



Mobile Robots Xii

Paolo Dario, Raja Chatila



Mobile Robots Xii:

Mobile Robots XII. ,1998 Algorithmic Foundations of Robotics XII Ken Goldberg,Pieter Abbeel,Kostas Bekris,Lauren Miller,2020-05-06 This book presents the outcomes of the 12th International Workshop on the Algorithmic Foundations of Robotics WAFR 2016 WAFR is a prestigious single track biennial international meeting devoted to recent advances in algorithmic problems in robotics Robot algorithms are an important building block of robotic systems and are used to process inputs from users and sensors perceive and build models of the environment plan low level motions and high level tasks control robotic actuators and coordinate actions across multiple systems However developing and analyzing these algorithms raises complex challenges both theoretical and practical Advances in the algorithmic foundations of robotics have applications to manufacturing medicine distributed robotics human robot interaction intelligent prosthetics computer animation computational biology and many other areas The 2016 edition of WAFR went back to its roots and was held in San Francisco California the city where the very first WAFR was held in 1994 Organized by Pieter Abbeel Kostas Bekris Ken Goldberg and Lauren Miller WAFR 2016 featured keynote talks by John Canny on A Guided Tour of Computer Vision Robotics Algebra and HCI Erik Demaine on Replicators Transformers and Robot Swarms Science Fiction through Geometric Algorithms Dan Halperin on From Piano Movers to Piano Printers Computing and Using Minkowski Sums and by Lydia Kavraki on 20 Years of Sampling Robot Motion Furthermore it included an Open Problems Session organized by Ron Alterovitz Florian Pokorny and Jur van den Berg There were 58 paper presentations during the three day event The organizers would like to thank the authors for their work and contributions the reviewers for ensuring the high quality of the meeting the WAFR Steering Committee led by Nancy Amato as well as WAFR s fiscal sponsor the International Federation of Robotics Research IFRR led by Oussama Khatib and Henrik Christensen WAFR 2016 was an enjoyable and memorable event

Transactions on Rough Sets XII James F. Peters,Roman Slowinski,Pawan Lingras,Andrzej Skowron,Duoqian Miao,Shusaku Tsumoto,2010-07-15 The LNCS journal Transactions on Rough Sets is devoted to the entire spectrum of rough sets related issues from logical and mathematical foundations through all aspects of rough set theory and its applications such as data mining knowledge discovery and intelligent information processing to relations between rough sets and other approaches to uncertainty vagueness and incompleteness such as fuzzy sets and theory of evidence This volume contains 8 revised selected papers from 11 submissions to the Rough Set and Knowledge Technology Conference RSKT 2008 together with 5 papers introducing advances in rough set theory and its applications The topics covered are perceptually near Pawlak partitions hypertext classification topological space versus rough set theory in terms of lattice theory feature extraction in interval valued information systems jumping emerging patterns JEP and rough set theory **Transactions on Computational Science XII** ,2011-07-27 The 12th issue of the Transactions on Computational Science journal edited by Alexei Sourin and Olga Sourina is devoted to the topic of cyberworlds The 13 papers in the volume constitute revised and

extended versions of a selection of contributions presented at CW 2010 the 20th International Conference on Cyberworlds held in Singapore in October 2010 The selected papers span the areas of tangible interfaces emotion recognition haptic modeling decision making under uncertainty reliability measures use of biometrics for avatar recognition cybernavigation multiuser virtual environments spatial data sampling web visualization and interactive character animation system design

