

CONTROL AND SYSTEMS THEORY

VOLUME 2

Parameter Estimation

Principles and Problems

Harold W. Sorenson



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L Darling-Hammond



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Algebraic Identification and Estimation Methods in Feedback Control Systems Hebertt Sira-Ramírez, Carlos García Rodríguez, John Cortés Romero, Alberto Luviano Juárez, 2014-03-13 Algebraic Identification and Estimation Methods in Feedback Control Systems presents a model based algebraic approach to online parameter and state estimation in uncertain dynamic feedback control systems This approach evades the mathematical intricacies of the traditional stochastic approach proposing a direct model based scheme with several easy to implement computational advantages The approach can be used with continuous and discrete linear and nonlinear mono variable and multi variable systems The estimators based on this approach are not of asymptotic nature and do not require any statistical knowledge of the corrupting noises to achieve good performance in a noisy environment These estimators are fast robust to structured perturbations and easy to combine with classical or sophisticated control laws This book uses module theory differential algebra and operational calculus in an easy to understand manner and also details how to apply these in the context of feedback control systems A wide variety of examples including mechanical systems power converters electric motors and chaotic systems are also included to illustrate the algebraic methodology Key features Presents a radically new approach to online parameter and state estimation Enables the reader to master the use and understand the consequences of the highly theoretical differential algebraic viewpoint in control systems theory Includes examples in a variety of physical applications with experimental results Covers the latest developments and applications Algebraic Identification and Estimation Methods in Feedback Control Systems is a comprehensive reference for researchers and practitioners working in the area of automatic control and is also a useful source of information for graduate and undergraduate students OracIs Ernest S. Armstrong, 2020-11-25 This book describes a computational system for designing linear feedback control laws and filters for linear time variant multivariable differential or difference equation state vector models It presents numerical examples to illustrate the use of ORACLS to solve selected design problems *Brain Signals* Risto J. Ilmoniemi, Jukka Sarvas, 2019-05-28 A unified treatment of the generation and analysis of brain generated electromagnetic fields In Brain Signals Risto Ilmoniemi and Jukka Sarvas present the basic physical and mathematical principles of magnetoencephalography MEG and electroencephalography EEG describing what kind of information is available in the neuroelectromagnetic field and how the measured MEG and EEG signals can be analyzed Unlike most previous works on these topics which have been collections of writings by different authors using different conventions this book presents the material in a unified manner providing the reader with a thorough understanding of basic principles and a firm basis for analyzing data generated by MEG and EEG The book first provides a brief introduction to brain states and the early history of EEG and MEG describes the generation of electromagnetic fields by neuronal activity and discusses the electromagnetic forward problem The authors then turn to EEG and MEG analysis offering a review of linear and matrix algebra and basic statistics needed for analysis of the data and presenting several

analysis methods dipole fitting the minimum norm estimate MNE beamforming the multiple signal classification algorithm MUSIC including RAP MUSIC with the RAP dilemma and TRAP MUSIC which removes the RAP dilemma independent component analysis ICA and blind source separation BSS with joint diagonalization New Developments in Biomedical Engineering Domenico Campolo, 2010-01-01 Biomedical Engineering is a highly interdisciplinary and well established discipline spanning across engineering medicine and biology A single definition of Biomedical Engineering is hardly unanimously accepted but it is often easier to identify what activities are included in it This volume collects works on recent advances in Biomedical Engineering and provides a bird view on a very broad field ranging from purely theoretical frameworks to clinical applications and from diagnosis to treatment *Principles of Dynamic Programming* Robert Edward Larson, J. L. Casti, 1978 APCCAS ..., 2002 *System Identification* Rik Pintelon, Johan Schoukens, 2004-03-22 Electrical Engineering System Identification A Frequency Domain Approach How does one model a linear dynamic system from noisy data This book presents a general approach to this problem with both practical examples and theoretical discussions that give the reader a sound understanding of the subject and of the pitfalls that might occur on the road from raw data to validated model The emphasis is on robust methods that can be used with a minimum of user interaction Readers in many fields of engineering will gain knowledge about Choice of experimental setup and experiment design Automatic characterization of disturbing noise Generation of a good plant model Detection qualification and quantification of nonlinear distortions Identification of continuous and discrete time models Improved model validation tools and from the theoretical side about System identification Interrelations between time and frequency domain approaches Stochastic properties of the estimators Stochastic analysis System Identification A Frequency Domain Approach is written for practicing engineers and scientists who do not want to delve into mathematical details of proofs Also it is written for researchers who wish to learn more about the theoretical aspects of the proofs Several of the introductory chapters are suitable for undergraduates Each chapter begins with an abstract and ends with exercises and examples are given throughout **Failure Diagnosis and Performance Monitoring** Louis-François Pau, 1981 Mastering System Identification in 100 Exercises Johan Schoukens, Rik Pintelon, Yves Rolain, 2012-04-02 This book enables readers to understand system identification and linear system modeling through 100 practical exercises without requiring complex theoretical knowledge The contents encompass state of the art system identification methods with both time and frequency domain system identification methods covered including the pros and cons of each Each chapter features MATLAB exercises discussions of the exercises accompanying MATLAB downloads and larger projects that serve as potential assignments in this learn by doing resource *Report - Hydrodynamics Laboratory, Massachusetts Institute of Technology* Massachusetts Institute of Technology. Hydrodynamics Laboratory, 1984-10 *International Symposium on Computer Vision*, 1995 *Subject Guide to Books in Print*, 1997

