

Michael Beetz

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Plan-Based Control of Robotic Agents

Improving the Capabilities of Autonomous Robots



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Planbased Control Of Robotic Agents Improving The Capabilities Of Autonomous Robots

Bruno Siciliano, Oussama Khatib



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environment for more than a year allowing people to issue navigation commands and monitor their execution via the Internet In 1998 Minerva 7 acted for 13 days as a museum tourguide in the Smithsonian Museum and led several thousand people through an exhibition These autonomous robots have in common that they rely on plan based control in order to achieve better problem solving competence In the plan based approach robots generate control actions by maintaining and executing a plan that is effective and has a high expected utility with respect to the robots current goals and beliefs Plans are robot control programs that a robot can not only execute but also reason about and manipulate 4 Thus a plan based controller is able to manage and adapt the robot's intended course of action the plan while executing it and can thereby better achieve complex and changing tasks

The British National Bibliography Arthur James Wells, 2003

Intelligent Autonomous Systems 7 Maria Gini, 2002 The goal of the Seventh International Conference on Intelligent Autonomous Systems IAS 7 was to exchange and stimulate research ideas that make future robots and systems more intelligent and autonomous This volume of proceedings contains 71 technical papers by authors from 15 countries

A Hybrid Deliberative Layer for Robotic Agents Ronny Hartanto, 2011-07-18 The Hybrid Deliberative Layer HDL solves the problem that an intelligent agent faces in dealing with a large amount of information which may or may not be useful in generating a plan to achieve a goal The information that an agent may need is acquired and stored in the DL model Thus the HDL is used as the main knowledge base system for the agent In this work a novel approach which amalgamates Description Logic DL reasoning with Hierarchical Task Network HTN planning is introduced An analysis of the performance of the approach has been conducted and the results show that this approach yields significantly smaller planning problem descriptions than those generated by current representations in HTN planning

KI 2007: Advances in Artificial Intelligence Joachim Hertzberg, Michael Beetz, Roman Englert, 2007-08-26 This book constitutes the thoroughly refereed proceedings of the 30th Annual German Conference on Artificial Intelligence KI 2007 held in Osnabrück Germany September 2007 The papers are organized in topical sections on cognition and emotion semantic Web analogy natural language reasoning ontologies spatio temporal reasoning machine learning spatial reasoning robot learning classical AI problems and agents

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Dragone, Juan Ye, Carsten Röcker, Gregory O'Hare, 2013-12-14 This book constitutes the refereed proceedings of the workshops co located with the 4th International Joint Conference on Ambient Intelligence AmI 2013 held in Dublin Ireland in December 2013 The 33 revised full papers presented were carefully reviewed and selected from numerous submissions to the following workshops 5th International Workshop on Intelligent Environments Supporting Healthcare and Well being WISHWell 13 3d International workshop on Pervasive and Context Aware Middleware PerCAM 13 2nd International Workshop on Adaptive Robotic Ecologies ARE 13 International Workshop on Aesthetic Intelligence AxI 13 First International Workshop on Uncertainty in Ambient Intelligence UAmI13 The papers are organized in topical sections on intelligent environments supporting healthcare and well being adaptive robotic ecologies uncertainty in ambient intelligence aesthetic intelligence pervasive and context aware middleware **Books in Print Supplement**, 2002 Exploring Cybernetics

Sabina Jeschke, Robert Schmitt, Alicia Dröge, 2015-12-04 Die Beiträge des Sammelbandes befassen sich mit zentralen Themen der Kybernetik Was ist Kybernetik überhaupt Wie können wir sie nutzen und wo können wir sie einsetzen Die Autoren zeigen dass unser Digitalzeitalter von umfassenden technologischen Neuerungen komplexer Vernetzung und schnellen Innovationszyklen gekennzeichnet ist die sich klassischen Beschreibungsmodellen und traditionellen Regelungsmechanismen entziehen Immer vielfältiger interagierende Strukturen erfordern neue Methoden um diese Komplexität zu beschreiben und zu gestalten Hochkarätige WissenschaftlerInnen verschiedenster Fachgebiete erläutern die Kybernetik aus Sicht ihrer jeweiligen Disziplin AI*IA 2007: Artificial Intelligence and Human-Oriented Computing Roberto Basili, Maria Teresa Pazienza, 2007-08-26 This book constitutes the refereed proceedings of the 10th Congress of the Italian Association for Artificial Intelligence AI IA 2007 Coverage includes knowledge representation and reasoning multiagent systems distributed AI knowledge engineering ontologies and the semantic Web machine learning natural language processing information retrieval and extraction AI and robotics AI and expressive media and intelligent access to multimedia information

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