Mobile Robots XII Douglas W. Gage, 1998 Intelligent Distributed Computing XII Javier Del Ser, Eneko Osaba, Miren Nekane Bilbao, Javier J. Sanchez-Medina, Massimo Vecchio, Xin-She Yang, 2018-09-14 This book gathers a wealth of research contributions on recent advances in intelligent and distributed computing and which present both architectural and algorithmic findings in these fields A major focus is placed on new techniques and applications for evolutionary computation swarm intelligence multi agent systems multi criteria optimization and Deep Shallow machine learning models all of which are approached as technological drivers to enable autonomous reasoning and decision making in complex distributed environments Part of the book is also devoted to new scheduling and resource allocation methods for distributed computing systems The book represents the peer reviewed proceedings of the 12th International Symposium on Intelligent Distributed Computing IDC 2018 which was held in Bilbao Spain from October 15 to 17 2018 **Robotics and Cognitive Approaches to Spatial Mapping** Margaret E. Jefferies, Wai-Kiang Yeap, 2008-01-10 This important work is an attempt to synthesize two areas that need to be treated in tandem The book brings together the fields of robot spatial mapping and cognitive spatial mapping which share some common core problems One would expect some cross fertilization of research between the two areas to have occurred yet this has begun only recently There are now signs that some synthesis is happening so this work is a timely one for students and engineers in robotics RoboCup 2008: Robot Soccer World Cup XII Luca Iocchi, Hitoshi Matsubara, Alfredo Weitzenfeld, Changjiu Zhou, 2009-06-24 The 12th annual RoboCup International Symposium was held during July 15 18 2008 in conjunction with RoboCup 2008 Competitions and Demonstrations The symposium represents the core meeting for the presentation and discussion of scientific contributions in diverse areas related to the main threads within RoboCup Soccer RoboCup Rescue RoboCup Home and RoboCup Junior Its scope encompassed but was not restricted to research and education activities within the fields of artificial intelligence and robotics A fundamental aspect of RoboCup is promoting science and technology among young students and researchers in addition to providing a forum for discussion and excitement about Robotics with practitioners from all over the world Since its first edition in 1997 in Nagoya the RoboCup Competitions and Symposium have attracted an increasing number of researchers and students from all the world and today it is a major event in robotics worldwide Due to its interdisciplinary nature and the exploration of various and intimate connections of theory and practice across a wide spectrum of different fields the symposium offered an excellent opportunity to introduce new techniques to various scientific disciplines The experimental interactive and benchmark character of the RoboCup initiative created the opportunity to present learn and evaluate novel ideas and approaches with significant potential

If promising they are then rapidly adopted and field tested by a large and still strongly growing community **Advances in Communications, Computing, Electronics, Networks, Robotics and Security Volume 12** Paul Dowland, 2016-07 This book is the twelfth in a series presenting research papers arising from MSc MRes research projects undertaken by students of the School of Computing and Mathematics at Plymouth University The publications in this volume are based upon research projects that were undertaken during the 2013 14 academic year A total of 17 papers are presented covering many aspects of modern networking and communication technology including security mobility coding schemes and quality measurement The expanded topic coverage compared to earlier volumes in this series reflects the broadening of our range of MSc programmes Specifically contributing programmes are Communications Engineering and Signal Processing Computer and Information Security Computer Science Computing Electrical and Electronic Engineering Network Systems Engineering and Robotics

Artificial Intelligence and Computational Intelligence Hepu Deng, Lanzhou Wang, Fu Lee Wang, Jingsheng Lei, 2009-11-21 The 2009 International Conference on Artificial Intelligence and Computational Intelligence AICI 2009 was held during November 7 8 2009 in Shanghai China The technical program of the conference reflects the tremendous growth in the fields of artificial intelligence and computational intelligence with contributions from a large number of participants around the world AICI 2009 received 1 203 submissions from 20 countries and regions After rigorous reviews 79 high quality papers were selected for this volume representing an acceptance rate of 6.6% These selected papers cover many new developments and their applications in the fields of artificial intelligence and computational intelligence Their publications reflect a sustainable interest from the wide academic community worldwide in tirelessly pursuing new solutions through effective utilizations of artificial intelligence and computational intelligence to real world problems We would like to specially thank all the committee members and reviewers without whose timely help it would have been impossible to review all the submitted papers to assemble this program We also would like to take this opportunity to express our heartfelt appreciation for all those who worked together in organizing this conference establishing the technical programs and running the conference meetings We greatly appreciate the authors speakers invited session organizers session Chairs and others who made this conference possible Lastly we would like to express our gratitude to the Shanghai University of Electric Power for the sponsorship and support of the conference Robotics Research Paolo Dario, Raja Chatila, 2005-02-17 ISRR the International Symposium on Robotics Research is one of robotics pioneering symposia which has established some of the field's most fundamental and lasting contributions over the past two decades This book presents the results of the eleventh edition of Robotics Research ISRR03 offering a broad range of topics in robotics The contributions provide a wide coverage of the current state of robotics research the advances and challenges in its theoretical foundation and technology basis and the developments in its traditional and new emerging areas of applications The diversity novelty and span of the work unfolding in these areas reveal the field's increased maturity and expanded scope and define the state of the art of robotics and its future direction Path

Planning for Vehicles Operating in Uncertain 2D Environments Viacheslav Pshikhopov, 2017-01-28 Path Planning for Vehicles Operating in Uncertain 2D environments presents a survey that includes several path planning methods developed using fuzzy logic grapho analytical search neural networks and neural like structures procedures of genetic search and unstable motion modes Presents a survey of accounting limitations imposed by vehicle dynamics Proposes modified and new original methods including neural networking grapho analytical and nature inspired Gives tools for a novice researcher to select a method that would suit their needs or help to synthesize new hybrid methods Underwater Vehicles Alexander Inzartsev, 2009-01-01 For the latest twenty to thirty years a significant number of AUVs has been created for the solving of wide spectrum of scientific and applied tasks of ocean development and research For the short time period the AUVs have shown the efficiency at performance of complex search and inspection works and opened a number of new important applications Initially the information about AUVs had mainly review advertising character but now more attention is paid to practical achievements problems and systems technologies AUVs are losing their prototype status and have become a fully operational reliable and effective tool and modern multi purpose AUVs represent the new class of underwater robotic objects with inherent tasks and practical applications particular features of technology systems structure and functional properties

