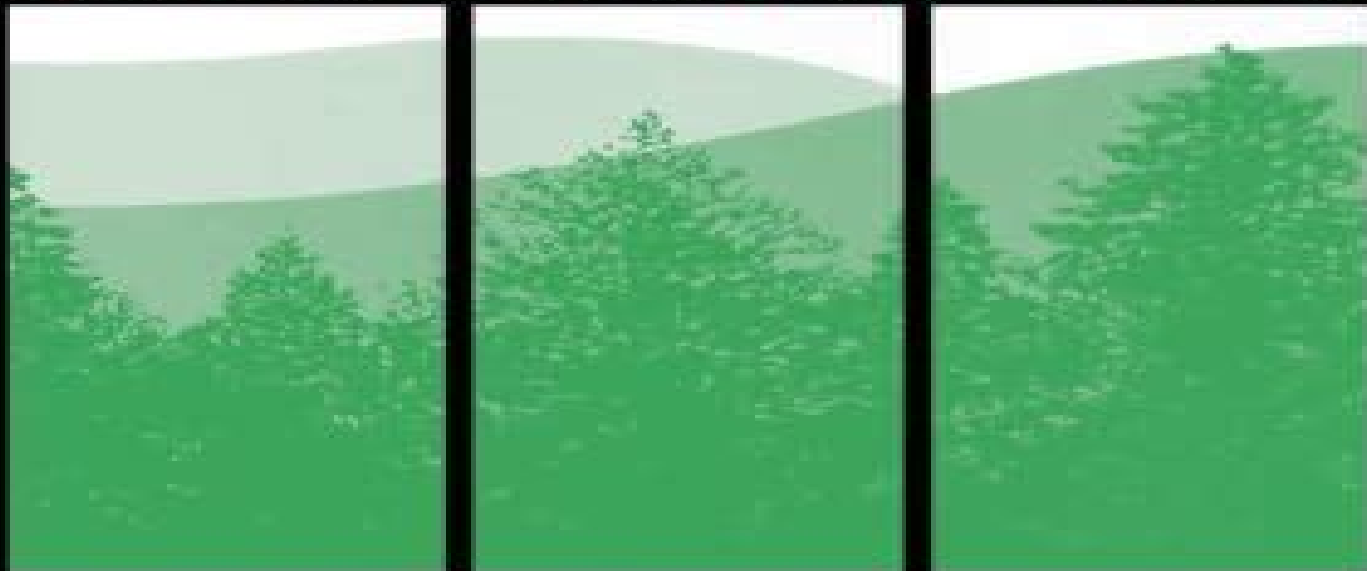PROCEEDINGS OF THE 1986 WORKSHOP

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Reasoning about Actions & Plans American Association for Artificial Intelligence,Center for the Study of Language and Information (U.S.),1987 Reasoning About Actions Plans   **Situation Theory and Its Applications: Volume 3** Robin Cooper,Peter Aczel,Kuniaki Mukai,John Perry,1990 Situation theory is the result of an interdisciplinary effort to create a full fledged theory of information Created by scholars and scientists from cognitive science computer science and AI linguistics logic philosophy and mathematics it aims to provide a common set of tools for the analysis of phenomena from all these fields Unlike Shannon Weaver type theories of information which are purely quantitative theories situation theory aims at providing tools for the analysis of the specific content of a situation signal message data base statement or other information carrying situation The question addressed is not how much information is carried but what information is carried   Current Trends in AI Planning Christer Bäckström,Erik Sandewall,1994 AI planning is a broad research topic linked with such issues as robotics control theory operations research and learning The purpose of EWSP 93 was twofold Planning under certainty or classical search based planning is one direction in the submitted papers with approaches ranging from the introduction of conditional actions to methods based on statistics and decision theory   Computational Theories of Interaction and Agency Philip Agre,Stanley J. Rosenschein,1996 Over time the field of artificial intelligence has developed an agent perspective expanding its focus from thought to action from search spaces to physical environments and from problem solving to long term activity Originally published as a special double volume of the journal Artificial Intelligence this book brings together fundamental work by the top researchers in artificial intelligence neural networks computer science robotics and cognitive science on the themes of interaction and agency It identifies recurring themes and outlines a methodology of the concept of agency The seventeen contributions cover the construction of principled characterizations of interactions between agents and their environments as well as the use of these characterizations to guide analysis of existing agents and the synthesis of artificial agents Artificial Intelligence series Special Issues of Artificial Intelligence   **Rules of Encounter** Jeffrey S. Rosenschein,Gilad Zlotkin,1994 Provides a unified coherent account of machine interaction at the level of the machine designers the society of designers and the level of the machine interaction itself the resulting artificial society Rules of Encounter applies the general approach and the mathematical tools of game theory in a formal analysis of rules or protocols governing the high level behavior of interacting heterogeneous computer systems It describes a theory of high level protocol design that can be used to constrain manipulation and harness the potential of automated negotiation and coordination strategies to attain more effective interaction among machines that have been programmed by different entities to pursue different goals While game theoretic ideas have been used to answer the question of how a computer should be programmed to act in a given specific interaction here they are used in a new way to address the question of how to design the rules of interaction themselves for automated agents Rules of Encounter provides a unified coherent account of machine interaction

