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Henry S. Baird

The MIT Press

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Anne Condon

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Image Understanding Workshop ,1994   Handbook of Computational Geometry J.R. Sack,J. Urrutia,1999-12-13 Computational Geometry is an area that provides solutions to geometric problems which arise in applications including Geographic Information Systems Robotics and Computer Graphics This Handbook provides an overview of key concepts and results in Computational Geometry It may serve as a reference and study guide to the field Not only the most advanced methods or solutions are described but also many alternate ways of looking at problems and how to solve them   **The Computational Complexity of Machine Learning** Michael J. Kearns,1990 We also give algorithms for learning powerful concept classes under the uniform distribution and give equivalences between natural models of efficient learnability This thesis also includes detailed definitions and motivation for the distribution free model a chapter discussing past research in this model and related models and a short list of important open problems   **The Connection Machine** W. Daniel Hillis,1985 Describes a new kind of computer which involves parallel processing and hundreds of small microprocessors with individually integrated memories and discusses the LISP programming language data structures and storage allocation

The Rapid Evaluation of Potential Fields in Particle Systems Leslie Greengard,1988 The evaluation of Coulombic or gravitational interactions in large ensembles of particles is an integral part of the numerical simulation of a large number of physical processes Examples include celestial mechanics plasma physics the vortex method in fluid dynamics molecular dynamics molecular dynamics and the solution of the Laplace equation via potential theory A numerical model follows the trajectories of a number of particles moving in accordance with Newton s second law of motion in a field generated by the whole ensemble In many situations in order to be of physical interest the simulation has to involve thousands of particles or more and the fields have to be evaluated for a large number of configurations Unfortunately an amount of work of the order O N sg has traditionally been required to evaluate all pairwise interactions in a system of N particles unless some approximation or truncation method is used Large scale simulations have been extremely expensive in some cases and prohibitive in others An algorithm is presented for the rapid evaluation of the potential and force fields in large scale systems of particles To evaluate all pairwise Coulombic interactions of N particles to within round off error the algorithm requires an amount of work proportional to N and this estimate does not depend on the statistics of the distribution Both two and three dimensional versions of the algorithm have been constructed Applications to several problems in physics chemistry biology and numerical complex analysis are discussed   **Systems and Signal Processing** ,1991   Model-based Image Matching Using Location Henry S. Baird,1984 This work deals with the computer vision problem of recognizing and locating rigid shapes in the plane which have been subjected to unknown rotation scaling and noise The recognition task includes both locating the overall pattern and identifying each of its features Location is achieved by finding a geometric registration function that does a good job of superimposing the instance and the model Identifying the features requires matching each

model feature with the corresponding instance feature A pruned tree search algorithm is developed which makes effective use of the Soviet ellipsoid algorithm for feasibility of linear constraints An interesting blend of theoretical analysis and practical implementation shows that the resulting algorithm has an expected runtime that is theoretically asymptotically quadratic in the number of feature points but practically linear in n for patterns with fewer than 100 points Contents Introduction Task Abstraction Prior Approaches A Linear Programming Approach Geometry of Registrations and Ellipsoids Worst Case Number of Feasible Matchings Random Patterns Expected Cost of Feasibility Testing Expected Size of Search Tree Monte Carlo Trials Conclusions Henry S Baird received his doctorate from Princeton University He is currently a technical staff member et AT T Bell Laboratories Model Based Image Matching Using Location is a 1984 ACM Distinguished Dissertation   <u>Current Geographical Publications</u> University of Wisconsin--Milwaukee. Library,1986 Current Geographical Publications CGP is a non profit service to the scholarly community initiated in 1938 by the American Geographical Society of New York Beginning in 2006 the format changed to include the tables of contents of current geographical journals The journal titles listed link to web pages or PDF scans of the current issue s contents   **Algorithms for Robotic Motion and Manipulation** Jean-Paul Laumond,Mark Overmars,1997-02-11 This volume deals with core problems in robotics like motion planning sensor based planning manipulation and assembly planning It also discusses the application of robotics algorithms in other domains such as molecular modeling computer graphics and image analysis Topics Include Planning Sensor Based Motion Planning Control and Moti   *IEEE Proceedings of the Southeastcon* ,1991   **The Cumulative Book Index** ,1985 A world list of books in the English language   *Computational Models of Games* Anne Condon,1989 Computational Models of Games describes a model of two person games called a probabilistic game automaton that unifies other important models that have been developed to reflect the game like properties of computational problems   **A Geometric Investigation of Reach** James Urey Korein,1985 This book focuses on a problem of fundamental importance in the robotics field that of manipulating a geometric linkage resembling a human arm or leg with the intent of reaching specific points in space Many analytic and numerical solutions have been developed for robot manipulators Recently a number of researchers have begun to investigate methods for the generation of manipulator workspaces sometimes called reach envelopes This work offers two new solutions to the reach problem an analytic solution for the special case of singly redundant chains of the type exemplified by human arms and legs and a solution for chains of arbitrary length which makes use of workspace descriptions An algorithm is also developed for the approximation of workspaces by polyhedra leading to an examination of the problem of sweeping polyhedra through space Contents Introduction Body Model Joint Adjustment and Limitations Overview of the Cartesian Positioning Problem Analytic Positioning Methods Numerical Optimization Methods Reach Hierarchy Methods Workspace Generation Sweeping Polyhedra Conclusions The Modelling System James U Korein received his doctorate from the University of Pennsylvania He is currently a researcher at IBM Thomas J Watson Research Center Yorktown Heights NY

