

Joachim Baumann

Mobile Agents: Control Algorithms



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Mobile Agents Control Algorithms

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Mobile Agents Control Algorithms:

Mobile Agents: Control Algorithms Joachim Baumann, 2006-12-31 In this monograph Joachim Baumann provides in depth coverage of essential research issues namely mechanisms for locating and terminating mobile agents and for orphan detection in a mobile agent system The reader will gain insights into the design and implementation of three control mechanisms for use in mobile agent systems the energy concept the path concept and the shadow concept The author examines these mechanisms and offers a solid argument as to why they would be better choices over existing mechanisms with respect to message complexity migration delay and availability All in all this book is an outstanding contribution to advancing the science of mobile agents and it will help the community better understand how to tame mobile agents

Mobile Agents Joachim Baumann, 2014-01-15

Control Algorithms for Mobile Agents Joachim Baumann, 1999

Mobile Agents Gian P. Picco, 2003-06-30 Recent years have witnessed the appearance of new paradigms for designing distributed applications where the application components can be relocated dynamically across the hosts of the network This form of code mobility lays the foundation for a new generation of technologies architectures models and applications in which the location at which the code is executed comes under the control of the designer rather than simply being a configuration accident Among the various flavors of mobile code the mobile agent paradigm has become particularly popular Mobile agents are programs able to determine autonomously their own migration to a different host and still retain their code and state or at least a portion thereof Thus distributed computations do not necessarily unfold as a sequence of requests and replies between clients and remote servers rather they encompass one or more visits of one or more mobile agents to the nodes involved Mobile code and mobile agents hold the potential to shape the next generation of technologies and models for distributed computation The first steps of this process are already evident today Web applets provide a case for the least sophisticated form of mobile code Java based distributed middleware makes increasing use of mobile code and the first commercial applications using mobile agents are starting to appear Mobile Agents Peter Braun, Wilhelm R.

Rossak, 2005-01-21 Mobile agents are software nomads that act as your personal representative working autonomously through networks They are able to visit network nodes directly using available computing power and are not limited by platform This emerging field is now poised to become a cornerstone for new Web based ubiquitous computing environments Mobile Agents provides a practical introduction to mobile agent technology and surveys the state of the art in mobile agent research Students and researchers can use the book as an introduction to the concepts and possibilities of this field and as an overview of ongoing research Developers can use it to identify the capabilities of the technology to decide if mobile agents are the right solution for them Practitioners can also gain hands on experience in programming mobile agents through exploration of the source code for a complete mobile agent environment available through the companion website Summarizes the state of the art in mobile agent research Identifies the benefits and limitations of current mobile agent

technology to help developers understand the possibilities of this new field Extensive mobile agents web portal www.mobileagents.org with the Java source code for a complete industrial quality environment for mobile agents with significant parts of the system open source *Software Agents for Future Communication Systems* Alex Hayzelden, John Bigham, 2012-12-06 Agent technology has recently become one of the most vibrant and fastest growing areas in information technology And advanced digital communication is a central enabling technology for the coming information society So software agents and their exploitation for future communication systems are attracting particular attention from the research and development community as well as from economic and user communities interested in everyday private and professional digital communication applications This monograph like anthology is the first systematic introduction to software agents and future communication systems Fifteen coherently written chapters by leading software agent researchers provide complementary coverage of the relevant issues Multi agent systems and mobile agent approaches are presented in a well balanced way and applied to most important topics in future communication systems In addition the volume editors have provided a detailed introductory survey chapters

Networked Control Systems Fei-Yue Wang, Derong Liu, 2008-06-17 Networked control systems NCS confer advantages of cost reduction system diagnosis and flexibility minimizing wiring and simplifying the addition and replacement of individual elements efficient data sharing makes taking globally intelligent control decisions easier with NCS The applications of NCS range from the large scale of factory automation and plant monitoring to the smaller networks of computers in modern cars places and autonomous robots Networked Control Systems presents recent results in stability and robustness analysis and new developments related to networked fuzzy and optimal control Many chapters contain case studies experimental simulation or other application related work showing how the theories put forward can be implemented The state of the art research reported in this volume by an international team of contributors makes it an essential reference for researchers and postgraduate students in control electrical computer and mechanical engineering and computer science

Security Modeling and Analysis of Mobile Agent Systems Lu Ma, Jeffrey J.-P. Tsai, 2006 A mobile agent system could be attacked by malicious agents platforms and third parties Mobile agents simply offer greater opportunities for abuse and misuse which broadens the scale of threats significantly In addition since mobile agents have some unique characteristics such as their mobility security problems have become more complicated in these systems These security problems have become a bottleneck in the development and maintenance of mobile agent systems especially in security sensitive applications such as electronic commerce This book introduces the concept and structure of mobile agent systems and discusses various attacks and countermeasures The emphasis is on the formal modeling and analysis of secure mobile agent systems and their applications

Sample Chapter s Chapter 1 Introduction 97 KB Contents Mobile Agent System Attacks and Countermeasures of Software System Security Security Issues in a Mobile Agent System A New Formal Model OCo Extended Elementary Object System EEOS A Formal Framework of a Generic Secure Mobile Agent System Based on