Medial measures for recognition, mapping and categorization Morteza Rezanejad, Visual shape analysis plays a fundamental role in perception by man and by computer allowing for inferences about properties of objects and scenes in the physical world Mathematical approaches to describing visual form can benefit from the use of representations that simultaneously capture properties of an object's outline as well as its interior Motivated by the success of medial models this doctoral thesis revisits a quantity related to medial axis computations the average outward flux of the gradient of the Euclidean distance function from a boundary and then addresses three distinct problems using this measure First I consider the problem of view sphere partitioning for view based object recognition from sparse views View based 3D object recognition requires a selection of model object views against which to match a query view Ideally for this to be computationally efficient such a selection should be sparse To address this problem I introduce a novel hierarchical partitioning of the view sphere into regions within which the silhouette of a model object is qualitatively unchanged To achieve this I propose a part based abstraction of a skeleton as a graph dubbed the Flux Graph which allows for views to be grouped Next I consider the problem of mapping an initially unknown 2D environment from possibly noisy sensed samples via an on line procedure which robustly computes a retraction of its boundaries to obtain a topological representation Here I motto an algorithm that allows for online map construction with loop closure I demonstrate that the proposed method allows the robot to localize itself on a partially constructed map to calculate a path to unexplored parts of the environment frontiers to compute a robust terminating condition when the robot has fully explored the environment and finally to achieve loop closure detection I also show that the resulting map is stable under disturbances to the sensed boundary and to variations in

starting locations for exploration Finally I consider the problem of scene categorization from complex line drawings In the context of human vision we show that local ribbon symmetry between neighboring pairs of contours facilitates the categorization of complex real world environments by human observers In the context of computer vision I demonstrate a high level of performance in the problem of convolutional neural network based recognition of natural scenes from line drawings even in the absence of color texture and shading information

Communication and Control for Robotic Systems Jason Gu,Rajeeb Dey,Nabanita Adhikary,2021-08-02 This book is a collection of high quality research articles The book includes topics specific to the emerging areas of control for robotic systems wireless communication and development of embedded systems for robotic applications The book integrates three important aspects of automation namely i communication ii control and iii embedded design for robotic applications This book is unique as it provides a unified framework for analysis design and deployment of the robotic applications across various engineering and non engineering disciplines including the three primary aspects mentioned above Furthermore the emerging research and development work pertaining to the deployment of intelligent nonlinear and embedded control for robotic system for non standard operating environment due to the widespread application of robotics technology for societal benefit is also a focal point of the book

International Aerospace Abstracts ,1998 Information and Software Technologies Robertas Damaševičius,Giedrė Vasiljevienė,2019-10-03 This book constitutes the refereed proceedings of the 25th International Conference on Information and Software Technologies ICIST 2019 held in Vilnius Lithuania in October 2019 The 46 papers presented were carefully reviewed and selected from 121 submissions The papers are organized in topical sections on information systems business intelligence for information and software systems information technology applications software engineering *Autonomous Robots* George A. Bekey,2005 An introduction to the science and practice of autonomous robots that reviews over 300 current systems and examines the underlying technology

Proceedings of the 5th International Conference on Electrical Engineering and Control Applications-Volume 1 Salim Ziani,Mohammed Chadli,Sofiane Bououden,Ivan Zelinka,2024-09-30 This book gathers papers presented during the 5th International Conference on Electrical Engineering and Control Applications ICEECA 2022 held on November 15 17 2022 Khenchela Algeria It covers new control system models troubleshooting tips and complex system requirements such as increased speed precision and remote capabilities Additionally the book discusses not only the engineering aspects of signal processing and various practical issues in the broad field of information transmission but also novel technologies for communication networks and modern antenna design The later part of the book covers important related topics such as fault diagnosis and fault tolerant control strategies for nonlinear systems and alternative energy sources This book is intended for researchers engineers and advanced postgraduate students in the fields of control and electrical engineering computer science signal processing as well as mechanical and chemical engineering

Applications of Digital Image Processing XII Society of Photo-optical

Instrumentation Engineers, New Mexico State University. Applied Optics Laboratory, 1989

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