

MODELLING AND SIMULATION OF ROBOT MANIPULATORS

A PRACTICAL PROCEEDINGS APPROACH

ALBERT W. DORRIGAN



Modelling And Simulation Of Robot Manipulators A Parallel Processing Approach

Giancarlo Genta



Modelling And Simulation Of Robot Manipulators A Parallel Processing Approach:

Modelling and Simulation of Robot Manipulators Albert Y. Zomaya, 1992 This book aims to describe how parallel computer architectures can be used to enhance the performance of robots and their great impact on future generations of robots It provides an in depth consistent and rigorous treatment of the topic A clear definition of tools with results is given which can be applied to parallel processing for robot kinematics and dynamics Another advantageous feature is that the algorithms presented have been implemented using a parallel processing system unlike many publications in the field which have presented results in only theoretical terms This book also includes benchmark results that can be used for the development of future work or can serve as a basis for comparison with other work In addition it surveys useful material to aid readers in pursuing further research

Sensor Modelling, Design and Data Processing for Autonomous Navigation Martin David Adams, 1999 This invaluable book presents an unbiased framework for modelling and using sensors to aid mobile robot navigation It addresses the problem of accurate and reliable sensing in confined environments and makes a detailed analysis of the design and construction of a low cost optical range finder This is followed by a quantitative model for determining the sources and propagation of noise within the sensor The physics behind the causes of erroneous data is also used to derive a model for detecting and labelling such data as false In addition the author's data processing algorithms are applied to the problem of environmental feature extraction This forms the basis of a solution to the problem of mobile robot localisation The book develops a relationship between the kinematics of a mobile robot during the execution of successive manoeuvres and the sensed features Results which update a mobile vehicle's position using features from 2D and 3D scans are presented

Introduction to the Mechanics of Space Robots Giancarlo Genta, 2011-10-27 Based on lecture notes on a space robotics course this book offers a pedagogical introduction to the mechanics of space robots After presenting an overview of the environments and conditions space robots have to work in the author discusses a variety of manipulatory devices robots may use to perform their tasks This is followed by a discussion of robot mobility in these environments and the various technical approaches The last two chapters are dedicated to actuators sensors and power systems used in space robots This book fills a gap in the space technology literature and will be useful for students and for those who have an interest in the broad and highly interdisciplinary field of space robotics and in particular in its mechanical aspects

Robot Manipulators Agustin Jimenez, Basil M. Al Hadithi, 2010-03-01 This book presents the most recent research advances in robot manipulators It offers a complete survey to the kinematic and dynamic modelling simulation computer vision software engineering optimization and design of control algorithms applied for robotic systems It is devoted for a large scale of applications such as manufacturing manipulation medicine and automation Several control methods are included such as optimal adaptive robust force fuzzy and neural network control strategies The trajectory planning is discussed in details for point to point and path motions control The results in obtained in this book are expected to be of

great interest for researchers engineers scientists and students in engineering studies and industrial sectors related to robot modelling design control and application The book also details theoretical mathematical and practical requirements for mathematicians and control engineers It surveys recent techniques in modelling computer simulation and implementation of advanced and intelligent controllers

Interdisciplinary Approaches to Robot Learning John Demiris, Andreas

Birk,2000 Annotation Robots are being used in increasingly complicated and demanding tasks often in environments that are complex or even hostile Underwater space and volcano exploration are just some of the activities that robots are taking part in mainly because the environments that are being explored are dangerous for humans Robots can also inhabit dynamic environments for example to operate among humans not just in factories but also taking on more active roles Recently for instance they have made their way into the home entertainment market Given the variety of situations that robots will be placed in learning becomes increasingly important Robot learning is essentially about equipping robots with the capacity to improve their behaviour over time based on their incoming experiences The papers in this volume present a variety of techniques Each paper provides a mini introduction to a subfield of robot learning Some also give a fine introduction to the field of robot learning as a whole There is one unifying aspect to the work reported in the book namely its interdisciplinary nature especially in the combination of robotics computer science and biology This approach has two important benefits first the study of learning in biological systems can provide robot learning scientists and engineers with valuable insights into learning mechanisms of proven functionality and versatility second computational models of learning in biological systems and their implementation in simulated agents and robots can provide researchers of biological systems with a powerful platform for the development and testing of learning theories

