Progress in Mathematics

Juan-Pablo Ortega Tudor S. Ratiu

# Momentum Maps and Hamiltonian Reduction

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# **Momentum Maps And Hamiltonian Reduction**

Jean-Louis Koszul, Yi Ming Zou

#### **Momentum Maps And Hamiltonian Reduction:**

Momentum Maps and Hamiltonian Reduction Juan-Pablo Ortega, Tudor S. Ratiu, 2013-04-17 The use of the symmetries of a physical system in the study of its dynamics has a long history that goes back to the founders of classical mechanics Symmetry based tech niques are often implemented by using the integrals 01 motion that one can sometimes associate to these symmetries The integrals of motion of a dynamical system are quan tities that are conserved along the flow of that system In classical mechanics symmetries are usually induced by point transformations that is they come exclusively from symmetries of the configuration space the intimate connection between integrals of motion and symmetries was formalized in this context by NOETHER 1918 This idea can be generalized to many symmetries of the entire phase space of a given system by associating to the Lie algebra action encoding the symmetry a function from the phase space to the dual of the Lie algebra This map whose level sets are preserved by the dynamics of any symmetrie system is referred to in modern terms as a momentum map of the symmetry a construction already present in the work of LIE 1890 Its remarkable properties were rediscovered by KOSTANT 1965 and SOURIAU 1966 1969 in the general case and by SMALE 1970 for the lifted action to the co tangent bundle of a configuration space For the his tory of the momentum map we refer to WEINSTEIN 1983b and MARSDEN AND RATIU 1999 11 2 Momentum Maps and Hamiltonian Reduction Juan Pablo Ortega, Tudor S. Hamiltonian Reduction by Stages Jerrold E. Marsden, Gerard Misiolek, Juan-Pablo Ortega, Matthew Ratiu,2014-01-15 Perlmutter, Tudor S. Ratiu, 2007-06-05 This volume provides a detailed account of the theory of symplectic reduction by stages along with numerous illustrations of the theory It gives special emphasis to group extensions including a detailed discussion of the Euclidean group the oscillator group the Bott Virasoro group and other groups of matrices The volume also provides ample background theory on symplectic reduction and cotangent bundle reduction **Noncommutative Geometry and Physics 2005** Ursula Carow-Watamura, 2007 Noncommutative geometry is a novel approach which is opening up new possibilities for geometry from a mathematical viewpoint It is also providing new tools for the investigation of quantum space time in physics Recent developments in string theory have supported the idea of quantum spaces and have strongly stimulated the research in this field This self contained volume contains survey lectures and research articles which address these issues and related topics The book is accessible to both researchers and graduate students beginning to study Similarity and Symmetry Methods Jean-François Ganghoffer, Ivaïlo Mladenov, 2014-07-19 The principle this subject aim of the book is to present a self contained modern account of similarity and symmetry methods which are important mathematical tools for both physicists engineers and applied mathematicians The idea is to provide a balanced presentation of the mathematical techniques and applications of symmetry methods in mathematics physics and engineering That is why it includes recent developments and many examples in finding systematically conservation laws local and nonlocal symmetries for ordinary and partial differential equations The role of continuous symmetries in classical and quantum field theories is

exposed at a technical level accessible even for non specialists. The importance of symmetries in continuum mechanics and mechanics of materials is highlighted through recent developments such as the construction of constitutive models for various materials combining Lie symmetries with experimental data As a whole this book is a unique collection of contributions from experts in the field including specialists in the mathematical treatment of symmetries researchers using symmetries from a fundamental applied or numerical viewpoint The book is a fascinating overview of symmetry methods aimed for graduate students in physics mathematics and engineering as well as researchers either willing to enter in the field or to capture recent developments and applications of symmetry methods in different scientific fields Formulations of Lagrangian and Hamiltonian Dynamics on Manifolds Taeyoung Lee, Melvin Leok, N. Harris McClamroch, 2017-08-14 This book provides an accessible introduction to the variational formulation of Lagrangian and Hamiltonian mechanics with a novel emphasis on global descriptions of the dynamics which is a significant conceptual departure from more traditional approaches based on the use of local coordinates on the configuration manifold In particular we introduce a general methodology for obtaining globally valid equations of motion on configuration manifolds that are Lie groups homogeneous spaces and embedded manifolds thereby avoiding the difficulties associated with coordinate singularities. The material is presented in an approachable fashion by considering concrete configuration manifolds of increasing complexity which then motivates and naturally leads to the more general formulation that follows Understanding of the material is enhanced by numerous in depth examples throughout the book culminating in non trivial applications involving multi body systems. This book is written for a general audience of mathematicians engineers and physicists with a basic knowledge of mechanics Some basic background in differential geometry is helpful but not essential as the relevant concepts are introduced in the book thereby making the material accessible to a broad audience and suitable for either self study or as the basis for a graduate course in applied mathematics engineering or physics Classical and Quantum Physics G. Marmo, David Martín de Diego, Miguel Muñoz Lecanda, 2019-10-26 This proceedings is based on the interdisciplinary workshop held in Madrid 5 9 March 2018 dedicated to Alberto Ibort on his 60th birthday Alberto has great and significantly contributed to many fields of mathematics and physics always with highly original and innovative ideas Most of Albertos s scientific activity has been motivated by geometric ideas concepts and tools that are deeply related to the framework of classical dynamics and quantum mechanics Let us mention some of the fields of expertise of Alberto Ibort Geometric Mechanics Constrained Systems Variational Principles Multisymplectic structures for field theories Super manifolds Inverse problem for Bosonic and Fermionic systems Quantum Groups Integrable systems BRST Symmetries Implicit differential equations Yang Mills Theories BiHamiltonian Systems Topology Change and Quantum Boundary Conditions Classical and Quantum Control Orthogonal Polynomials Quantum Field Theory and Noncommutative Spaces Classical and Quantum Tomography Quantum Mechanics on phase space Wigner Weyl formalism Lie Jordan Algebras Classical and Quantum

