

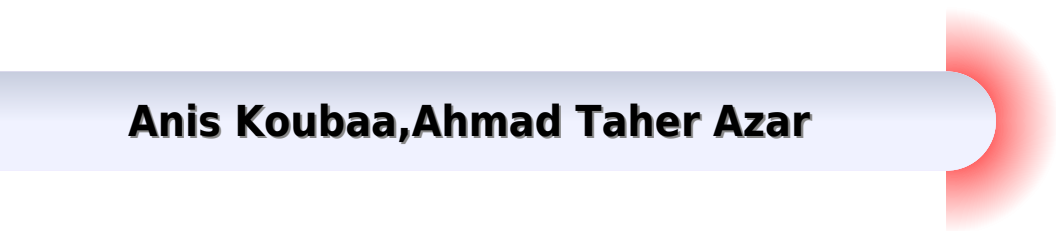
**Sergiy Butenko, Robert Murphey
and Panos Pardalos
(Editors)**

**Recent Developments
in Cooperative Control
and Optimization**

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Recent Developments In Cooperative Control And Optimization

Anis Koubaa, Ahmad Taher Azar



Recent Developments In Cooperative Control And Optimization:

Recent Developments in Cooperative Control and Optimization Sergiy Butenko, Robert Murphey, Panos M.

Pardalos, 2013-12-01 Over the past several years cooperative control and optimization has unquestionably been established as one of the most important areas of research in the military sciences Even so cooperative control and optimization transcends the military in its scope having become quite relevant to a broad class of systems with many exciting commercial applications One reason for all the excitement is that research has been so incredibly diverse spanning many scientific and engineering disciplines This latest volume in the Cooperative Systems book series clearly illustrates this trend towards diversity and creative thought And no wonder cooperative systems are among the hardest systems control science has endeavored to study hence creative approaches to modeling analysis and synthesis are a must The definition of cooperation itself is a slippery issue As you will see in this and previous volumes cooperation has been cast into many different roles and therefore has assumed many diverse meanings Perhaps the most we can say which unites these disparate concepts is that cooperation 1 requires more than one entity 2 the entities must have some dynamic behavior that influences the decision space 3 the entities share at least one common objective and 4 entities are able to share information about themselves and their environment Optimization and control have long been active fields of research in engineering

Optimization and Logistics Challenges in the Enterprise Wanpracha Chaovalitwongse, Kevin C. Furman, Panos M. Pardalos, 2009-06-17 In a world with highly competitive markets and economic instability due to capitalization industrial competition has increasingly intensified In order for many industries to survive and succeed they need to develop highly effective coordination between supply chain partners dynamic collaborative and strategic alliance relationships and efficient logistics and supply chain network designs Consequently in the past decade there has been an explosion of interest among academic researchers and industrial practitioners in innovative supply chain and logistics models algorithms and coordination policies Mathematically distinct from classical supply chain management this emerging research area has been proven to be useful and applicable to a wide variety of industries This book brings together recent advances in supply chain and logistics research and computational optimization that apply to a collaborative environment in the enterprise

Mathematical Aspects of Network Routing Optimization Carlos A.S. Oliveira, Panos M. Pardalos, 2011-08-26 Before the appearance of broadband links and wireless systems networks have been used to connect people in new ways Now the modern world is connected through large scale computational networked systems such as the Internet Because of the ever advancing technology of networking efficient algorithms have become increasingly necessary to solve some of the problems developing in this area Mathematical Aspects of Network Routing Optimization focuses on computational issues arising from the process of optimizing network routes such as quality of the resulting links and their reliability Algorithms are a cornerstone for the understanding of the protocols underlying multicast routing The main objective in the text is to derive efficient algorithms

with or without guarantee of approximation Notes have been provided for basic topics such as graph theory and linear programming to assist those who are not fully acquainted with the mathematical topics presented throughout the book Mathematical Aspects of Network Routing Optimization provides a thorough introduction to the subject of algorithms for network routing and focuses especially on multicast and wireless ad hoc systems This book is designed for graduate students researchers and professionals interested in understanding the algorithmic and mathematical ideas behind routing in computer networks It is suitable for advanced undergraduate students graduate students and researchers in the area of network algorithms Safety and Reliability in Cooperating Unmanned Aerial Systems Camille Alain Rabbath,N.