Fuzzy Logic Control H. B. Verbruggen, Robert

Babu?ka,1999 Fuzzy logic control has become an important methodology in control engineering This volume deals with applications of fuzzy logic control in various domains The contributions are divided into three parts The first part consists of two state of the art tutorials on fuzzy control and fuzzy modeling Surveys of advanced methodologies are included in the second part These surveys address fuzzy decision making and control fault detection isolation and diagnosis complexity reduction in fuzzy systems and neuro fuzzy methods The third part contains application oriented contributions from various fields such as process industry cement and ceramics vehicle control and traffic management electromechanical and production systems avionics biotechnology and medical applications The book is intended for researchers both from the academic world and from industry

Soft Computing for Control of Non-Linear Dynamical Systems Oscar Castillo, Patricia

Melin,2012-12-06 This book presents a unified view of modelling simulation and control of non linear dynamical systems using soft computing techniques and fractal theory Our particular point of view is that modelling simulation and control are problems that cannot be considered apart because they are intrinsically related in real world applications Control of non linear dynamical systems cannot be achieved if we don't have the appropriate model for the system On the other hand we

know that complex non linear dynamical systems can exhibit a wide range of dynamic behaviors ranging from simple periodic orbits to chaotic strange attractors so the problem of simulation and behavior identification is a very important one Also we want to automate each of these tasks because in this way it is more easy to solve a particular problem A real world problem may require that we use modelling simulation and control to achieve the desired level of performance needed for the particular application

High-level Feedback Control With Neural Networks Young Ho Kim, Frank L Lewis, 1998-09-28 Complex industrial or robotic systems with uncertainty and disturbances are difficult to control As system uncertainty or performance requirements increase it becomes necessary to augment traditional feedback controllers with additional feedback loops that effectively add intelligence to the system Some theories of artificial intelligence AI are now showing how complex machine systems should mimic human cognitive and biological processes to improve their capabilities for dealing with uncertainty This book bridges the gap between feedback control and AI It provides design techniques for high level neural network feedback control topologies that contain servo level feedback control loops as well as AI decision and training at the higher levels Several advanced feedback topologies containing neural networks are presented including dynamic output feedback reinforcement learning and optimal design as well as a fuzzy logic reinforcement controller The control topologies are intuitive yet are derived using sound mathematical principles where proofs of stability are given so that closed loop performance can be relied upon in using these control systems Computer simulation examples are given to illustrate the performance

Computer Vision, Models And Inspection A David Marshall, Ralph Martin, 1992-03-26 The main focus of this book is on the uses of computer vision for inspection and model based matching It also provides a short self contained introductory course on computer vision The authors describe various state of the art approaches to problems and then set forth their proposed approach to matching and inspection They deal primarily with 3 D vision but also discuss 2 D vision strategies when relevant The book is suitable for researchers final year undergraduates and graduate students Useful review questions at the end of each chapter allow this book to be used for self study

Intelligent Assembly Systems Mark H. Lee, J. J. Rowland, 1995 This book deals with a key area of industrial robotics the automation of small batch assembly Assembly imparts enormous added value but turns out to be extraordinarily difficult to automate The work presented here all from the Centre for Intelligent Systems at the University of Wales Aberystwyth addresses this issue and shows ways in which the difficulties may be reduced through systematic architectural designs and specific structures for interfacing and controlling sensory actuation systems The book develops three main themes a task centred approach to robotic assembly explicit reasoning techniques for fault diagnosis and error handling and sensor actuator integration methods These are vital topics for those concerned with flexible automation and robotics

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