Quantum to Classical transition Contraction of Associative Algebras contact geometry among many others In each contribution one may find not only technical novelties but also completely new way of looking at the considered problems. Even an experienced reader reading Alberto's contributions on his field of expertise will find new perspectives on the considered topic. His enthusiasm is happily contagious for this reason he has had and still has very bright students wishing to elaborate their PhD thesis under his guidance. What is more impressive is the broad list of rather different topics on which he has contributed. **Topics in Differential Geometry** Peter W. Michor, 2008. This book treats the fundamentals of differential geometry manifolds flows. Lie groups and their actions invariant theory differential forms and de Rham cohomology bundles and connections. Riemann manifolds isometric actions and symplectic and Poisson geometry. It gives the careful reader working knowledge in a wide range of topics of modern coordinate free differential geometry in not too many pages. A prerequisite for using this book is a good knowledge of undergraduate analysis and linear algebra BOOK JACKET.

Probing The Meaning Of Quantum Mechanics: Physical, Philosophical, And Logical Perspectives Diederik Aerts, Sven Aerts, Christian De Ronde, 2014-03-06 This book provides a new original perspective on one of the most fascinating and important open questions in science What is quantum mechanics talking about Quantum theory is perhaps our best confirmed physical theory However in spite of its great empirical effectiveness and the subsequent technological developments that it gave rise to in the 20th century from the interpretation of the periodic table of elements to CD players holograms and quantum state teleportation it stands even today without a universally accepted interpretation. The novelty of the book comes from the multiple viewpoints and the original angles taken by a group of young researchers from Europe and South America who gathered for several years under the auspices of the Center Leo Apostel Each member of the group presented ideas concerning the interpretation of quantum mechanics We had discussions ranging from the philosophical underpinnings of local realism and holism information and decision theoretic approaches to quantum theory all the way to the many worlds interpretation Strikingly in much the same way as different and indeed incompatible observations are needed to fully describe the physical state of affairs in quantum mechanics the various interpretations of the theory also seem to shed viable but not necessarily compatible perspectives on different aspects of the same grand framework The discussions that followed were both technical and lively but perhaps their most remarkable quality was the absence of rigid points of view that unfortunately seems to paralyze so much of the discussion in this area This book is an expression which can be interesting not only to the specialists but also for the general public attempting to get a grasp on one of the still most fundamental questions of present physics Geometric Control of Mechanical Systems Francesco Bullo, Andrew D. Lewis, 2019-06-12 The primary emphasis of this book is the modeling analysis and control of mechanical systems The methods and results presented can be applied to a large class of mechanical control systems including applications in robotics autonomous vehicle control and multi body systems The book is unique in that it presents a unified rather than an