at the level of the machine designers the society of designers and the level of the machine interaction itself the resulting artificial society Taking into account such attributes of the artificial society as efficiency and the self interest of each member in the society of designers it analyzes what kinds of rules should be instituted to govern interaction among these autonomous agents The authors point out that adjusting the rules of public behavior or the rules of the game by which the programs must interact can influence the private strategies that designers set up in their machines shaping design choices and run time behavior as well as social behavior Artificial Intelligence series **Proceedings of MSR-RoManSy 2024** Pierre Larochelle,J. Michael McCarthy,Craig P. Lusk,2024-05-28 This book gathers the latest fundamental research contributions innovations and applications in the field of design and analysis of complex robotic mechanical systems machines and mechanisms as presented by leading researchers at the combined IFToMM Symposium of RoManSy and USCToMM Symposium on Mechanical Systems and Robotics MSR RoManSy held in St Petersburg FL USA on May 22 25 2024 It covers highly diverse topics including soft wearable and origami robotic systems applications to walking flying climbing underground swimming and space systems human rehabilitation and performance augmentation design and analysis of mechanisms and machines human robot collaborative systems service robotics mechanical systems and robotics education and the commercialization of mechanical systems and robotics The contributions which were selected by means of a rigorous international peer review process highlight numerous exciting and impactful research results that will inspire novel research directions and foster multidisciplinary research collaborations among researchers from around the globe *Proceedings of the Eighteenth Annual Conference of the Cognitive Science Society* Garrison W. Cottrell,2019-02-21 This volume features the complete text of all regular papers posters and summaries of symposia presented at the 18th annual meeting of the Cognitive Science Society Papers have been loosely grouped by topic and an author index is provided in the back In hopes of facilitating searches of this work an electronic index on the Internet s World Wide Web is provided Titles authors and summaries of all the papers published here have been placed in an online database which may be freely searched by anyone You can reach the Web site at http www cse ucsd edu events cogsci96 proceedings You may view the table of contents for this volume on the LEA Web site at http www erlbaum com *Encyclopedia of Computer Science and Technology* Allen Kent,James G. Williams,1994-08-31 This comprehensive reference work provides immediate fingertip access to state of the art technology in nearly 700 self contained articles written by over 900 international authorities Each article in the Encyclopedia features current developments and trends in computers software vendors and applications extensive bibliographies of leading figures in the field such as Samuel Alexander John von Neumann and Norbert Wiener and in depth analysis of future directions **Computational Logic: Logic Programming and Beyond** Antonis C. Kakas,Fariba Sadri,2003-08-02 Alan Robinson This set of essays pays tribute to Bob Kowalski on his 60th birthday an anniversary which gives his friends and colleagues an excuse to celebrate his career as an original thinker a charismatic communicator and a