L[chevin,2010 Overview of recent advances in the analysis and design of health management systems for cooperating unmanned aerial vehicles Cooperative health management CHM systems seek to provide adaptation to the presence of faults by capitalizing on the availability of interconnected computing sensing and actuation resources Complements the proposed CHM concepts by means of case studies and application examples and presents fundamental principles and results encompassing optimization systems theory information theory dynamics modeling and simulation Microgrid Architectures, Control and Protection Methods Naser Mahdavi Tabatabaei,Ersan Kabalci,Nicu Bizon,2019-08-01 This book presents intuitive explanations of the principles of microgrids including their structure and operation and their applications It also discusses the latest research on microgrid control and protection technologies and the essentials of microgrids as well as enhanced communication systems The book provides solutions to microgrid operation and planning issues using various methodologies including planning and modelling AC and DC hybrid microgrids energy storage systems in microgrids and optimal microgrid operational planning Written by specialists it is filled in innovative solutions and research related to microgrid operation making it a valuable resource for those interested in developing updated approaches in electric power analysis design and operational strategies Thanks to its in depth explanations and clear three part structure it is useful for electrical engineering students researchers and technicians **Advances in Nature and Biologically Inspired**

Computing Nelishia Pillay,Andries P. Engelbrecht,Ajith Abraham,Mathys C. du Plessis,Václav Snášel,Azah Kamilah Muda,2015-12-01 World Congress on Nature and Biologically Inspired Computing NaBIC is organized to discuss the state of the art as well as to address various issues with respect to Nurturing Intelligent Computing Towards Advancement of Machine Intelligence This Volume contains the papers presented in the Seventh World Congress NaBIC 15 held in Pietermaritzburg South Africa during December 01 03 2015 The 39 papers presented in this Volume were carefully reviewed and selected The Volume would be a valuable reference to researchers students and practitioners in the computational intelligence field Advances in Human-Robot Interaction Vladimir Kulyukin,2009-12-01 Rapid advances in the field of robotics have made it possible to use robots not just in industrial automation but also in entertainment rehabilitation and home service Since robots will likely affect many aspects of human existence fundamental questions of human robot

interaction must be formulated and if at all possible resolved Some of these questions are addressed in this collection of papers by leading HRI researchers

Handbook of Research on Advanced Wireless Sensor Network Applications, Protocols, and Architectures Ray, Niranjana K.,Turuk, Ashok Kumar,2016-08-01 The implementation of wireless sensor networks has wide ranging applications for monitoring various physical and environmental settings However certain limitations with these technologies must be addressed in order to effectively utilize them The Handbook of Research on Advanced Wireless Sensor Network Applications Protocols and Architectures is a pivotal reference source for the latest research on recent innovations and developments in the field of wireless sensors Examining the advantages and challenges presented by the application of these networks in various areas this book is ideally designed for academics researchers students and IT developers

Safe Robot Navigation Among Moving and Steady Obstacles Andrey V. Savkin,Alexey S. Matveev,Michael Hoy,Chao Wang,2015-09-25 Safe Robot Navigation Among Moving and Steady Obstacles is the first book to focus on reactive navigation algorithms in unknown dynamic environments with moving and steady obstacles The first three chapters provide introduction and background on sliding mode control theory sensor models and vehicle kinematics Chapter 4 deals with the problem of optimal navigation in the presence of obstacles Chapter 5 discusses the problem of reactively navigating In Chapter 6 border patrolling algorithms are applied to a more general problem of reactively navigating A method for guidance of a Dubins like mobile robot is presented in Chapter 7 Chapter 8 introduces and studies a simple biologically inspired strategy for navigation a Dubins car Chapter 9 deals with a hard scenario where the environment of operation is cluttered with obstacles that may undergo arbitrary motions including rotations and deformations Chapter 10 presents a novel reactive algorithm for collision free navigation of a nonholonomic robot in unknown complex dynamic environments with moving obstacles Chapter 11 introduces and examines a novel purely reactive algorithm to navigate a planar mobile robot in densely cluttered environments with unpredictably moving and deforming obstacles Chapter 12 considers a multiple robot scenario For the Control and Automation Engineer this book offers accessible and precise development of important mathematical models and results All the presented results have mathematically rigorous proofs On the other hand the Engineer in Industry can benefit by the experiments with real robots such as Pioneer robots autonomous wheelchairs and autonomous mobile hospital First book on collision free reactive robot navigation in unknown dynamic environments Bridges the gap between mathematical model and practical algorithms Presents implementable and computationally efficient algorithms of robot navigation Includes mathematically rigorous proofs of their convergence A detailed review of existing reactive navigation algorithm for obstacle avoidance Describes fundamentals of sliding mode control

Structural Information and Communication Complexity Sergio Rajsbbaum,Alkida Balliu,Joshua J. Daymude,Dennis Olivetti,2023-05-24 This book constitutes the refereed proceedings of the 30th International Colloquium on Structural Information and Communication Complexity SIROCCO 2023 held in Alcal de Henares Spain during June 6 9 2023