inclusive treatment of control theory for mechanical systems A distinctive feature of the presentation is its reliance on techniques from differential and Riemannian geometry The book contains extensive examples and exercises and will be suitable for a growing number of courses in this area It begins with the detailed mathematical background proceeding through innovative approaches to physical modeling analysis and design techniques Numerous examples illustrate the proposed methods and results while the many exercises test basic knowledge and introduce topics not covered in the main body of the text The audience of this book consists of two groups The first group is comprised of graduate students in engineering or mathematical sciences who wish to learn the basics of geometric mechanics nonlinear control theory and control theory for mechanical systems Readers will be able to immediately begin exploring the research literature on these subjects The second group consists of researchers in mechanics and control theory Nonlinear control theoreticians will find explicit links between concepts in geometric mechanics and nonlinear control theory Researchers in mechanics will find an overview of topics in control theory that have relevance to mechanics Differential Geometry of Singular Spaces and **Reduction of Symmetry** Jedrzej Śniatycki, 2013-06-13 A complete presentation of the theory of differential spaces with applications to the study of singularities in systems with symmetry New Spaces in Physics: Volume 2 Mathieu Anel, Gabriel Catren, 2021-04-01 After the development of manifolds and algebraic varieties in the previous century mathematicians and physicists have continued to advance concepts of space This book and its companion explore various new notions of space including both formal and conceptual points of view as presented by leading experts at the New Spaces in Mathematics and Physics workshop held at the Institut Henri Poincar in 2015 This volume covers a broad range of topics in mathematical physics including noncommutative geometry supergeometry derived symplectic geometry higher geometric quantization intuitionistic quantum logic problems with the continuum description of spacetime twistor theory loop quantum gravity and geometry in string theory It is addressed primarily to mathematical physicists and mathematicians but also to Introduction to Symplectic Geometry Jean-Louis Koszul, Yi Ming historians and philosophers of these disciplines Zou, 2019-04-15 This introductory book offers a unique and unified overview of symplectic geometry highlighting the differential properties of symplectic manifolds It consists of six chapters Some Algebra Basics Symplectic Manifolds Cotangent Bundles Symplectic G spaces Poisson Manifolds and A Graded Case concluding with a discussion of the differential properties of graded symplectic manifolds of dimensions 0 n It is a useful reference resource for students and researchers interested in geometry group theory analysis and differential equations This book is also inspiring in the emerging field of Geometric Science of Information in particular the chapter on Symplectic G spaces where Jean Louis Koszul develops Jean Marie Souriau s tools related to the non equivariant case of co adjoint action on Souriau s moment map through Souriau s Cocycle opening the door to Lie Group Machine Learning with Souriau Fisher metric Symplectic Geometry and Mathematical Physics P. Donato, 1991-12 This volume contains the proceedings of the conference Colloque de

Goometrie Symplectique et Physique Mathematique which was held in Aix en Provence France June 11 15 1990 in honor of Jean Marie Souriau The conference was one in the series of international meetings of the Seminaire Sud Rhodanien de Goometrie an organization of geometers and mathematical physicists at the Universities of Avignon Lyon Mar seille and Montpellier The scientific interests of Souriau one of the founders of geometric quantization range from classical mechanics symplectic geometry and quantization problems to general relativity and astrophysics. The themes of this conference cover only the first two of these four areas The subjects treated in this volume could be classified in the following way symplectic and Poisson geometry Arms Wilbour Bloch Ratiu Brylinski Kostant Cushman Sjamaar Dufour Lichnerowicz Medina Ouzilou classical mechanics Benenti Holm Marsden Marle particles and fields in physics Garcia Perez Munoz Masque Gotay Montgomery Ne eman Sternberg Sniatycki and quantization Blattner Huebschmann Karasev Rawnsley Roger Rosso Weinstein However these subjects are so interrelated that a classification by headings such as pure differential geometry applications of Lie groups constrained systems in physics etc would have produced a completely different clustering The list of authors is not quite identical to the list of speakers at the conference M Karasev was invited but unable to attend C Itzykson and M Vergne spoke on work which is represented here only by the title of Itzykson's talk Surfaces triangulees et integration matricielle and a summary of Vergne s talk **Geometric Mechanics - Part I: Dynamics And Symmetry** (2nd Edition) Darryl D Holm, 2011-07-13 See also GEOMETRIC MECHANICS Part II Rotating Translating and Rolling 2nd Edition This textbook introduces the tools and language of modern geometric mechanics to advanced undergraduates and beginning graduate students in mathematics physics and engineering It treats the fundamental problems of dynamical systems from the viewpoint of Lie group symmetry in variational principles The only prerequisites are linear algebra calculus and some familiarity with Hamilton's principle and canonical Poisson brackets in classical mechanics at the beginning undergraduate level The ideas and concepts of geometric mechanics are explained in the context of explicit examples Through these examples the student develops skills in performing computational manipulations starting from Fermat's principle working through the theory of differential forms on manifolds and transferring these ideas to the applications of reduction by symmetry to reveal Lie Poisson Hamiltonian formulations and momentum maps in physical applications The many Exercises and Worked Answers in the text enable the student to grasp the essential aspects of the subject In addition the modern language and application of differential forms is explained in the context of geometric mechanics so that the importance of Lie derivatives and their flows is clear All theorems are stated and proved explicitly The organisation of the first edition has been preserved in the second edition However the substance of the text has been rewritten throughout to improve the flow and to enrich the development of the material In particular the role of Noether's theorem about the implications of Lie group symmetries for conservation laws of dynamical systems has been emphasised throughout with many applications a **Geometric Mechanics** Darryl D Holm, 2008-04-14 This textbook introduces the tools and language of