EEOS Translating the EEOS Model to Colored Petri Net Model Simulation and Analysis of the Extended Elementary Object System Model of a Secure Mobile Agent System A Case Study in Electronic Commerce A Case Study in E Auction System
 Readership Computer scientists researchers software engineers programmers and graduate students in software engineering networking and automated systems *Multi-Agent Systems and Agreement Technologies* Michael Rovatsos, George Vouros, Vicente Julian, 2016-04-16 This book constitutes the revised selected papers from the 13 European Conference on Multi Agent Systems EUMAS 2015 and the Third International Conference on Agreement Technologies AT 2015 held in Athens Greece in December 2015 The 36 papers presented in this volume were carefully reviewed and selected from 65 submissions They are organized in topical sections named coordination and planning learning and optimization argumentation and negotiation norms trust and reputation agent based simulation and agent programming Modelling Future Telecommunications Systems P. Cochrane, David J.T. Heatley, 2012-12-06 Telecommunications today is in the midst of far reaching changes due to rapid development of new technologies services and social evolution This is the first book to model the process of change in telecommunications including all of the relevant factors The approach is practical and responsible based on hard facts and tested models It deals with fundamental issues affecting the future development of telecoms and its impact on societies and presents views which some will find radical *Mobile Agents in Networking and Distributed Computing* Jiannong Cao, Sajal Kumar Das, 2012-07-31 The book focuses on mobile agents which are computer programs that can autonomously migrate between network sites This text introduces the concepts and principles of mobile agents provides an overview of mobile agent technology and focuses on applications in networking and distributed computing **Cooperative Event-Based Control of Mobile Agents** Michael Schwung, 2022-06-01 This thesis proposes a method that plans trajectories for autonomous agents to enable them to fulfil different tasks while ensuring the collision free movement The agents are locally controlled and connected over an unreliable communication network that may induce packet losses and transmission delays Further sensors e g for a distance measurement are not used and communication should only be invoked if it is necessary to avoid a collision The basic problem occurs for two agents The first agent can change its trajectory at any time without regard to the second agent which has to ensure the collision avoidance To this aim it adapts its trajectory based only on local data and communicated information about the current and future movement of the first agent A control unit for the second agent is introduced that has to execute four tasks to ensure the control aims 1 Estimation of the current network properties 2 Prediction of the movement of the stand on agent 3 Invocation of communication whenever the local data becomes too uncertain 4 Planning of collision avoiding trajectories The main result of the thesis is a novel control method for mobile agents that solves the four tasks leading to a proven collision avoidance The method consists of a delay estimator a prediction unit an event generator and a trajectory planning unit The method can be used for different types of agents e g UAVs or cars with only slight modifications The proposed method is tested and

evaluated through simulations and experiments with both two quadrotors and two nonholonomic robots

Agent and Multi-Agent Systems: Technologies and Applications Anne Hakansson, Ronald Hartung, 2009-05-25 This book constitutes the proceedings of the Third International Symposium on Agent and Multi Agent Systems Technologies and Applications held in Uppsala Sweden during June 3 5 2009 The 86 papers contained in this volume were carefully reviewed and selected from numerous submissions There are 13 main tracks covering the methodology and applications of agent and multi agent systems and 8 special sessions on specific topics within the field The papers are divided in topical sections on social and organizational structures of agents negotiation protocols mobile agents and robots agent design and implementation e commerce simulation systems and game systems agent systems and ontologies agents for network systems communication and agent learning systems Web services and semantic Web self organization in multi agent systems management and e business mobile and intelligent agents for networks and services engineering interaction protocols agent based simulation decision making and systems optimization digital economy agent based optimization ABO2009 distributed systems and artificial intelligence applications

Bio-Inspired Self-Organizing Robotic Systems Yan Meng, Yaochu Jin, 2011-05-08 Self organizing approaches inspired from biological systems such as social insects genetic molecular and cellular systems under morphogenesis and human mental development has enjoyed great success in advanced robotic systems that need to work in dynamic and changing environments Compared with classical control methods for robotic systems the major advantages of bio inspired self organizing robotic systems include robustness self repair and self healing in the presence of system failures and or malfunctions high adaptability to environmental changes and autonomous self organization and self reconfiguration without a centralized control Bio inspired Self organizing Robotic Systems provides a valuable reference for scientists practitioners and research students working on developing control algorithms for self organizing engineered collective systems such as swarm robotic systems self reconfigurable modular robots smart material based robotic devices unmanned aerial vehicles and satellite constellations

Software Agent-Based Applications, Platforms and Development Kits Rainer Unland, Matthias Klusch, Monique Calisti, 2006-01-27 This book introduces major agent platforms frameworks systems tools and applications Each system is described by their developers in sufficient detail so that the reader can get a good understanding of the architecture functionality and application areas of the system All systems are running systems One main focus of the book lies on agent platforms and toolkits

Proceedings of the Fourth International Network Conference 2004 (INC2004) Steven Furnell, Paul Dowland, 2004