A Geometric Investigation of Reach is a 1984 ACM Distinguished Dissertation   *Two Issues in Public Key Cryptography* Ben-Zion Chor,1986 This book explores public key cryptographic systems first investigating the question of cryptographic security of bits in the RSA encryption and then constructing a new knapsack type public key cryptosystem based on arithmetic in finite fields In Part I two problems involving the RSA encryption of a message are proved to be equivalent This equivalence implies that an adversary given the ciphertext can t do better than guessing unless s he can break the RSA code The results generated by the author s proof indicate that Rabin RSA encryption can be directly used for pseudo random bit generation A new knapsack type public key cryptosystem is introduced in Part II along with a detailed description of its implementation The system is based on a novel application of arithmetic in finite fields following a construction by Bose and Chowla By choosing appropriate parameters the density of the resulting knapsack can be controlled In particular the density can be made high enough to foil low density attacks against this new system At present there are no known attacks capable of breaking the system in a reasonable amount of time Ben Zion Chor received his doctorate from MIT where he is currently a Post Doctoral Fellow in the Computer Science Laboratory Two Issues in Public Key Cryptography RSA Bit Security and a New Knapsack Type Systemis a 1985 ACM Distinguished Dissertation   **Uses of Randomness in Algorithms and Protocols** Joe Kilian,1990 Uses of Randomness in Algorithms and Protocolsmakes fundamental contributions to two different fields of complexity theory computational number theory and cryptography The most famous result is Goldwasser and Kilian s invention of a new approach to distinguish prime numbers from composites using methods from the theory of elliptic curves over finite fields The Goldwasser Kilian algorithm is the first to yield a polynomial size proof of its assertions ensuring correctness while still provably running fast on most inputs This new primality test implies for the first time and without any assumptions that large certified primes can be generated in expected polynomial time under a distribution that is close to uniform It provides a provocative new link between algebraic geometry and primality testing one of the most ancient algorithmic problems in number theory Heuristic implementations of the algorithm are currently considered to be the fastest existing methods to certify primes Kilian also provides two elegant and original contributions to theoretical cryptography He shows how to base general two party protocols on a simple protocol known as oblivious transfer proving the first completeness result of this kind He also introduces a generalization of interactive proof systems known as multi prover interactive proof systems and shows that anything provable in this model is provable in zero knowledge Joe Kilian is a National Science Foundation Postdoctoral Fellow at MIT and Harvard Contents Introduction New Techniques in Primality Testing Committing Bits Using Oblivious Transfer Circuit Evaluation Using Oblivious Transfer The NC1 Circuit Base Oblivious Evaluation of Arbitrary Circuits Interactive Proof Systems with Multiple Provers   **Digital Imaging for Cultural Heritage Preservation** Filippo Stanco,Sebastiano Battiato,Giovanni Gallo,2017-12-19 This edition presents the most prominent topics and applications of digital image processing analysis and computer graphics in the field of cultural heritage

preservation The text assumes prior knowledge of digital image processing and computer graphics fundamentals Each chapter contains a table of contents illustrations and figures that elucidate the presented concepts in detail as well as a chapter summary and a bibliography for further reading Well known experts cover a wide range of topics and related applications including spectral imaging automated restoration computational reconstruction digital reproduction and 3D models *The Design and Evaluation of a High Performance Smalltalk System* David Michael Ungar,1987 This project was sponsored by Defense Advance Research Projects Agency DoD ARPA Order No 3803 monitored by Naval Electronic System Command under Contractor No N00034 R 0251 It was also sponsored by Defense Advance Research Projects Agency DoD ARPA Order No 4871 monitored by Naval Electronic Systems Command under Contract No N00039 84 C 0089 **The Power of Interaction** Carsten Lund,1992 The Power of Interaction presents a new algebraic technique for constructing interactive proof systems and demonstrates the immense power of randomization and interaction in proving statements efficiently Lund shows that two provers can interact with a randomized verifier to provide proofs that are exponentially more efficient than traditional proofs and that one prover can interact with an efficient randomized verifier to prove statements that have no known efficient traditional proofs Carsten Lund is a Postdoctoral Fellow at AT T Bell Laboratories **All the Right Moves** Carl Ebeling,1987 All the Right Moves presents a parallel architecture that makes this tradeoff irrelevant using the VLSI architecture described in this book the Hitech chess program is able to search both quickly and knowledgeably Arts and Technology Fay Huang,Reen-Cheng Wang,2010-01-13 We welcome you to the First International Conference on Arts and Technology ArtsIT 2009 hosted by CSIE of the National Ilan University and co organized by the National Science Council ICST College of EECS at National Ilan University Software Simulation Society in Taiwan ISAC TCA NCHC CREATE NET and Institute for Information Industry ArtsIT2009 was held in Yilan Taiwan during September 24 25 2009 The conference comprised the following themes New Media Technologies Evolutionary systems that create arts or display art works such as tracking sensors wearable computers mixed reality etc Software Art Image processing or computer graphics techniques that create arts including algorithmic art mathematic art advanced modeling and rend ing etc Animation Techniques 2D or 3D computer animations AI based animations etc Multimedia Integration of different media such as virtual reality systems audio performing arts etc Interactive Methods Vision based tracking and recognition interactive art etc The conference program started with an opening ceremony followed by three keynote speeches and four technical sessions distributed over a period of two days Two poster sessions one hour each were scheduled before the afternoon oral sessions An Int active Arts Exhibition was held in conjunction with ArtsIT 2009 Twelve well known digital arts teams from Taiwan exhibited 15 artworks in this event including 10 int active installation arts 4 video arts and 1 digital print The conference received around 50 submissions from 15 different countries

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