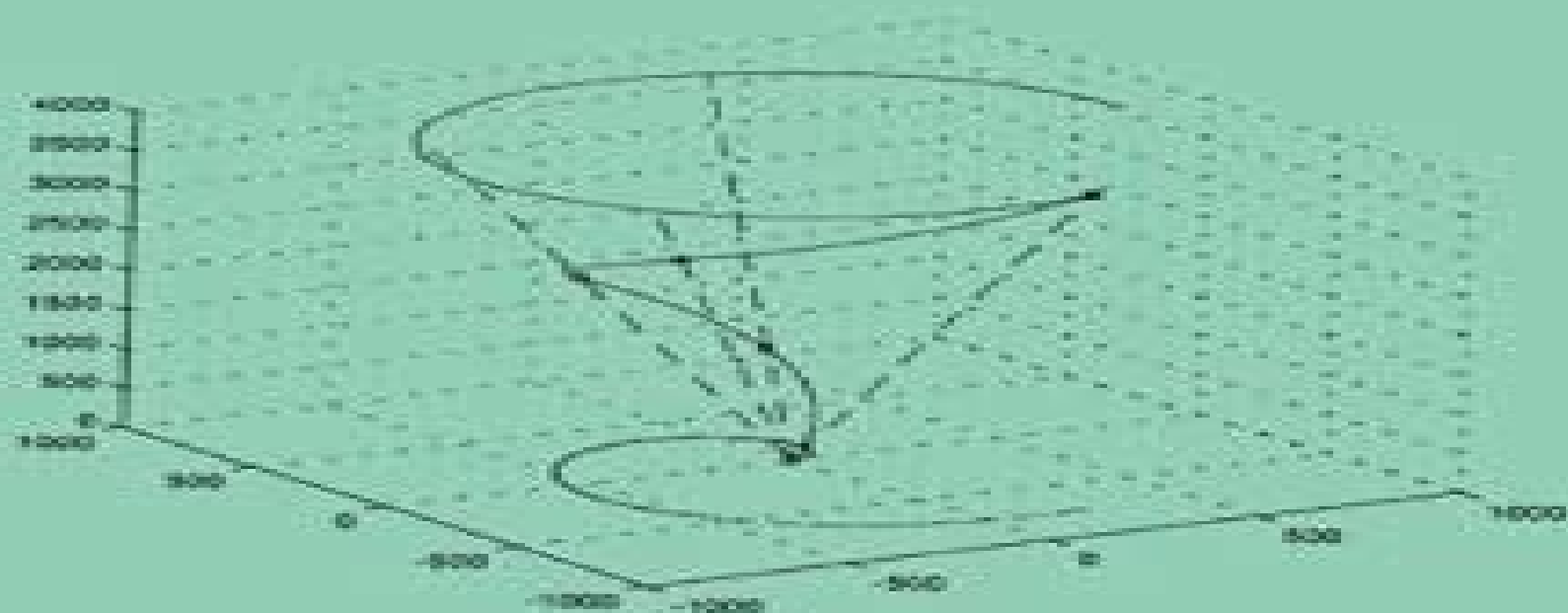


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Systems Simulator MSS which is an open source Matlab Simulink toolbox for marine systems The MSS toolbox includes hydrodynamic models and motion control systems for ships underwater vehicles and floating structures With an appropriate balance between mathematical theory and practical applications academic and industrial researchers working in marine and control engineering aspects of manned and unmanned maritime vehicles will benefit from this comprehensive handbook It is also suitable for final year undergraduates and postgraduates lecturers development officers and practitioners in the areas of rigid body modeling hydrodynamics simulation of marine craft control and estimation theory decision support systems and sensor fusion www.wiley.com/go/fossen_marine

Proceedings of the International Conference on Modern Research in Aerospace Engineering Sanjay Singh, Pushkar Raj, Samir Tambe, 2018-02-09 This book includes high quality research papers presenting the latest advances in aerospace and related engineering fields The papers are organized according to six broad areas i Aerospace Propulsion ii Space Research Avionics and Instrumentation iii Aerodynamics Wind Tunnel and Computational fluid dynamics CFD iv Structural Analysis and Finite Element Method FEM v Materials Manufacturing and Air Safety and vi Aircraft Environmental and Control System and Stability making it easy for readers to find the information they require Offering insights into the state of the art in aerospace engineering the original research presented is valuable to academics researchers undergraduate and postgraduate students as well as professionals in industry and R D The clearly written book can be used for the validation of data and the development of experimental and simulation techniques as well as other mathematical approaches