The 26 full papers presented in this book were carefully reviewed and selected from 48 submissions SIROCCO is devoted to the study of the interplay between structural knowledge communication and computing in decentralized systems of multiple communicating entities Special emphasis is given to innovative approaches leading to better understanding of the relationship between computing and communication This is the 30th edition of SIROCCO and 3 of the 26 papers in this book are devoted to celebrating this fact plus an additional paper about a recent trend to study special models of computation

Mobile Computing Techniques in Emerging Markets: Systems, Applications and Services Kumar, A.V. Senthil,Rahman, Hakikur,2012-01-31 This book provides the latest research and best practices in the field of mobile computing offering theoretical and pragmatic viewpoints on mobile computing Provided by publisher *Pervasive Computing and Networking* Mohammad S. Obaidat,Mieso Denko,Isaac Woungang,2011-06-09 This book presents state of the art research on architectures algorithms protocols and applications in pervasive computing and networks With the widespread availability of wireless and mobile networking technologies and the expected convergence of ubiquitous computing with these emerging technologies in the near future pervasive computing and networking research and applications are among the hot topics on the agenda of researchers working on the next generation of mobile communications and networks This book provides a comprehensive guide to selected topics both ongoing and emerging in pervasive computing and networking It contains contributions from high profile researchers and is edited by leading experts in this field The main topics covered in the book include pervasive computing and systems pervasive networking security and pervasive networking and communication Key Features Discusses existing and emerging communications and computing models design architectures mobile and pervasive wireless applications technology and research challenges in pervasive computing systems networking and communications Provides detailed discussions of key research challenges and open research issues in the field of autonomic computing and networking Offers information on existing experimental studies including case studies implementation test beds in industry and academia Includes a set of PowerPoint slides for each chapter for instructors adopting it as a textbook *Pervasive Computing and Networking* will be an ideal reference for practitioners and researchers working in the areas of communication networking and pervasive computing and networking It also serves as an excellent textbook for graduate and senior undergraduate courses in computer science computer engineering electrical engineering software engineering and information engineering and science Unmanned Aerial Systems Anis Koubaa,Ahmad Taher Azar,2021-01-21 *Unmanned Aerial Systems* Theoretical Foundation and Applications presents some of the latest innovative approaches to drones from the point of view of dynamic modeling system analysis optimization control communications 3D mapping search and rescue surveillance farmland and construction monitoring and more With the emergence of low cost UAS a vast array of research works in academia and products in the industrial sectors have evolved The book covers the safe operation of UAS including but not limited to fundamental design mission and path planning control theory computer vision artificial intelligence

applications requirements and more This book provides a unique reference of the state of the art research and development of unmanned aerial systems making it an essential resource for researchers instructors and practitioners Covers some of the most innovative approaches to drones Provides the latest state of the art research and development surrounding unmanned aerial systems Presents a comprehensive reference on unmanned aerial systems with a focus on cutting edge technologies and recent research trends in the area

Technological Advancements and Applications in Mobile Ad-Hoc Networks: Research Trends Lakhtaria, Kamaljit I.,2012-03-31 Mobile ad hoc networks must be rapidly interoperable customizable and quick to adapt to the latest technological advances Technological Advancements and Applications in Mobile Ad Hoc Networks Research Trends offers a current look into the latest research in the field frameworks for development and future directions As mobile networks become more complex it is vital for researchers practitioners and academics alike to stay abreast within the ever burgeoning field With a wide range of applications theories and use across industrial commercial and domestic settings mobile ad hoc networks are a topic of vital discussion and this volume offers the cutting edge developments with contributions from around the world

Search and Classification Using Multiple Autonomous Vehicles Yue Wang,Islam I. Hussein,2012-04-02 Search and Classification Using Multiple Autonomous Vehicles provides a comprehensive study of decision making strategies for domain search and object classification using multiple autonomous vehicles MAV under both deterministic and probabilistic frameworks It serves as a first discussion of the problem of effective resource allocation using MAV with sensing limitations i e for search and classification missions over large scale domains or when there are far more objects to be found and classified than there are autonomous vehicles available Under such scenarios search and classification compete for limited sensing resources This is because search requires vehicle mobility while classification restricts the vehicles to the vicinity of any objects found The authors develop decision making strategies to choose between these competing tasks and vehicle motion control laws to achieve the proposed management scheme Deterministic Lyapunov based probabilistic Bayesian based and risk based decision making strategies and sensor management schemes are created in sequence Modeling and analysis include rigorous mathematical proofs of the proposed theorems and the practical consideration of limited sensing resources and observation costs A survey of the well developed coverage control problem is also provided as a foundation of search algorithms within the overall decision making strategies Applications in both underwater sampling and space situational awareness are investigated in detail The control strategies proposed in each chapter are followed by illustrative simulation results and analysis Academic researchers and graduate students from aerospace robotics mechanical or electrical engineering backgrounds interested in multi agent coordination and control in detection and estimation or in Bayes filtration will find this text of interest

