main sections set out below 1 Abstracts 2 Review Paper 3 Models with Multiple Criteria and Single or Multiple Decision Makers 4 Use of Optimisation Models as Decision Support Tools 5 Role of Information Systems in Decision Making Database and Model Management Issues 6 Methods of Artificial Intelligence in Decision Making Intelligent Knowledge Based Systems 7 Representation of Uncertainty in Mathematical Models and Knowledge Based Systems 8 Mathematical Basis for Constructing Models and Model Validation Hypermedia Courseware: Structures of Communication and Intelligent Help Armando Oliveira, 2012-12-06 This book is based on the NATO Advanced Research Workshop on Structures of Com munication and Intelligent Help for Hypermedia Courseware which was held at Espinho Portugal April 19 24 1990 The texts included here should not be regarded as untouched proceedings of this meeting but as the result of the reflections which took place there and which led the authors to revise their texts in that light The Espinho ARW was itself to some extent the continuation of the ARW on Designing Hypermedia Hypertext for Learning held in Germany in 1989 D H Jonassen H Mandl eds Designing Hypermedia for Learning NATO ASI

Series F Vol 67 Springer 1990 At that meeting an essential conclusion became apparent the importance and interest of hyper media products as potential pedagogical tools It was then already predictable that the enormous evolution of hypermedia would lead to its association with multimedia technologies namely for the production of courseware Parallel to the improvement of the didactic potential and quality which results from this association it nevertheless brought along a natural array of difficulties some old some new in the con ception and use of hypermedia products Today there is agreement that one of the most promising technological advances for education is represented by the use of text sound and images based on nonlinear techniques of information handling and searching of hypermedia architectures The problem of hypermedia is fundamentally one of communication this leads to an attempt at defining a language for hypermedia Mathematical Problem Solving and New Information Technologies Joao P. Ponte, Joao F. Matos, Jose M. Matos, Domingos Fernandes, 2013-06-29 A strong and fluent competency in mathematics is a necessary condition for scientific technological and economic progress However it is widely recognized that problem solving reasoning and thinking processes are critical areas in which students performance lags far behind what should be expected and desired Mathematics is indeed an important subject but is also important to be able to use it in extra mathematical contexts Thinking strictly in terms of mathematics or thinking in terms of its relations with the real world involve guite different processes and issues This book includes the revised papers presented at the NATO ARW Information Technology and Mathematical Problem Solving Research held in April 1991 in Viana do Castelo Portugal which focused on the implications of computerized learning environments and cognitive psychology research for these mathematical activities In recent years several committees professional associations and distinguished individuals throughout the world have put forward proposals to renew mathematics curricula all emphasizing the importance of problem solving In order to be successful these reforming intentions require a theory driven research base But mathematics problem solving may be considered a chaotic field in which progress has been guite slow Progress In Image Analysis And Processing Ii - Proceedings Of The 6th International Conference Virginio Cantoni, Stefano Levialdi, M. Ferretti, R. Negrini, R. Stefanelli, 1992-06-08 This book presents reports by well known experts on the most recent research results in image coding analysis and understanding and promising applications for solving real problems in manufacturing remote sensing and biomedicine The topics covered include shape analysis and computer vision pattern recognition methods and applications parallel computer architectures for image processing and analysis human perception and use of artificial intelligence techniques for image understanding languages for image abstraction processing and retrieval vision modules and neural computation Signal Processing and Pattern Recognition in Nondestructive Evaluation of Materials C.H. Chen, 2012-12-06 The NATO Advanced Research Workshop on Signal Processing and Pattern Recognition in Nondestructive Evaluation NOE of Materials was held August 19 22 1987 at the Manoir St Castin Lac Beauport Quebec Canada Modern signal processing pattern recognition and

artificial intelligence have been playing an increasingly important role in improving nondestructive evaluation and testing techniques. The cross fertilization of the two major areas can lead to major advances in NOE as well as presenting a new research area in signal processing. With this in mind the Workshop provided a good review of progress and comparison of potential techniques as well as constructive discussions and suggestions for effective use of modern signal processing to improve flaw detection classification and prediction as well as material characterization. This Proceedings volume includes most presentations given at the Workshop This publication like the meeting itself is unique in the sense that it provides extensive interactions among the interrelated areas of NOE. The book starts with research advances on inverse problems and then covers different aspects of digital waveform processing in NOE and eddy current signal analysis. These are followed by four papers of pattern recognition and AI in NOE and five papers of image processing and reconstruction in NOE. The last two papers deal with parameter estimation problems. Though the list of papers is not extensive as the field of NOE signal processing is very new the book has an excellent collection of both tutorial and research papers in this exciting new field.

