A Framework for Reasoning about Rational Agents

Wojciech Jamroga and Nils Bulling Department of Informatics, Clausthal University of Technology, Germany (wiamroga,bulling)@in.tu-clausthal.de

ABSTRACT

We propose an extension of alternating-time temporal logic, that can be used for reasoning about the behavior and abilities of agents under various rationality assumptions.

Categories and Subject Descriptors

1.2.11 [Artificial Intelligence]: Distributed Artificial Intelligence— Multiagent Systems; 1.2.4 [Artificial Intelligence]: Knowledge Representation Formalisms and Methods—Modal logic

General Terms

Theory:

Keywords

multi-agent systems, game theory, temporal logic, rationality

1. INTRODUCTION

Aftermating-time temporal logic (ATL) [1] is a temporal logic that incorporates some basic game theoretical notions. In this paper, we extend ATL, with a notion of plausibility, which can be used to model and reason about rational behavior of agents. In our approach, some strategies (or rather senings profiles) can be assumed plausible, and one can reason about what can be plausibly achieved by agents under such an assumption.

This idea has been inspired by the way in which games are analyzed in game theory. First, game theory identifies a number of solution concepts (e.g., Nash equilibrium, undominated strategies, Pareto optimality) that can be used to define rationality of players. Then, we usually assume that players play rationally in the sense of one of the concepts, and we ask about the outcome of the game ander this assumption. Note that solution concepts do not only help to determine the right decision for "out" agent. Perhaps even more importantly, they constrain the possible (predicted) responses of the opponents. For many games the number of all possible outcomes is infinite, although only some of them "make sense". Still, we need a notion of rationality (like subgame-perfect Nash equilibrium) to

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AAMAS '07 May 14-18 2007, Honolulu, Hawai'i, USA. Copyright 2007 IFAAMAS discard the "less sensible" ones, and determine what should happen had the game been played by ideal players.

There are two possible points of focus in this context. Research within game theory understandably favors work on characterization of various types of rationality (and defining most appropriate solution concepts). Applications of game theory, also understandably, tend toward using the solution concepts to predict the outcome in a given game (i.e., to "solve" the game). The first issue has been studied in the framework of logic, for example in [2, 4, 10, 11]; more recently, game-theoretical solution concepts have been characterized in dynamic logic [7]. dynamic epistemic logic [3], and ATL [13, 8]. The second issue seems to have been neglected in logic-based research; papers by Van Otterloo and his colleagues [14, 16, 15] are the only exceptions we know of (and each of them commits to a particular view of rationality). Here, we try to fill in this gap, and propose a general, modal logic-based framework for reasoning about behavior and abilities of rational agents.

2. ATL

The language of Alternating-time Temporal Logic [1] is defined over a set Agt of agents and a set II of propositions, and consists of the following formulae:

$$\varphi := \varphi [\neg \varphi] \varphi \wedge \varphi [\notin A \otimes \gamma, \quad \gamma := O \varphi [D \varphi] \varphi \mathcal{U} \varphi.$$

where $p \in \Pi$ and $A \subseteq Agt$. Informally, $((A)) \varphi$ says that agents A have a collective strategy to enforce φ . ATL formulae include the usual temporal operators: \bigcirc ("in the next state"), \square ("always from now on") and M (strict "until"), Additionally, \bigcirc ("now or sometime in the future") can be defined as $\bigcirc \varphi \equiv \top M \varphi$.

The semantics of ATL is defined in concurrent game attactures:

$$M = (Ags, Q, \Pi, \pi, Act, d, \phi),$$

consisting of: a set Agt = $\{1, \dots, k\}$ of agents: set Q of states; set Π of atomic propositions: valuation of propositions: $\pi: Q \longrightarrow P(Act)$ indicates the actions available to agent $a \in Agt \times Q \longrightarrow P(Act)$ indicates the actions available to agent $a \in Agt$ in state $q \in Q$. A move vector in state q is a tuple $(m_1, \dots, m_k) \in d(q)$ where $d(q) = \prod_{a \in Agt} d_a(q)$ is the set of all move vectors in q. Finally, o is a transition function which maps a state $q \in Q$ and a move vector $(m_1, \dots, m_k) \in d(q)$ to another state $g' = o(q, (m_1, \dots, m_k))$.

A computation or path $\lambda = q_0 q_1 \dots$ is an infinite sequence of states such that there is a transition between each q_i, q_{i+1} . We define $\lambda[i] = q_i$ to denote the i-th state of λ . Λ_{Ad} denotes all paths of M. The set of all paths, starting in q_i is given by $\Lambda_{Ad}(q)$.

A (memoryless) strategy of agent α is a function $s_\alpha: Q \longrightarrow Act$ such that $s_\alpha(q) \subseteq d_\alpha(q)$. The set of strategies for agent α is denoted by Σ_α . A collective arrange s_A for team $A \subseteq Agt$ specifies an individual strategy for each agent $\alpha \in A$. Now, $\Sigma_A =$

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Michael T. Cox, Anita Raja

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