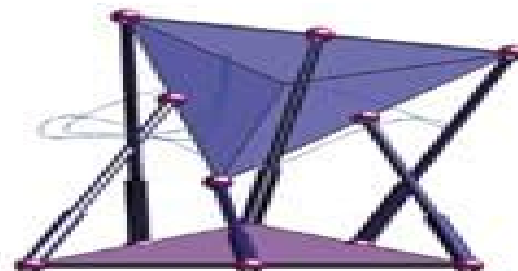
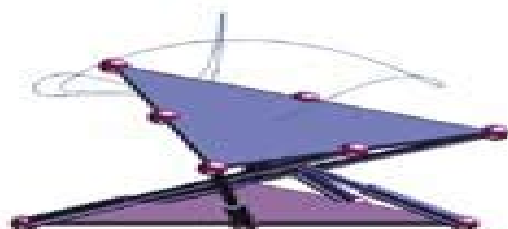
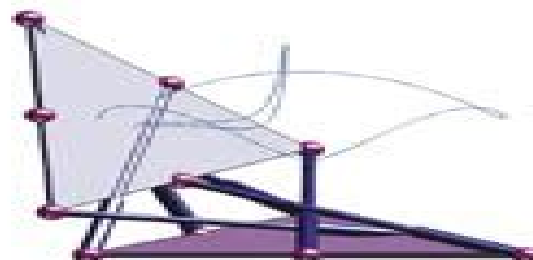
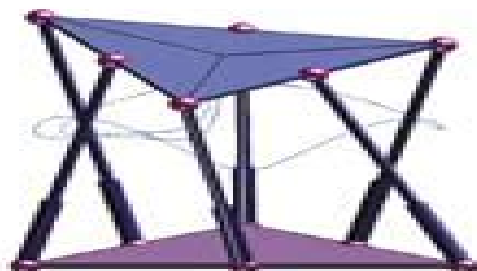


The Numerical Solution of Systems of Polynomials Arising in Engineering and Science



Numerical Solution Of Systems Of Polynomials Arising In Engineering And Science

**Andrew J Sommese, Charles W
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The Numerical Solution Of Systems Of Polynomials Arising In Engineering And Science Andrew J Sommese, Charles W Wampler, II, 2005-03-21 Written by the founders of the new and expanding field of numerical algebraic geometry this is the first book that uses an algebraic geometric approach to the numerical solution of polynomial systems and also the first one to treat numerical methods for finding positive dimensional solution sets The text covers the full theory from methods developed for isolated solutions in the 1980 s to the most recent research on positive dimensional sets

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Numerically Solving Polynomial Systems with Bertini Daniel J. Bates, Jonathan D. Hauenstein, Andrew J. Sommese, Charles W. Wampler, 2013-11-08 This book is a guide to concepts and practice in numerical algebraic geometry the solution of systems of polynomial equations by numerical methods Through numerous examples the authors show how to apply the well received and widely used open source Bertini software package to compute solutions including a detailed manual on syntax and usage options The authors also maintain a complementary web page where readers can find supplementary materials and Bertini input files Numerically Solving Polynomial Systems with Bertini approaches numerical algebraic geometry from a user s point of view with numerous examples of how Bertini is applicable to polynomial systems It treats the fundamental task of solving a given polynomial system and describes the latest advances in the field including algorithms for intersecting and projecting algebraic sets methods for treating singular sets the nascent field of real numerical algebraic geometry and applications to large polynomial systems arising from differential equations Those who wish to solve polynomial systems can start gently by finding isolated solutions to small systems advance rapidly to using algorithms for finding positive dimensional solution sets curves surfaces etc and learn how to use parallel computers on large problems These techniques are of interest to engineers and scientists in fields where polynomial equations arise including robotics control theory economics physics numerical PDEs and computational chemistry

