

Jadran Lenarčič · Manfred Husty *Editors*

Latest Advances in Robot Kinematics

 Springer

Recent Advances In Robot Kinematics

Jadran Lenarcic, Manfred Husty



Recent Advances In Robot Kinematics:

Recent Advances in Robot Kinematics Jadran Lenarčič, Vincenzo Parenti Castelli, 2012-12-06 The articles of this book were reported and discussed at the fifth international symposium on Advances in Robot Kinematics As is known the first symposium of this series was organised in 1988 in Ljubljana The following meetings took place every other year in Austria Italy and Slovenia Linz Ferrara Ljubljana Portoroz Bernardin It must be emphasised that the symposia run under the patronage of the International Federation for the Theory of Machines and Mechanisms IFToMM In this period Advances in Robot Kinematics has been able to attract the most outstanding authors in the area and also to create an optimum combination of a scientific pragmatism and a friendly atmosphere Hence it has managed to survive in a strong competition of many international conferences and meetings In the most ancient way robot kinematics is regarded as an application of the kinematics of rigid bodies However there are topics and problems that are typical for robot kinematics that cannot easily be found in any other scientific field It is our belief that the initiative of Advances in Robot Kinematics has contributed to develop a remarkable scientific community The present book is of interest to researchers doctoral students and teachers engineers and mathematicians specialising in kinematics of robots and mechanisms mathematical modelling simulation design and control of robots

Latest Advances in Robot Kinematics Jadran Lenarčič, Manfred Husty, 2012-05-19 This book is of interest to researchers inquiring about modern topics and methods in the kinematics control and design of robotic manipulators It considers the full range of robotic systems including serial parallel and cable driven manipulators both planar and spatial The systems range from being less than fully mobile to kinematically redundant to overconstrained In addition to recognized areas this book also presents recent advances in emerging areas such as the design and control of humanoids and humanoid subsystems and the analysis modeling and simulation of human body motions as well as the mobility analysis of protein molecules and the development of machines which incorporate man

Advances in Robot Kinematics: Motion in Man and Machine Jadran Lenarčič, Michael M. Stanišić, 2010-07-20 The first International Meeting of Advances in Robot Kinematics ARK occurred in September 1988 by invitation to Ljubljana Slovenia of a group of 20 internationally recognized researchers representing six different countries from three continents There were 22 lectures and approximately 150 attendees This success of bringing together excellent research and the international community led to the formation of a Scientific Committee and the decision to repeat the event biannually The meeting was made open to all individuals with a critical peer review process of submitted papers The meetings have since been continuously supported by the Jozef Stefan Institute and since 1992 have come under patronage of the Inter

tional Federation for the Promotion of Mechanism and Machine Science IFToMM Springer published the first book of the series in 1991 and since 1994 Kluwer and Springer have published a book of the presented papers every two years The papers in this book present the latest topics and methods in the kinematics control and design of robotic manipulators They consider the full

range of botic systems including serial parallel and cable driven manipulators both planar and spatial The systems range from being less than fully mobile to kinematically redundant to overconstrained The meeting included recent advances in emerging areas such as the design and control of humanoids and humanoid subsystems the analysis modeling and simulation of human body motion the mobility analysis of protein molecules and the development of systems which integrate man and chine

Advances in Robot Kinematics Jadran Lenarčič,Oussama Khatib,2014-05-19 The topics addressed in this book cover the whole range of kinematic analysis synthesis and design and consider robotic systems possessing serial parallel and cable driven mechanisms The robotic systems range from being less than fully mobile to kinematically redundant to over constrained The fifty six contributions report the latest results in robot kinematics with emphasis on emerging areas such as design and control of humanoids or humanoid subsystems The book is of interest to researchers wanting to bring their knowledge up to date regarding modern topics in one of the basic disciplines in robotics which relates to the essential property of robots the motion of mechanisms

Advances in Robot Kinematics 2016 Jadran Lenarčič,Jean-Pierre Merlet,2017-07-26 This book brings together 46 peer reviewed papers that are of interest to researchers wanting to know more about the latest topics and methods in the fields of the kinematics control and design of robotic systems These papers cover the full range of robotic systems including serial parallel and cable driven manipulators both planar and spatial The systems range from being less than fully mobile to kinematically redundant to over constrained In addition to these more familiar areas the book also highlights recent advances in some emerging areas such as the design and control of humanoids and humanoid subsystems the analysis modeling and simulation of human body motions mobility analyses of protein molecules and the development of machines that incorporate man