Learning Electricity and Electronics with Advanced Educational Technology Michel Caillot, 1993-11-03 This volume is based on a NATO Advanced Research Workshop in the Special Programme on Advanced Educational Technology The objective of the workshop was to bring together researchers producing software in the field of electricity education and more generally in physics education and researchers involved in the connection between cognitive science and the learning of a well defined domain such as electricity The book is divided into five main parts New approaches to teaching electricity research on the teaching of electricity has shown that traditional presentations should be guestioned Analogies and models in electricity teaching experiments based on different models of electricity are presented Contextualized electricity a new field of research studies how adults who work with electricity and electronic devices represent electric phenomena and concepts Using computers in electricity teaching studies show how computers can be used for assessing electricity knowledge and student models of electricity Design of learning environments here interactive learning environments some of them specially designed for practical work in electronics are presented Speech Recognition and Coding Antonio J. Rubio Ayuso, Juan M. Lopez Soler, 2012-12-06 Based on a NATO Advanced Study Institute held in 1993 this book addresses recent advances in automatic speech recognition and speech coding The book contains contributions by many of the most outstanding researchers from the best laboratories worldwide in the field The contributions have been grouped into five parts on acoustic modeling language modeling speech processing analysis and synthesis speech coding and vector quantization and neural nets For each of these topics some of the best known researchers were invited to give a lecture In addition to these lectures the topics were complemented with discussions and presentations of the work of those attending Altogether the reader is given a wide perspective on recent advances in the field and will be able to see the trends for future work Automating Instructional Design, Development, and Delivery Robert D. Tennyson, 2012-12-06 This workshop was organized and

presented by an international group of scholars interested in the advancement of automating instructional design Although the principal leader for this effort was myself each of the committee members devoted equally in time and effort in the total preparation and conducting of the workshop Members of the organizing committee included Dr Klaus Breuer from disce and the University of Paderbom Germany Dr Begofia Gros from the University of Barcelona and Dr Daniel Muraida and Dr Michael Spector from the Armstrong Laboratory USA Dr Gros participated as the co director of the workshop and was directly responsible for the preparation and operation of the workshop in Sitges Spain The workshop was held in Sitges a short distance from Barcelona March 23 27 1992 Because of preparations at that time for the 1992 summer Olympic Games in Barcelona the workshop was moved to a more convenient location The theme of the workshop included three main topics planning production and implementation Dr Peter Goodyear from the Lancaster University England presented the invited keynote address During the four day workshop 14 papers were presented and discussed Following each of the three topic areas Drs Gros and Breuer led discussions critiquing the ideas presented Technology-Based Learning Environments Stella Vosniadou, Erik de Corte, Heinz Mandl, 2012-12-06 The present volume contains a large number of the papers contributed to the Advanced Study Institute on the Psychological and Educational Foundations of Technology Based Learning Environments which took place in Crete in the summer of 1992 The purpose of the Advanced Study Institute was to bring together a small number of senior lecturers and advanced graduate students to investigate and discuss the psychological and educational foundations of technology based learning environments and to draw the implications of recent research findings in the area of cognitive science for the development of educational technology As is apparent from the diverse nature of the contributions included in this volume the participants at the ASI came from different backgrounds and looked at the construction of technology based learning environments from rather diverse points of view Despite the diversity a surprising degree of overlap and agreement was achieved Most of the contributors agreed that the kinds of technology supported learning environments we should construct should stimulate students to be active and constructive in their knowledge building efforts embed learning in meaningful and authentic activities encourage collaboration and social interaction and take into consideration students prior knowledge and beliefs

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