Mobile Agents Niranjan Suri, 2003-06-30 Welcome to the proceedings of the 6th IEEE International Conference on Mobile Agents MA 2002 took place in Barcelona Spain and was co located with the 4th International Workshop on Mobile Agents for Telecommunications Applications Both events were held at the Universitat Pompeu Fabra October 22 25 2002 Mobile agents may be defined as programs that with varying degree of autonomy can move between hosts across a network Mobile agents combine the notions of mobile code mobile computation and

mobile state Capabilities of mobile agents include Supporting unreliable networks and disconnected operation Counteracting low bandwidth high latency communication links Deploying newbehaviour through mobile code and recon guring systems on the y Distributing processing load across systems Improving survivability in the face of network and system failure Given the above capabilities mobile agents while they may not be referred to as such are nowbecoming accepted as a fundamental architectural construct for the design and development of complex adaptive systems that need to operate in highly dynamic environments Mobile agents also support applications in several domains such as ubiquitous computing grid computing remote sensing data mining system management and agile computing

Transactions on Computational Collective Intelligence XVIII Ngoc Thanh Nguyen,2015-07-30 These transactions publish research in computer based methods of computational collective intelligence CCI and their applications in a wide range of fields such as the semantic Web social networks and multi agent systems TCCI strives to cover new methodological theoretical and practical aspects of CCI understood as the form of intelligence that emerges from the collaboration and competition of many individuals artificial and or natural The application of multiple computational intelligence technologies such as fuzzy systems evolutionary computation neural systems consensus theory etc aims to support human and other collective intelligence and to create new forms of CCI in natural and or artificial systems This eighteenth issue contains 9 carefully selected and revised contributions

Multi-Agent Systems Vladimir Shikhin,2019-03-06 This book integrates the practices of enthusiastic investigators in the field of MAS based approaches elaboration and implementation The content of the book identifies the most complicated tasks and their possible solutions while implementing MAS instrumentation into engineering practice The proposed focus on the control problems involves a wide range of adjacent problems described in the chapters of the book Material presented in the book aim to provide the basic knowledge for further MAS systems study and control design to reach the goals and needs coming from engineering practice under often contradictory existing requirements

Marine Navigation and Safety of Sea Transportation Adam Weintrit,2009-06-02 In recent years much attention has been paid to safety of navigation and marine transportation Marine Navigation and Safety of Sea Transportation addresses the main aspects of marine safety including safety of navigation manoeuvring and ship handling systems marine traffic control and automatic identification systems navigation tools system

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Table of Contents Mobile Agents Control Algorithms

1. Understanding the eBook Mobile Agents Control Algorithms
 - The Rise of Digital Reading Mobile Agents Control Algorithms
 - Advantages of eBooks Over Traditional Books
2. Identifying Mobile Agents Control Algorithms
 - Exploring Different Genres
 - Considering Fiction vs. Non-Fiction
 - Determining Your Reading Goals
3. Choosing the Right eBook Platform
 - Popular eBook Platforms
 - Features to Look for in an Mobile Agents Control Algorithms
 - User-Friendly Interface
4. Exploring eBook Recommendations from Mobile Agents Control Algorithms
 - Personalized Recommendations
 - Mobile Agents Control Algorithms User Reviews and Ratings
 - Mobile Agents Control Algorithms and Bestseller Lists
5. Accessing Mobile Agents Control Algorithms Free and Paid eBooks
 - Mobile Agents Control Algorithms Public Domain eBooks

- Mobile Agents Control Algorithms eBook Subscription Services
- Mobile Agents Control Algorithms Budget-Friendly Options
- 6. Navigating Mobile Agents Control Algorithms eBook Formats
 - ePub, PDF, MOBI, and More
 - Mobile Agents Control Algorithms Compatibility with Devices
 - Mobile Agents Control Algorithms Enhanced eBook Features
- 7. Enhancing Your Reading Experience
 - Adjustable Fonts and Text Sizes of Mobile Agents Control Algorithms
 - Highlighting and Note-Taking Mobile Agents Control Algorithms
 - Interactive Elements Mobile Agents Control Algorithms
- 8. Staying Engaged with Mobile Agents Control Algorithms
 - Joining Online Reading Communities
 - Participating in Virtual Book Clubs
 - Following Authors and Publishers Mobile Agents Control Algorithms
- 9. Balancing eBooks and Physical Books Mobile Agents Control Algorithms
 - Benefits of a Digital Library
 - Creating a Diverse Reading Collection Mobile Agents Control Algorithms
- 10. Overcoming Reading Challenges
 - Dealing with Digital Eye Strain
 - Minimizing Distractions
 - Managing Screen Time
- 11. Cultivating a Reading Routine Mobile Agents Control Algorithms
 - Setting Reading Goals Mobile Agents Control Algorithms
 - Carving Out Dedicated Reading Time
- 12. Sourcing Reliable Information of Mobile Agents Control Algorithms
 - Fact-Checking eBook Content of Mobile Agents Control Algorithms
 - Distinguishing Credible Sources
- 13. Promoting Lifelong Learning
 - Utilizing eBooks for Skill Development
 - Exploring Educational eBooks

14. Embracing eBook Trends

- Integration of Multimedia Elements
- Interactive and Gamified eBooks

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