Advances in Robot Kinematics: Analysis and Control Jadran Lenarčič,Manfred L. Husty,2013-04-17 The contributions in this book were presented at the sixth international symposium on Advances in Robot Kinematics organised in June July 1998 in Strobl Salzburg in Austria The preceding symposia of the series took place in Ljubljana 1988 Linz 1990 Ferrara 1992 Ljubljana 1994 and Piran 1996 Ever since its first event ARK has attracted the most outstanding authors in the area and managed to create a perfect combination of professionalism and friendly atmosphere We are glad to observe that in spite of a strong competition of many international conferences and meetings ARK is continuing to grow in terms of the number of participants and in terms of its scientific impact In its ten years ARK has contributed to develop a remarkable scientific community in the area of robot kinematics The last four symposia were organised under the patronage of the International Federation for the Theory of Machines and Mechanisms IFToMM interest to researchers doctoral students and teachers The book is of engineers and mathematicians specialising in kinematics of robots and mechanisms mathematical modelling simulation design and control of robots It is divided into sections that were found as the prevalent areas of the contemporary kinematics research As it can easily be noticed an important part of the book is dedicated to various aspects of the kinematics of parallel mechanisms that persist to

be one of the most attractive areas of research in robot kinematics

Advances in Robot Kinematics and Computational Geometry Jadran Lenarčič, Bahram Ravani, 2013-06-29

Recently research in robot kinematics has attracted researchers with different theoretical profiles and backgrounds such as mechanical and electrical engineering computer science and mathematics It includes topics and problems that are typical for this area and cannot easily be met elsewhere As a result a specialised scientific community has developed concentrating its interest in a broad class of problems in this area and representing a conglomeration of disciplines including mechanics theory of systems algebra and others Usually kinematics is referred to as the branch of mechanics which treats motion of a body without regard to the forces and moments that cause it In robotics kinematics studies the motion of robots for programming control and design purposes It deals with the spatial positions orientations velocities and accelerations of the robotic mechanisms and objects to be manipulated in a robot workspace The objective is to find the most effective mathematical forms for mapping between various types of coordinate systems methods to minimise the numerical complexity of algorithms for real time control schemes and to discover and visualise analytical tools for understanding and evaluation of motion properties of various mechanisms used in a robotic system

Recent Advances in Robotic Systems Guanghui Wang, 2016-09-28 This book brings together some recent advances and development in robotics In 12 chapters written by experts and researchers in respective fields the book presents some up to date research ideas and findings in a wide range of robotics including the design modeling control learning interaction and navigation of robots From an application perspective the book covers UAVs USVs mobile robots humanoid robots graspers and underwater robots The unique text offers practical guidance to graduate students and researchers in research and applications in the field of robotics

New Advances in Mechanisms, Mechanical Transmissions and Robotics Erwin-Christian Lovasz, Inocentiu Maniu, Ioan Doroftei, Mircea Ivanescu, Corina-Mihaela

Gruescu, 2020-10-14 This volume gathers the proceedings of the Joint International Conference of the XIII International Conference on Mechanisms and Mechanical Transmissions MTM and the XXIV International Conference on Robotics Robotics held in Timișoara Romania It addresses the applications of mechanisms and transmissions in several modern technical fields such as mechatronics biomechanics machines micromachines robotics and apparatus In doing so it combines theoretical findings and experimental testing The book presents peer reviewed papers written by researchers specialized in mechanism analysis and synthesis dynamics of mechanisms and machines mechanical transmissions biomechanics precision mechanics mechatronics micromechanisms and microactuators computational and experimental methods CAD in mechanism and machine design mechanical design of robot architecture parallel robots mobile robots micro and nano robots sensors and actuators in robotics intelligent control systems biomedical engineering teleoperation haptics and virtual reality