Modular System Design and Evaluation Mark Sh. Levin,2014-09-06 This book examines seven key combinatorial engineering frameworks composite schemes consisting of algorithms and or interactive procedures for hierarchical modular composite systems These

frameworks are based on combinatorial optimization problems e.g knapsack problem multiple choice problem assignment problem morphological clique problem with the author's version of morphological design approach Hierarchical Morphological Multicriteria Design HMMD providing a conceptual lens with which to elucidate the examples discussed This approach is based on ordinal estimates of design alternatives for systems parts components however the book also puts forward an original version of HMMD that is based on new interval multiset estimates for the design alternatives with special attention paid to the aggregation of modular solutions system versions The second part of Modular System Design and Evaluation provides ten information technology case studies that enriches understanding of the design of system design detection of system bottlenecks and system improvement amongst others The book is intended for researchers and scientists students and practitioners in many domains of information technology and engineering The book is also designed to be used as a text for courses in system design systems engineering and life cycle engineering at the level of undergraduate level graduate PhD levels and for continuing education The material and methods contained in this book were used over four years in Moscow Institute of Physics and Technology State University in the author's faculty course System Design

Multi-Robot Systems. From Swarms to Intelligent Automata, Volume III Lynne E. Parker, Frank E. Schneider, Alan C. Schultz, 2005-08-15 This proceedings volume documents recent cutting edge developments in multi robot systems research This volume is the result of the Third International workshop on Multi Robot Systems that was held in March 2005 at the Naval Research Laboratory in Washington D C This workshop brought together top researchers working in areas relevant to designing teams of autonomous vehicles including robots and unmanned ground air surface and undersea vehicles The workshop focused on the challenging issues of team architectures vehicle learning and adaptation heterogeneous group control and cooperation task selection dynamic autonomy mixed initiative and human and robot team interaction A broad range of applications of this technology are presented in this volume including UCAVS Unmanned Combat Air Vehicles micro air vehicles UUVs Unmanned Underwater Vehicles UGVs Unmanned Ground vehicles planetary exploration assembly in space clean up and urban search and rescue This proceedings volume represents the contributions of the top researchers in this field and serves as a valuable tool for professionals in this interdisciplinary field **Proceedings of the Third International Conference on Contemporary Issues in Computer and Information Sciences (CICIS 2012)** , **Aerospace Robotics II** Jerzy Sasiadek, 2015-02-14 This book presents a selection of conference contributions from CARO 13 Conference on Aerospace Robotics which was held in Warsaw from July 1 to 3 2013 It presents the most important and crucial problems of space automation in context of future exploration programs These programs could involve such issues as space situational awareness program planetary protection exploitation of minerals assembly manufacturing and search for new habitable location for next human generations The future exploration of Space and related activities will involve robots In particular new autonomous robots need to be developed with high degree of intelligence Such robots would

make space exploration possible but also they would make space automation an important factor in variety of activities related to Space *Recent Progress in Robotics: Viable Robotic Service to Human* Sukhan Lee, Il Hong Suh, 2008-01-14 th

This volume is an edition of the papers selected from the 13 International Conference on Advanced Robotics ICAR 2007 held in Jeju Korea August 22-25 2007 with the theme Viable Robotics Service to Human It is intended to deliver readers the most recent technical progress in robotics in particular toward the advancement of robotic service to human To ensure its quality this volume took only 28 papers out of the 214 papers accepted for publication for ICAR 2007 The selection was based mainly on the technical merit but also took into consideration whether the subject represents a theme of current interest For the final inclusion authors of the selected papers were requested for another round of revision and expansion In this volume we organize the 28 contributions into three chapters Chapter 1 covers Novel Mechanisms Chapter 2 deals with perception guided navigation and manipulation and Chapter 3 addresses human robot interaction and intelligence Chapters 1 2 and 3 consist of 7 13 and 8 contributions respectively For the sake of clarity Chapter 2 is divided further into two parts with Part 1 for Perception Guided Navigation and Part 2 for Perception Guided Manipulation Chapter 3 is also divided into two parts with Part 1 for Human Robot Interaction and Part 2 for Intelligence For the convenience of readers a chapter summary is introduced as an overview in the beginning of each chapter The chapter summaries were prepared by Dr Munsang Kim for Chapter 1 Prof

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