forceful intellectual leader The logic programming community hereby and herein conveys its respect and thanks to him for his pivotal role in creating and fostering the conceptual paradigm which is its raison d tre The diversity of interests covered here reflects the variety of Bob s concerns Read on It is an intellectual feast Before you begin permit me to send him a brief personal but public message Bob how right you were and how wrong I was I should explain When Bob arrived in Edinburgh in 1967 resolution was as yet fairly new having taken several years to become at all widely known Research groups to investigate various aspects of resolution sprang up at several institutions the one organized by Bernard Meltzer at Edinburgh University being among the first For the half dozen years that Bob was a leading member of Bernard s group I was a frequent visitor to it and I saw a lot of him We had many discussions about logic computation and language **Knowledge in Action** Raymond Reiter,2001-07-27 Specifying and implementing dynamical systems with the situation calculus Modeling and implementing dynamical systems is a central problem in artificial intelligence robotics software agents simulation decision and control theory and many other disciplines In recent years a new approach to representing such systems grounded in mathematical logic has been developed within the AI knowledge representation community This book presents a comprehensive treatment of these ideas basing its theoretical and implementation foundations on the situation calculus a dialect of first order logic Within this framework it develops many features of dynamical systems modeling including time processes concurrency exogenous events reactivity sensing and knowledge probabilistic uncertainty and decision theory It also describes and implements a new family of high level programming languages suitable for writing control programs for dynamical systems Finally it includes situation calculus specifications for a wide range of examples drawn from cognitive robotics planning simulation databases and decision theory together with all the implementation code for these examples This code is available on the book s Web site *Principles of Semantic Networks* John F. Sowa,2014-07-10 Principles of Semantic Networks Explorations in the Representation of Knowledge provides information pertinent to the theory and applications of semantic networks This book deals with issues in knowledge representation which discusses theoretical topics independent of particular implementations Organized into three parts encompassing 19 chapters this book begins with an overview of semantic network structure for representing knowledge as a pattern of interconnected nodes and arcs This text then analyzes the concepts of subsumption and taxonomy and synthesizes a framework that integrates many previous approaches and goes beyond them to provide an account of abstract and partially defines concepts Other chapters consider formal analyses which treat the methods of reasoning with semantic networks and their computational complexity This book discusses as well encoding linguistic knowledge The final chapter deals with a formal approach to knowledge representation that builds on ideas originating outside the artificial intelligence literature in research on foundations for programming languages This book is a valuable resource for mathematicians **Artificial Intelligence Methods in Software Testing** Mark Last,Abraham Kandel,Horst Bunke,2004 Coverage of novel methods for software testing and software quality

assurance Introduction to state of the art data mining models and techniques Analyses of new and promising application domains of artificial intelligence and data mining in software quality engineering Contributions from leading authors in the fields of software engineering and data mining **Practical Planning** David E. Wilkins,2014-06-28 Planning or reasoning about actions is a fundamental element of intelligent behavior and one that artificial intelligence has found very difficult to implement The most well understood approach to building planning systems has been under refinement since the late 1960s and has now reached a level of maturity where there are good prospects for building working planners Practical Planning is an in depth examination of this classical planning paradigm through an intensive case study of SIPE a significantly implemented planning system The author the developer of SIPE defines the planning problem in general explains why reasoning about actions is so complex and describes all parts of the SIPE system and the algorithms needed to achieve efficiency Details are discussed in the context of problems and important issues in building a practical planner discussions of how other systems address these issues are also included Assuming only a basic background in AI Practical Planning will be of great interest to professionals interested in incorporating planning capabilities into AI systems *Machine Learning Methods for Planning* Steven Minton,2014-05-12 Machine Learning Methods for Planning provides information pertinent to learning methods for planning and scheduling This book covers a wide variety of learning methods and learning architectures including analogical case based decision tree explanation based and reinforcement learning Organized into 15 chapters this book begins with an overview of planning and scheduling and describes some representative learning systems that have been developed for these tasks This text then describes a learning apprentice for calendar management Other chapters consider the problem of temporal credit assignment and describe tractable classes of problems for which optimal plans can be derived This book discusses as well how reactive integrated systems give rise to new requirements and opportunities for machine learning The final chapter deals with a method for learning problem decompositions which is based on an idealized model of efficiency for problem reduction search This book is a valuable resource for production managers planners scientists and research workers **Philosophy and AI** Robert Cummins,John L. Pollock,1991 Philosophy and AI presents invited contributions that focus on the different perspectives and techniques that philosophy and AI bring to the theory of rationality Philosophers have found that the concepts and technology of artificial intelligence provide useful ways to test theories of knowledge and reason Conversely researchers in artificial intelligence noting that the production of information processing systems require a prior theory of rationality have begun writing philosophy Philosophy and AI presents invited contributions that focus on the different perspectives and techniques that philosophy and AI bring to the theory of rationality A Bradford Book **Exploring Artificial Intelligence** Howard E. Shrobe,2014-05-12 Exploring Artificial Intelligence Survey Talks from the National Conference on Artificial Intelligence provides information pertinent to the distinct subareas of artificial intelligence research This book discusses developments in machine learning techniques Organized into six parts