Future Vision and Trends on Shapes, Geometry and Algebra Raffaele de Amicis, Giuseppe Conti, 2014-06-13 Mathematical algorithms are a fundamental component of Computer Aided Design and Manufacturing CAD CAM systems This book provides a bridge between algebraic geometry and geometric modelling algorithms formulated within a computer science framework Apart from the algebraic geometry topics covered the entire book is based on the unifying concept of using algebraic techniques properly specialized to solve geometric problems to seriously improve accuracy robustness and efficiency of CAD systems It provides new approaches as well as industrial

applications to deform surfaces when animating virtual characters to automatically compare images of handwritten signatures and to improve control of NC machines This book further introduces a noteworthy representation based on 2D contours which is essential to model the metal sheet in industrial processes It additionally reviews applications of numerical algebraic geometry to differential equations systems with multiple solutions and bifurcations Future Vision and Trends on Shapes Geometry and Algebra is aimed specialists in the area of mathematics and computer science on the one hand and on the other hand at those who want to become familiar with the practical application of algebraic geometry and geometric modelling such as students researchers and doctorates

Approximate Commutative Algebra Lorenzo Robbiano, John Abbott, 2009-09-18 Approximate Commutative Algebra is an emerging field of research which endeavours to bridge the gap between traditional exact Computational Commutative Algebra and approximate numerical computation The last 50 years have seen enormous progress in the realm of exact Computational Commutative Algebra and given the importance of polynomials in scientific modelling it is very natural to want to extend these ideas to handle approximate empirical data deriving from physical measurements of phenomena in the real world In this volume nine contributions from established researchers describe various approaches to tackling a variety of problems arising in Approximate Commutative Algebra

Topological and Statistical Methods for Complex Data Janine Bennett, Fabien Vivodtzev, Valerio Pascucci, 2014-11-19 This book contains papers presented at the Workshop on the Analysis of Large scale High Dimensional and Multi Variate Data Using Topology and Statistics held in Le Barp France June 2013 It features the work of some of the most prominent and recognized leaders in the field who examine challenges as well as detail solutions to the analysis of extreme scale data The book presents new methods that leverage the mutual strengths of both topological and statistical techniques to support the management analysis and visualization of complex data It covers both theory and application and provides readers with an overview of important key concepts and the latest research trends Coverage in the book includes multi variate and or high dimensional analysis techniques feature based statistical methods combinatorial algorithms scalable statistics algorithms scalar and vector field topology and multi scale representations In addition the book details algorithms that are broadly applicable and can be used by application scientists to glean insight from a wide range of complex data sets

Interactions of Classical and Numerical Algebraic Geometry Daniel James Bates, 2009-09-16 This volume contains the proceedings of the conference on Interactions of Classical and Numerical Algebraic Geometry held May 22-24 2008 at the University of Notre Dame in honor of the achievements of Professor Andrew J Sommese While classical algebraic geometry has been studied for hundreds of years numerical algebraic geometry has only recently been developed Due in large part to the work of Andrew Sommese and his collaborators the intersection of these two fields is now ripe for rapid advancement The primary goal of both the conference and this volume is to foster the interaction between researchers interested in classical algebraic geometry and those interested in numerical methods The topics in this book include but are not limited to various new results

