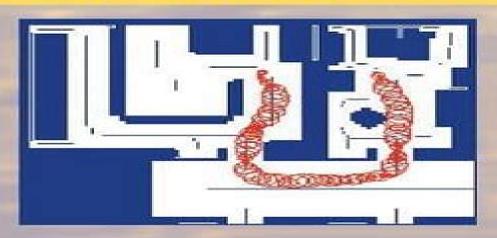
# Plan-Based Control of Robotic Agents

Improving the Capabilities of Autonomous Robots





**Bruno Siciliano, Oussama Khatib** 

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vironment for more than a year allowing people to issue navigation commands and monitor their execution via the Internet In 1998 Minerva 7 acted for 13 days as a museum tourguide in the Smithsonian Museum and led several thousand people through an exhibition These autonomous robots have in common that they rely on plan based c trol in order to achieve better problem solving competence In the plan based approach robots generate control actions by maintaining and executing a plan that is e ective and has a high expected utility with respect to the robots c rent goals and beliefs Plans are robot control programs that a robot can not only execute but also reason about and manipulate 4 Thus a plan based c troller is able to manage and adapt the robot's intended course of action the plan while executing it and can thereby better achieve complex **The British National Bibliography** Arthur James Wells, 2003 **Intelligent Autonomous** and changing tasks Systems 7 Maria Gini, 2002 The goal of the Seventh International Conference on Intelligent Autonomous Systems IAS 7 was to exchange and stimulate research ideas that make future robots and systems more intelligent and autonomous This volume of proceedings contains 71 technical papers by authors from 15 countries A Hybrid Deliberative Layer for Robotic **Agents** Ronny Hartanto, 2011-07-18 The Hybrid Deliberative Layer HDL solves the problem that an intelligent agent faces in dealing with a large amount of information which may or may not be useful in generating a plan to achieve a goal The information that an agent may need is acquired and stored in the DL model Thus the HDL is used as the main knowledge base system for the agent In this work a novel approach which amalgamates Description Logic DL reasoning with Hierarchical Task Network HTN planning is introduced An analysis of the performance of the approach has been conducted and the results show that this approach yields significantly smaller planning problem descriptions than those generated by current representations in HTN planning KI 2007: Advances in Artificial Intelligence Joachim Hertzberg, Michael Beetz, Roman Englert, 2007-08-26 This book constitutes the thoroughly refereed proceedings of the 30th Annual German Conference on Artificial Intelligence KI 2007 held in Osnabr ck Germany September 2007 The papers are organized in topical sections on cognition and emotion semantic Web analogy natural language reasoning ontologies spatio temporal reasoning machine learning spatial reasoning robot learning classical AI problems and agents KI 2003: Advances in Artificial Intelligence Andreas Günter, Rudolf Kruse, Bernd Neumann, 2003-09-09 This book constitutes the refereed proceedings of the 26th Annual German Conference on Artificial Intelligence KI 2003 held in Hamburg Germany in September 2003 The 42 revised full papers presented together with 5 invited papers were carefully reviewed and selected from 90 submissions from 22 countries The papers are organized in topical sections on logics and ontologies cognitive modeling reasoning methods machine learning neural networks reasoning under uncertainty planning and constraints spatial modeling user modeling and KI 2003: Advances in Artificial Intelligence Andreas Gu nter, Rudolf Kruse, Bernd Neumann, 2003-09-09 agent technology This book constitutes the refereed proceedings of the 26th Annual German Conference on Artificial Intelligence KI 2003 held in Hamburg Germany in September 2003 The 42 revised full papers presented together with 5 invited papers were carefully

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Dragone, Juan Ye, Carsten Röcker, Gregory O'Hare, 2013-12-14 This book constitutes the refereed proceedings of the workshops co located with the 4th International Joint Conference on Ambient Intelligence AmI 2013 held in Dublin Ireland in December 2013 The 33 revised full papers presented were carefully reviewed and selected from numerous submissions to the following workshops 5th International Workshop on Intelligent Environments Supporting Healthcare and Well being WISHWell 13 3d International workshop on Pervasive and Context Aware Middleware PerCAM 13 2nd International Workshop on Adaptive Robotic Ecologies ARE 13 International Workshop on Aesthetic Intelligence AxI 13 First International Workshop on Uncertainty in Ambient Intelligence UAmI13 The papers are organized in topical sections on intelligent environments supporting healthcare and well being adaptive robotic ecologies uncertainty in ambient intelligence aesthetic intelligence pervasive and context aware middleware Books in Print Supplement ,2002 **Exploring Cybernetics** Sabina Jeschke, Robert Schmitt, Alicia Dröge, 2015-12-04 Die Beitr ge des Sammelbandes befassen sich mit zentralen Themen der Kybernetik Was ist Kybernetik berhaupt Wie k nnen wir sie nutzen und wo k nnen wir sie einsetzen Die Autoren zeigen dass unser Digitalzeitalter von umfassenden technologischen Neuerungen komplexer Vernetzung und schnellen Innovationszyklen gekennzeichnet ist die sich klassischen Beschreibungsmodellen und traditionellen Regelungsmechanismen entziehen Immer vielf ltiger interagierende Strukturen erfordern neue Methoden um diese Komplexit t zu beschreiben und zu gestalten Hochkar tige WissenschaftlerInnen verschiedenster Fachgebiete erl utern die Kybernetik aus Sicht ihrer jeweiligen Disziplin AI\*IA 2007: Artificial Intelligence and Human-Oriented Computing Roberto Basili, Maria Teresa Pazienza, 2007-08-26 This book constitutes the refereed proceedings of the 10th Congress of the Italian Association for Artificial Intelligence AI IA 2007 Coverage includes knowledge representation and reasoning multiagent systems distributed AI knowledge engineering ontologies and the semantic Web machine learning natural language processing information retrieval and extraction AI and robotics AI and expressive media and intelligent access to multimedia information

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