Advances in Robot Kinematics Jadran Lenarčič, Federico Thomas, 2013-06-29 This is the fifth book of the Kluwer's series *Advances in Robot Kinematics* The book presents the most recent research advances in the theory design control and

application of robotic systems which are intended for a variety of purposes such as manipulation manufacturing automation surgery locomotion and biomechanics The issues addressed are fundamentally kinematic in nature including synthesis calibration redundancy force control dexterity inverse and forward kinematics kinematic singularities as well as over constrained systems Methods used include line geometry quaternion algebra screw algebra and linear algebra These methods are applied to both parallel and serial multi degree of freedom systems The results should interest researchers teachers and students in fields of engineering and mathematics related to robot theory design control and application Each contribution in this book had been rigorously reviewed by two or three independent reviewers and 53 articles had been recommended for publication We are happy to observe that Advances in Robot Kinematics has always attracted the most outstanding authors and has developed a remarkable scientific community in the area Many important and original scientific results were for the first time reported and discussed in these books All articles in this book were also reported at the eight international symposium on Advances in Robot Kinematics that was organised in June 2002 in Caldes de Malavella in Spain

Recent Advances in Industrial Machines and Mechanisms Sanjoy K. Ghoshal, Arun K. Samantaray, Sandipan Bandyopadhyay, 2024-01-04 This book presents select proceedings of the Conference on Industrial Problems on Machines and Mechanisms IPRoMM 2022 It presents a comprehensive coverage of the recent developments in analysis design and manufacturing of a range of modern and next generation industrial machines and solutions to mitigate common and emerging problems in their maintenance and operation The topics covered include design manufacturing and performance analysis of mechanical and mechatronic machine components and assemblies machine dynamics including rotor dynamics vehicle dynamics and multi body dynamics robotics and automation hydraulic and pneumatic systems and control vibration engineering tribology condition monitoring failure analysis manufacturing systems and processes reliability and quality engineering thermo fluid and combustion systems aerospace systems acoustics automotive engineering etc The book discusses theoretical and practical developments in these fields which have direct industrial relevance The book serves as a valuable reference for researchers and professionals interested in analysis design manufacturing maintenance and operation of industrial machinery

Advances in Robot Kinematics 2018 Jadran Lenarcic, Vincenzo Parenti-Castelli, 2018-06-22 This is the proceedings of ARK 2018 the 16th International Symposium on Advances in Robot Kinematics that was organized by the Group of Robotics Automation and Biomechanics GRAB from the University of Bologna Italy ARK are international symposia of the highest level organized every two years since 1988 ARK provides a forum for researchers working in robot kinematics and stimulates new directions of research by forging links between robot kinematics and other areas The main topics of the symposium of 2018 were kinematic analysis of robots robot modeling and simulation kinematic design of robots kinematics in robot control theories and methods in kinematics singularity analysis kinematic problems in parallel robots redundant robots cable robots over constrained linkages kinematics in biological systems humanoid robots and humanoid subsystems

Technology Developments: the Role of Mechanism and Machine Science and IFToMM Marco Ceccarelli, 2011-05-26 This is the first book of a series that will focus on MMS Mechanism and Machine Science This book also presents IFToMM the International Federation on the Promotion of MMS and its activity This volume contains contributions by IFToMM officers who are Chairs of member organizations MOs permanent commissions PCs and technical committees TCs who have reported their experiences and views toward the future of IFToMM and MMS The book is composed of three parts the first with general considerations by high standing IFToMM persons the second chapter with views by the chairs of PCs and TCs as dealing with specific subject areas and the third one with reports by the chairs of MOs as presenting experiences and challenges in national and territory communities This book will be of interest to a wide public who wish to know the status and trends in MMS both at international level through IFToMM and in national local frames through the leading actors of activities In addition the book can be considered also a fruitful source to find out who s who in MMS historical backgrounds and trends in MMS developments as well as for challenges and problems in future activity by IFToMM community and in MMS at large

Advances in Robot Kinematics: Analysis and Design Jadran Lenarčič, Philippe Wenger, 2008-05-29 This book presents the most recent research advances in the theory design control and application of robotic systems which are intended for a variety of purposes such as manipulation manufacturing automation surgery locomotion and biomechanics