Underwater Vehicles Alexander Inzartsev, 2009-01-01 For the latest twenty to thirty years a significant number of AUVs has been created for the solving of wide spectrum of scientific and applied tasks of ocean development and research For the short time period the AUVs have shown the efficiency at performance of complex search and inspection works and opened a number of new important applications Initially the information about AUVs had mainly review advertising character but now more attention is paid to practical achievements problems and systems technologies AUVs are losing their prototype status and have become a fully operational reliable and effective tool and modern multi purpose AUVs represent the new class of underwater robotic objects with inherent tasks and practical applications particular features of technology systems structure and functional properties

Design of Unmanned Aerial Systems Mohammad H. Sadraey, 2020-04-13 Provides a comprehensive introduction to the design and analysis of unmanned aircraft systems with a systems perspective Written for students and engineers who are new to the field of unmanned aerial vehicle design this book teaches the many UAV design techniques being used today and demonstrates how to apply aeronautical science concepts to their design Design of Unmanned Aerial Systems covers the design of UAVs in three sections vehicle design autopilot design and ground systems design in a way that allows readers to fully comprehend the science behind the subject so that they can then demonstrate creativity in the application of these concepts on their own It teaches students and engineers all about UAV classifications design groups design requirements mission planning conceptual design detail design

and design procedures It provides them with in depth knowledge of ground stations power systems propulsion systems automatic flight control systems guidance systems navigation systems and launch and recovery systems Students will also learn about payloads manufacturing considerations design challenges flight software microcontroller and design examples In addition the book places major emphasis on the automatic flight control systems and autopilots Provides design steps and procedures for each major component Presents several fully solved step by step examples at component level Includes numerous UAV figures images to emphasize the application of the concepts Describes real stories that stress the significance of safety in UAV design Offers various UAV configurations geometries and weight data to demonstrate the real world applications and examples Covers a variety of design techniques processes such that the designer has freedom and flexibility to satisfy the design requirements in several ways Features many end of chapter problems for readers to practice Design of Unmanned Aerial Systems is an excellent text for courses in the design of unmanned aerial vehicles at both the upper division undergraduate and beginning graduate levels

FMCW Radar Design M. Jankiraman, 2018-07-31 Frequency Modulated Continuous Wave FMCW radars are a fast expanding area in radar technology due to their stealth features extremely high resolutions and relatively clutter free displays This groundbreaking resource offers engineers expert guidance in designing narrowband FMCW radars for surveillance navigation and missile seeking It also provides professionals with a thorough understanding of underpinnings of this burgeoning technology Moreover readers find detailed coverage of the RF components that form the basis of radar construction Featuring clear examples the book presents critical discussions on key applications Practitioners learn how to use time saving MATLAB and SystemVue design software to help them with their challenging projects in the field Additionally this authoritative reference shows engineers how to analyze FMCW radars of various types including missile seekers and missile altimeters Packed with over 600 equations the book presents discussions on key radar algorithms and their implementation as well as designing modern radar to meet given operational requirements

Proceedings of 4th 2024 International Conference on Autonomous Unmanned Systems (4th ICAUS 2024)

Lianqing Liu, Yifeng Niu, Wenxing Fu, Yi Qu, 2025-03-27 This book includes original peer reviewed research papers from the 4th ICAUS 2024 which provides a unique and engaging platform for scientists engineers and practitioners from all over the world to present and share their most recent research results and innovative ideas The 4th ICAUS 2024 aims to stimulate researchers working in areas relevant to intelligent unmanned systems Topics covered include but are not limited to Unmanned Aerial Ground Surface Underwater Systems Robotic Autonomous Control Navigation and Positioning Architecture Energy and Task Planning and Effectiveness Evaluation Technologies Artificial Intelligence Algorithm Bionic Technology and their Application in Unmanned Systems The papers presented here share the latest findings in unmanned systems robotics automation intelligent systems control systems integrated networks modelling and simulation This makes the book a valuable resource for researchers engineers and students alike

Advanced Mobile Robotics DaeEun Kim, 2020-03-06 Mobile

robotics is a challenging field with great potential. It covers disciplines including electrical engineering, mechanical engineering, computer science, cognitive science, and social science. It is essential to the design of automated robots in combination with artificial intelligence, vision, and sensor technologies. Mobile robots are widely used for surveillance, guidance, transportation, and entertainment tasks, as well as medical applications. This Special Issue intends to concentrate on recent developments concerning mobile robots and the research surrounding them to enhance studies on the fundamental problems observed in the robots. Various multidisciplinary approaches and integrative contributions including navigation, learning, and adaptation, networked systems, biologically inspired robots, and cognitive methods are welcome contributions to this Special Issue, both from a research and an application perspective.

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