in complex algebraic geometry a primer on Seshadri constants analyses and presentations of existing and novel numerical homotopy methods for solving polynomial systems a numerical method for computing the dimensions of the cohomology of twists of ideal sheaves and the application of algebraic methods in kinematics and phylogenetics *Mathematical Software - ICMS 2020* Anna Maria Bigatti, Jacques Carette, James H. Davenport, Michael Joswig, Timo de Wolff, 2020-07-07 This book constitutes the proceedings of the 7th International Conference on Mathematical Software ICMS 2020 held in Braunschweig Germany in July 2020 The 48 papers included in this volume were carefully reviewed and selected from 58 submissions The program of the 2020 meeting consisted of 20 topical sessions each of which providing an overview of the challenges achievements and progress in a environment of mathematical software research development and use The New Palgrave Dictionary of Economics, 2016-05-18 The award winning The New Palgrave Dictionary of Economics 2nd edition is now available as a dynamic online resource Consisting of over 1 900 articles written by leading figures in the field including Nobel prize winners this is the definitive scholarly reference work for a new generation of economists Regularly updated This product is a subscription based product *21st Century Kinematics* J. Michael McCarthy, 2012-08-04 21st Century Kinematics focuses on algebraic problems in the analysis and synthesis of mechanisms and robots compliant mechanisms cable driven systems and protein kinematics The specialist contributors provide the background for a series of presentations at the 2012 NSF Workshop The text shows how the analysis and design of innovative mechanical systems yield increasingly complex systems of polynomials characteristic of those systems In doing so it takes advantage of increasingly sophisticated computational tools developed for numerical algebraic geometry and demonstrates the now routine derivation of polynomial systems dwarfing the landmark problems of even the recent past The 21st Century Kinematics workshop echoes the NSF supported 1963 Yale Mechanisms Teachers Conference that taught a generation of university educators the fundamental principles of kinematic theory As such these proceedings will provide admirable supporting theory for a graduate course in modern kinematics and should be of considerable interest to researchers in mechanical design robotics or protein kinematics or who have a broader interest in algebraic geometry and its applications **Nonlinear Computational Geometry** Ioannis Z. Emiris, Frank Sottile, Thorsten Theobald, 2009-10-28 An original motivation for algebraic geometry was to understand curves and surfaces in three dimensions Recent theoretical and technological advances in areas such as robotics computer vision computer aided geometric design and molecular biology together with the increased availability of computational resources have brought these original questions once more into the forefront of research One particular challenge is to combine applicable methods from algebraic geometry with proven techniques from piecewise linear computational geometry such as Voronoi diagrams and hyperplane arrangements to develop tools for treating curved objects These research efforts may be summarized under the term nonlinear computational geometry This volume grew out of an IMA workshop on Nonlinear Computational Geometry in May June 2007 organized by I Z Emiris R Goldman F Sottile T Theobald which

gathered leading experts in this emerging field The research and expository articles in the volume are intended to provide an overview of nonlinear computational geometry Since the topic involves computational geometry algebraic geometry and geometric modeling the volume has contributions from all of these areas By addressing a broad range of issues from purely theoretical and algorithmic problems to implementation and practical applications this volume conveys the spirit of the IMA workshop

Combinatorial, Computational, and Applied Algebraic Geometry Serkan Hoşten, Diane Maclagan, Frank Sottile, 2025-10-01 This volume consists of surveys on topics to which Bernd Sturmfels has contributed over his mathematical career invariant theory Gröbner bases toric ideals and varieties algebraic methods in discrete and convex optimization hypergeometric systems algebraic statistics likelihood geometry tropical geometry chemical reaction networks numerical methods in algebraic geometry sums of squares tropical geometry tensors and algebraic vision Each article gives a gentle introduction to the topic Many contributions summarize the state of the art in each subject The volume is perfect for anyone who wishes an entry point to any one of these diverse topics

Polynomial Optimization, Moments, and Applications Michal Kočvara, Bernard Mourrain, Cordian Riener, 2023-12-27 Polynomial optimization is a fascinating field of study that has revolutionized the way we approach nonlinear problems described by polynomial constraints The applications of this field range from production planning processes to transportation energy consumption and resource control This introductory book explores the latest research developments in polynomial optimization presenting the results of cutting edge interdisciplinary work conducted by the European network POEMA For the past four years experts from various fields including algebraists geometers computer scientists and industrial actors have collaborated in this network to create new methods that go beyond traditional paradigms of mathematical optimization By exploiting new advances in algebra and convex geometry these innovative approaches have resulted in significant scientific and technological advancements This book aims to make these exciting developments accessible to a wider audience by gathering high quality chapters on these hot topics Aimed at both aspiring and established researchers as well as industry professionals this book will be an invaluable resource for anyone interested in polynomial optimization and its potential for real world applications

Matrix Methods in the Design Analysis of Mechanisms and Multibody Systems John J. Uicker, Pradip N. Sheth, Bahram Ravani, 2013-04-15 This is an integrated approach to kinematic and dynamic analysis The matrix techniques presented are general and applicable to two or three dimensional systems The techniques lend themselves to programming and digital computation and can be a usable tool for designers and are applicable to the design analysis of all multibody mechanical systems