Recent Advances in Mechanical Infrastructure Ajit Kumar Parwani, PL. Ramkumar, Kumar Abhishek, Saurabh Kumar Yadav, 2021-03-01 This book contains high quality papers presented in the conference Recent Advances in Mechanical Infrastructure ICRAM 2020 held at IITRAM Ahmedabad India from 21 23 August 2020 The topics covered in this book are recent advances in thermal infrastructure manufacturing infrastructure and infrastructure planning and design

Mechanism Design for Robotics Marco Ceccarelli, Alessandro Gasparetto, 2019-06-21 MEDER 2018 the IFToMM International Symposium on Mechanism Design for Robotics was the fourth event in a series that was started in 2010 as a specific conference activity on mechanisms for robots The aim of the MEDER Symposium is to bring researchers industry professionals and students together from a broad range of disciplines dealing with mechanisms for robots in an intimate collegial and stimulating environment In the 2018 MEDER event we received significant attention regarding this initiative as can be seen by the fact that the Proceedings contain contributions by authors from all around the world The Proceedings of the MEDER 2018 Symposium have been published within the Springer book series on MMS and the book contains 52 papers that have been selected after review for oral presentation These papers cover several aspects of the wide field of robotics dealing with mechanism aspects in theory design numerical evaluations and applications This Special Issue of Robotics https://www.mdpi.com/journal/robotics/special_issues MDR has been obtained as a result of a second review process and selection but all the papers that have been accepted for MEDER 2018 are of very good quality with interesting contents that are suitable for journal publication and the selection process has been difficult

Basics of Robotics Adam Morecki, Jozef

Knapczyk,2014-05-04 This volume contains the basic concepts of modern robotics basic definitions systematics of robots in industry service medicine and underwater activity Important information on walking and mili walking machines are included as well as possible applications of microrobots in medicine agriculture underwater activity **Robot Mechanisms** Jadran Lenarcic,Tadej Bajd,Michael M. Stanišić,2012-06-12 This book provides a comprehensive introduction to the area of robot mechanisms primarily considering industrial manipulators and humanoid arms The book is intended for both teaching and self study Emphasis is given to the fundamentals of kinematic analysis and the design of robot mechanisms The coverage of topics is untypical The focus is on robot kinematics The book creates a balance between theoretical and practical aspects in the development and application of robot mechanisms and includes the latest achievements and trends in robot science and technology **New Advances in Mechanisms, Transmissions and Applications** Victor Petuya,Charles Pinto,Erwin-Christian Lovasz,2013-08-04 The Second Conference on Mechanisms Transmissions and Applications MeTrApp 2013 was organised by the Mechanical Engineering Department of the University of the Basque Country Spain under the patronage of the IFToMM Technical Committees Linkages and Mechanical Controls and Micromachines and the Spanish Association of Mechanical Engineering The aim of the workshop was to bring together researchers scientists industry experts and students to provide in a friendly and stimulating environment the opportunity to exchange know how and promote collaboration in the field of Mechanism and Machine Science The topics treated in this volume are mechanism and machine design biomechanics mechanical transmissions mechatronics computational and experimental methods dynamics of mechanisms and micromechanisms and microactuators *Product Engineering* Doru Talaba,Thomas Roche,2006-06-01 This book contains an edited version of the lectures and selected contributions presented during the Advanced Summer Institute on Product Engineering Eco Design Technologies and Green Energy organized at the st Transilvania University of Brasov Romania in the period 14 21 of July 2004 The Advanced Summer Institute ASI was organized in the framework of the European FP5 funded project ADEPT Advanced computer aided Design of Ecological Products and Technologies integrating green energy sources and was devoted to the Product Engineering field with particular attention to the aspects related to the environmentally conscious design and green energy sources The objective of the ASI was to create the framework for meeting of leading scientists with PhD holders and advanced PhD students carrying out research in the field of Eco Design CAD Simulation technologies Robotics Manufacturing and green energy sources The aim was to create conditions for high level training through a series of 15 invited lectures presented by world reputed scientists as well as to give possibilities for young researchers to present their achievements and to establish professional contacts The ASI was seen also as an opportunity for academics practitioners and consultants from Europe and elsewhere who are involved in the study management development and implementation of product engineering principles in the learning and teaching sectors as well as professionals to come together and share ideas on projects and examples of best practice

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