encompassing 16 chapters this book begins with an overview of intelligent tutoring systems which describes how to guide a student to learn new concepts This text then links closely with one of the concerns of intelligent tutoring systems namely how to interact through the utilization of natural language Other chapters consider the various aspects of natural language understanding and survey the huge body of work that tries to characterize heuristic search programs This book discusses as well how computer programs can create plans to satisfy goals The final chapter deals with computational facilities that support This book is a valuable resource for cognitive scientists psychologists domain experts computer scientists instructional designers expert teachers and research workers   Designing Autonomous Agents Pattie Maes,1990 Designing Autonomous Agents provides a summary and overview of the radically different architectures that have been developed over the past few years for organizing robots These architectures have led to major breakthroughs that promise to revolutionize the study of autonomous agents and perhaps artificial intelligence in general The new architectures emphasize more direct coupling of sensing to action distributedness and decentralization dynamic interaction with the environment and intrinsic mechanisms to cope with limited resources and incomplete knowledge The research discussed here encompasses such important ideas as emergent functionality task level decomposition and reasoning methods such as analogical representations and visual operations that make the task of perception more realistic Contents A Biological Perspective on Autonomous Agent Design Randall D Beer Hillel J Chiel Leon S Sterling Elephants Don t Play Chess Rodney A Brooks What Are Plans For Philip E Agre and David Chapman Action and Planning in Embedded Agents Leslie Pack Kaelbling and Stanley J Rosenschein Situated Agents Can Have Goals Pattie Maes Exploiting Analogical Representations Luc Steels Internalized Plans A Representation for Action Resources David W Payton Integrating Behavioral Perceptual and World Knowledge in Reactive Navigation Ronald C Arkin Symbol Grounding via a Hybrid Architecture in an Autonomous Assembly System Chris Malcolm and Tim Smithers Animal Behavior as a Paradigm for Developing Robot Autonomy Tracy L Anderson and Max Donath   **Conceptual Modeling - ER 2009** Alberto H. F. Laender,Silvana Castano,Umeshwar Dayal,Fabio Casati,José Palazzo M. de Oliverira,2009-10-26 This book constitutes the refereed proceedings of the 28th International Conference on Conceptual Modeling ER 2009 held in Gramado Brazil in November 2009 The 31 revised full papers presented together with 18 demo papers were carefully reviewed and selected from 162 submissions The papers are organized in topical sections on conceptual modeling requirements engineering query approaches space and time modeling schema matching and integration application contexts process and service modeling and industrial session   Logic Programs, Norms and Action Alexander Artikis,Robert Craven,Nihan Kesim Cicekli,Babak Sadighi,Kostas Stathis,2012-04-25 This book is dedicated to Marek Sergot Professor in Computational Logic at Imperial College London on the occasion of his 60th birthday Professor Sergot s scientific contributions range over many different fields He has developed a series of novel ideas and formal methods bridging areas including artificial intelligence computational logic philosophical logic legal theory artificial intelligence and

law multi agent systems and bioinformatics By combining his background in logic and computing with his interest in the law deontic logic action and related areas and applying to all his capacity to understand the subtleties of social interaction and normative reasoning Professor Sergot has opened up new directions of research and has been a reference an inspiration and a model for many researchers in the fields to which he has contributed The Festschrift includes several reminiscences and introductory essays describing Professor Sergot s achievements followed by a series of articles on logic programming temporal reasoning and action languages artificial intelligence and law deontic logic and norm governed systems and logical approaches to policies   *ARPA/Rome Laboratory Knowledge-based Planning and Scheduling Initiative Workshop Proceedings, Tuscon, Arizona, February 21-24, 1994* ,1994

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