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## Book Reviews

**Process Dynamics and Control; Vol. 1: Analysis of Dynamic Systems; Vol. 2: Control System Synthesis**—J. M. Douglas (Englewood Cliffs, NJ: Prentice-Hall, 1972, Vol. 1, 367 pp.; Vol. 2, 447 pp.). *Reviewed by D. E. Cormack, Department of Chemical Engineering and Applied Chemistry, University of Toronto, Toronto, ON, Canada M5S 1A4.*

The book is intended as a survey of the basic concepts in modern control theory. The material is presented in two volumes: the first volume concentrates on dynamic system analysis; the second volume systematically examines the strategy of control system design. The material in Volume 1 would be suitable for a junior level undergraduate course, while the combined volumes would provide an excellent basis for a senior level or introductory graduate course. The text could also serve to familiarize control engineers in industry with some of the new approaches to process control.

The control problem is introduced in Volume 1 with a heuristic discussion of system dynamics and control as it applies to the automobile. The discussion proceeds to the optimum steady-state design problem with its inherent shortcomings. In Chapter 3, *system dynamics* are considered. The fundamental principles of mass, energy, and momentum balances are used to derive dynamic models for a progression of lumped and distributed linear and nonlinear chemical engineering systems which form the basis of the system analysis and control systems synthesis in the remainder of the text. The simplification of nonlinear systems by linearization and the treatment of high-order systems by matrix methods are discussed in some detail.

In Chapter 4 the Laplace transform is used to generate dynamic solutions to the lumped-parameter systems derived previously for various time-dependent inputs. The discussion concentrates on the time-domain analysis, but some discussion of the frequency response is also presented.

Chapter 5 outlines some techniques for the analysis of distributed parameter systems. Once again, the Laplace transform is used extensively. The difficulty encountered in inverting the complex transforms motivates a discussion of techniques to develop approximate finite-order transfer functions from either the dynamic model or from actual plant data.

Chapter 6 deals with the analysis of nonlinear systems by linearization about the steady state. The need to assess the domain of validity of the linearization technique by examining the higher order terms in a perturbation expansion is emphasized.

The second volume of the text considers the ways in which the dynamic characteristics of first-, second-, and third-order plants can be altered to advantage. In Chapter 7, the discussion is concerned with the application of Bode diagrams, the root-locus method, and the empirical approaches of Ziegler-Nichols and Cohen and Coon to the design of classical proportional-integral-differential controllers for single input-output systems. Existing work on the feedback control of distributed parameter processes is reviewed briefly.

In Chapter 8, the classical concepts are generalized, to the extent possible, to multivariable plants. The design of noninteracting control systems via Bristol's technique and via modal analysis is presented. Concepts of observability and controllability are also discussed. The inability to handle adequately the multivariable systems by classical servomechanism theory motivates the discussion of optimal control theory in Chapter 9. Pontryagin's minimum principle is derived in its most general form for lumped and distributed parameter systems. In addition to the usual performance indices of minimum cost, minimum time, and quadratic integral, the author considers those performance criteria which lead to the classical P-I-D control laws. It is implied that this would be a useful way to approach multivariable plants.

Finally, Chapter 10 deals with deliberate unsteady-state operation of chemical systems to achieve superior performance. The author closes with the suggestion that a bold and imaginative approach to process control can have significant advantages.

Each chapter ends with a large selection of problems (many of which reflect the obvious good humor of the author) with which the reader can develop and test his skills.

The book is well written and, overall, the treatment of the material is original. The approach is of a fundamental and rigorous nature, but at the same time, the level of presentation requires only a first course in ordinary differential equations in preparation. In addition, some prior exposure to matrix theory and partial differential equations would be helpful.

**Introduction to the Theory of Fuzzy Subsets—Vol. 1: Fundamental Theoretical Elements**—A. Kaufmann (New York: Academic, 1975, 432 pp.). *Reviewed by A. P. Bonneri, Metro-Sabena, Brussels, Belgium.*

This book is the English translation of the French original published three years ago and constitutes the first volume of a collection of five. The first volume to be reviewed surveys mathematical essentials (especially from an algebraic and structural point of view) of fuzzy sets. The remaining four volumes (of which two are already published in French) are devoted to applications.

Chapter 1 is an introduction to a number of concepts. Fuzzy subsets (the prefix "sub" is henceforth omitted) are defined as a mapping of the elements of a universe set into the closed interval  $[0,1]$ . This mapping, called the membership function, is a generalization of the characteristic function. The operations/concepts of complement, inclusion, union, intersection, algebraic product and sum as well as Hamming and Euclidean distances are extended to fuzzy sets. The concepts of the nonfuzzy set nearest to a given fuzzy set and nonfuzzy set of given level are introduced. It is shown how a fuzzy set can be

# Process Dynamics And Control Volume 1 Analysis Of Dynamic Systems

**James Merrill Douglas**



## **Process Dynamics And Control Volume 1 Analysis Of Dynamic Systems:**

Process Dynamics and Control: Analysis of dynamic systems James Merrill Douglas, 1972      **Elementary Process Dynamics and Control** A. Johnson, 1976      **Process Dynamics and Control: Control system synthesis** James Merrill Douglas, 1972      Artificial Intelligence in Information and Communication Technologies, Healthcare and Education Parikshit N Mahalle, Rajendra S Talware, Ganesh C Patil, Sachin R Sakhare, Yogesh H Dandawate, Pravin R Futane, 2022-12-27 Artificial Intelligence in Information and Communication Technologies Healthcare and Education A Roadmap Ahead is designed as a reference text and discusses inter dependability communication and effective control for the betterment of services through artificial intelligence AI as well as the challenges and path ahead for AI in computing and control across different domains of business and human life The book accommodates technologies and application domains including backbone hardware systems and methods for deployment which help incorporating intelligence through different supervised and probabilistic learning approaches Features The book attempts to establish a connection between hardware software technologies and algorithmic intelligence for data analysis and decision support in domains such as healthcare education and other aspects of business and mobility It presents various recent applications of artificial intelligence in information and communication technologies such as search and optimization methods machine learning data representation and ontologies and multi agent systems The book provides a collection of different case studies with experimentation results than mere theoretical and generalized approaches Covers most of the applications using the trending technologies like machine learning ML data science DS Internet of Things IoT and underlying information and communication technologies The book is aimed primarily at advanced undergraduates and postgraduate students studying computer science computer applications and information technology Researchers and professionals will also find this book useful      **Catalog of Copyright Entries. Third Series** Library of Congress. Copyright Office, 1974      **Process Control** Jean-Pierre Corriou, 2017-08-17 This reference book can be read at different levels making it a powerful source of information It presents most of the aspects of control that can help anyone to have a synthetic view of control theory and possible applications especially concerning process engineering

*Technology for Large Space Systems: A Bibliography with Indexes (supplement 20)* United States. National Aeronautics and Space Administration. Scientific and Technical Information Division, 1989      **CONTROL SYSTEMS, ROBOTICS AND AUTOMATION - Volume I** Heinz Unbehauen, 2009-10-11 This Encyclopedia of Control Systems Robotics and Automation is a component of the global Encyclopedia of Life Support Systems EOLSS which is an integrated compendium of twenty one Encyclopedias This 22 volume set contains 240 chapters each of size 5000 30000 words with perspectives applications and extensive illustrations It is the only publication of its kind carrying state of the art knowledge in the fields of Control Systems Robotics and Automation and is aimed by virtue of the several applications at the following five major target audiences University and College Students Educators Professional Practitioners Research Personnel and Policy Analysts Managers and

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