Stochastic Models, Information Theory, and Lie Groups, Volume 1 Gregory S. Chirikjian, 2009-09-02 This unique two volume set presents the subjects of stochastic processes information theory and Lie groups in a unified setting thereby building bridges between fields that are rarely studied by the same people Unlike the many excellent formal treatments available for each of these subjects individually the emphasis in both of these volumes is on the use of stochastic geometric and group theoretic

concepts in the modeling of physical phenomena Stochastic Models Information Theory and Lie Groups will be of interest to advanced undergraduate and graduate students researchers and practitioners working in applied mathematics the physical sciences and engineering Extensive exercises and motivating examples make the work suitable as a textbook for use in courses that emphasize applied stochastic processes or differential geometry **Computational Kinematics** Federico Thomas,Alba Perez Gracia,2013-10-17 Computational kinematics is an enthralling area of science with a rich spectrum of problems at the junction of mechanics robotics computer science mathematics and computer graphics The covered topics include design and optimization of cable driven robots analysis of parallel manipulators motion planning numerical methods for mechanism calibration and optimization geometric approaches to mechanism analysis and design synthesis of mechanisms kinematical issues in biomechanics construction of novel mechanical devices as well as detection and treatment of singularities The results should be of interest for practicing and research engineers as well as Ph D students from the fields of mechanical and electrical engineering computer science and computer graphics **Algebra, Geometry and Their Interactions** Alberto Corso,Juan Carlos Migliore,Claudia Polini,2007 This volume s papers present work at the cutting edge of current research in algebraic geometry commutative algebra numerical analysis and other related fields with an emphasis on the breadth of these areas and the beneficial results obtained by the interactions between these fields This collection of two survey articles and sixteen refereed research papers written by experts in these fields gives the reader a greater sense of some of the directions in which this research is moving as well as a better idea of how these fields interact with each other and with other applied areas The topics include blowup algebras linkage theory Hilbert functions divisors vector bundles determinantal varieties square free monomial ideals multiplicities and cohomological degrees and computer vision

Advances in Reconfigurable Mechanisms and Robots II Xilun Ding,Xianwen Kong,Jian S. Dai,2015-11-23 This book presents the most recent advances in the research and applications of reconfigurable mechanisms and robots It collects 93 independently reviewed papers presented at the Third ASME IFToMM International Conference on Reconfigurable Mechanisms and Robots ReMAR 2015 held in Beijing China 20 22 July 2015 The conference papers are organized into seven parts to cover the reconfiguration theory topology kinematics and design of reconfigurable mechanisms including reconfigurable parallel mechanisms The most recent results on reconfigurable robots are presented including their analysis design simulation and control Bio inspired mechanisms are also explored in the challenging fields of rehabilitation and minimally invasive surgery This book further addresses deployable mechanisms and origami inspired mechanisms and showcases a wide range of successful applications of reconfigurable mechanisms and robots Advances in Reconfigurable Mechanisms and Robots II should be of interest for researchers engineers and postgraduate students in mechanical engineering electrical engineering computer science and mathematics **Quantum Metrology with Photoelectrons** Paul Hockett,2018-04-20 Since the turn of the century the increasing availability of photoelectron imaging experiments along with

the increasing sophistication of experimental techniques and the availability of computational resources for analysis and numerics has allowed for significant developments in such photoelectron metrology Quantum Metrology with Photoelectrons Volume 2 Applications and Advances discusses the fundamental concepts along with recent and emerging applications Volume 2 explores the applications and development of quantum metrology schemes based on photoelectron measurements The author begins with a brief historical background on complete photoionization experiments followed by the details of state reconstruction methodologies from experimental measurements Three specific applications of quantum metrology schemes are discussed in detail In addition the book provides advances future directions and an outlook including ongoing work to generalise these schemes and extend them to dynamical many body systems Volume 2 will be of interest to readers wishing to see the sometimes messy details of state reconstruction from photoelectron measurements as well as explore the future prospects for this class of metrology *Solving Polynomial Systems Using Continuation for Engineering and Scientific Problems* Alexander Morgan, 2009-06-04 An elementary introduction to polynomial continuation

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