modern geometric mechanics to advanced undergraduate and beginning graduate students in mathematics physics and engineering It treats the dynamics of rotating spinning and rolling rigid bodies from a geometric viewpoint by formulating their solutions as coadjoint motions generated by Lie groups The only prerequisites are linear algebra multivariable calculus and some familiarity with Euler Lagrange variational principles and canonical Poisson brackets in classical mechanics at the beginning undergraduate level Variational calculus on tangent spaces of Lie groups is explained in the context of familiar concrete examples Through these examples the student develops skills in performing computational manipulations starting from vectors and matrices working through the theory of guaternions to understand rotations and then transferring these skills to the computation of more abstract adjoint and coadjoint motions Lie Poisson Hamiltonian formulations momentum maps and finally dynamics with nonholonomic constraints The 120 Exercises and 55 Worked Answers help the student to grasp the essential aspects of the subject and to develop proficiency in using the powerful methods of geometric mechanics In addition all theorems are stated and proved explicitly The book s many examples and worked exercises make it ideal for both classroom use and self study Contents GalileoNewton Lagrange HamiltonQuaternionsQuaternionic ConjugacySpecial Orthogonal GroupThe Special Euclidean GroupGeometric Mechanics on SE 3 Heavy Top EquationsThe Euler Poincar TheoremLie Poisson Hamiltonian FormMomentum MapsRound Rolling Rigid Bodies Readership Advanced undergraduate and graduate students in mathematics physics and engineering researchers interested in learning the basic ideas in the fields non experts interested in geometric mechanics dynamics and symmetry Geometric Mechanics: Rotating, translating and rolling Darryl D. Holm, 2008 Introduces the tools and language of modern geometric mechanics to advanced undergraduate and beginning graduate students in mathematics physics and engineering This book treats the dynamics of rotating spinning and rolling rigid bodies from a geometric viewpoint by formulating their solutions as coadjoint motions generated by Lie groups The Restricted Three-Body Problem and Holomorphic Curves Urs Frauenfelder, Otto van Koert, 2018-08-29 The book serves as an introduction to holomorphic curves in symplectic manifolds focusing on the case of four dimensional symplectizations and symplectic cobordisms and their applications to celestial mechanics The authors study the restricted three body problem using recent techniques coming from the theory of pseudo holomorphic curves The book starts with an introduction to relevant topics in symplectic topology and Hamiltonian dynamics before introducing some well known systems from celestial mechanics such as the Kepler problem and the restricted three body problem After an overview of different regularizations of these systems the book continues with a discussion of periodic orbits and global surfaces of section for these and more general systems. The second half of the book is primarily dedicated to developing the theory of holomorphic curves specifically the theory of fast finite energy planes to elucidate the proofs of the existence results for global surfaces of section stated earlier The book closes with a chapter summarizing the results of some numerical experiments related to finding periodic orbits and global surfaces of sections in the restricted three body problem This book

is also part of the Virtual Series on Symplectic Geometry http www springer com series 16019 Representation Theory and Automorphic Forms Toshiyuki Kobayashi, Wilfried Schmid, Jae-Hyun Yang, 2007-10-10 This volume uses a unified approach to representation theory and automorphic forms It collects papers written by leading mathematicians that track recent progress in the expanding fields of representation theory and automorphic forms and their association with number theory and differential geometry Topics include Automorphic forms and distributions modular forms visible actions Dirac cohomology holomorphic forms harmonic analysis self dual representations and Langlands Functoriality Conjecture Both graduate students and researchers will find inspiration in this volume Complex Convexity and Analytic Functionals Mats Andersson, Mikael Passare, Ragnar Sigurdsson, 2012-12-06 A set in complex Euclidean space is called C convex if all its intersections with complex lines are contractible and it is said to be linearly convex if its complement is a union of complex hyperplanes These notions are intermediates between ordinary geometric convexity and pseudoconvexity Their importance was first manifested in the pioneering work of Andr Martineau from about forty years ago Since then a large number of new related results have been obtained by many different mathematicians. The present book puts the modern theory of complex linear convexity on a solid footing and gives a thorough and up to date survey of its current status Applications include the Fantappi transformation of analytic functionals integral representation formulas polynomial interpolation and solutions to linear partial differential equations

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