

volume 43

lecture notes in pure and applied mathematics



mathematics of finite-dimensional control systems

theory and design

David L. Russell

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David L. Russell



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Robust Engineering Designs of Partial Differential Systems and Their Applications Bor-Sen Chen, 2021-12-23 Most systems in science engineering and biology are of partial differential systems PDSs modeled by partial differential equations Many books about partial differential equations have been written by mathematicians and mainly address some fundamental mathematic backgrounds and discuss some mathematic properties of partial differential equations Only a few books on PDSs have been written by engineers however these books have focused mainly on the theoretical stabilization analysis of PDSs especially mechanical systems This book investigates both robust stabilization control design and robust filter design and reference tracking control design in mechanical signal processing and control systems to fill a gap in the study of PDSs Robust Engineering Designs of Partial Differential Systems and Their Applications offers some fundamental background in the first two chapters The rest of the chapters focus on a specific design topic with a corresponding deep investigation into robust H filtering stabilization or tracking design for more complex and practical PDSs under stochastic fluctuation and external disturbance This book is aimed at engineers and scientists and addresses the gap between the theoretical stabilization results of PDSs in academic and practical engineering designs more focused on the robust H filtering

stabilization and tracking control problems of linear and nonlinear PDSs under intrinsic random fluctuation and external disturbance in industrial applications Part I provides backgrounds on PDSs such as Galerkin s and finite difference methods to approximate PDSs and a fuzzy method to approximate nonlinear PDSs Part II examines robust H filter designs for the robust state estimation of linear and nonlinear stochastic PDSs And Part III treats robust H stabilization and tracking control designs of linear and nonlinear PDSs Every chapter focuses on an engineering design topic with both theoretical design analysis and practical design examples

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American Mathematical Monthly, 1980 **Signal Processing and Systems Theory** Charles K. Chui, Guanrong

Chen, 2012-12-06 Signal Processing and Systems Theory is concerned with the study of H optimization for digital signal processing and discrete time control systems The first three chapters present the basic theory and standard methods in digital filtering and systems from the frequency domain approach followed by a discussion of the general theory of approximation in Hardy spaces AAK theory is introduced first for finite rank operators and then more generally before being extended to the multi input multi output setting This mathematically rigorous book is self contained and suitable for self study The advanced mathematical results derived here are applicable to digital control systems and digital filtering

Subject Catalog, 1979 Library of Congress, 1979 *Subject Catalog* Library of Congress, **Cybernetics Abstracts**, 1979 **Applied Mechanics Reviews**, 1972 *Library of Congress Catalogs* Library of Congress, 1980 *Internationale Bibliographie der Rezensionen wissenschaftlicher Literatur*, 1981

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