Non-Smooth and Complementarity-Based Distributed Parameter Systems Michael Hintermüller, Roland

Herzog,Christian Kanzow,Michael Ulbrich,Stefan Ulbrich,2022-02-18 Many of the most challenging problems in the applied sciences involve non differentiable structures as well as partial differential operators thus leading to non smooth distributed parameter systems This edited volume aims to establish a theoretical and numerical foundation and develop new algorithmic paradigms for the treatment of non smooth phenomena and associated parameter influences Other goals include the realization and further advancement of these concepts in the context of robust and hierarchical optimization partial differential games and nonlinear partial differential complementarity problems as well as their validation in the context of complex applications Areas for which applications are considered include optimal control of multiphase fluids and of superconductors image processing thermoforming and the formation of rivers and networks Chapters are written by leading researchers and present results obtained in the first funding phase of the DFG Special Priority Program on Nonsmooth and Complementarity Based Distributed Parameter Systems Simulation and Hierarchical Optimization that ran from 2016 to 2019

Advances in Control Systems C. T. Leondes,2014-12-01 Advances in Control Systems Theory and Applications Volume 1 provides information pertinent to the significant progress in the field of automatic control This book presents several fundamental approaches to algorithms for the determination of optimum control inputs to a system Organized into six chapters this volume begins with an overview of the optimal method of controlling a given system with respect to the given criterion of performance This text then summarizes some of the basic results of the maximum principle and illustrates how they may be exploited in control system studies Other chapters consider the fundamental approach underlying almost all the existing works on the control of distributed parameter systems This book discusses as well some important concepts in the theory of optimal control The final chapter deals with the problem of controlling processes under the condition of uncertain changes in the process to be controlled This book is a valuable resource for practicing engineers applied mathematicians and scientists Scientific and Technical Aerospace Reports ,1994 Identifiability and Observability in Epidemiological

Models Nik Cuniffe,Frédéric Hamelin,Abderrahman Iggidr,Alain Rapaport,Gauthier Sallet,2024-07-02 This book introduces the concepts of identifiability and observability in mathematical epidemiology as well as those of observers constructions It first exposes and illustrates on several examples the mathematical definitions and properties of observability and identifiability A chapter is dedicated to the well known Kermack McKendrick model for which the complete analysis of identifiability and observability is not available in the literature Then several techniques of observer constructions in view of online estimation of state and parameters are presented and deployed on several models New developments relevant for applications in epidemiology are also given Finally practical considerations are discussed with data and numerical simulations related to models previously analysed in the book The book will be appealing to epidemiological modellers and mathematicians working on models in epidemiology This book contributes to Sustainable Development Goal 3 SDG3 Good Health and Well Being **Advances in State and Parameter Estimation** Jitendra R. Raol,Parimala P.,Reshma V.,Sara M.

George, 2025-05-27 This book deals with the basics of parameter estimation and state estimation as the fundamental building blocks of mathematical modelling activity in the broader field of control theory All the methods are validated using MATLAB based implementations with realistically simulated data for general dynamic systems as well as for aircraft parameter estimation This book includes several illustrative examples and chapter end exercises Features Provides comprehensive coverage of all issues related to parameter and state estimation Discusses advanced topics related to Kalman filter stability analysis image centroid tracking and neural networks for parameter estimation Explores convergence and stability results for the discussed methods Reviews the estimation of parameters in linear nonlinear models and distributed fitting Includes MATLAB based illustrative examples and exercises This book is aimed at researchers and graduate students in systems and control signal processing estimation theory engineering mathematics and aerospace engineering **Technology for Large Space Systems**, 1983 **Applied Mechanics Reviews**, 1967 *Nonlinear Digital Filters* Ioannis Pitas, Anastasios N. Venetsanopoulos, 2013-03-14 The function of a filter is to transform a signal into another one more suitable for a given purpose As such filters find applications in telecommunications radar sonar remote sensing geophysical signal processing image processing and computer vision Numerous authors have considered deterministic and statistical approaches for the study of passive active digital multidimensional and adaptive filters Most of the filters considered were linear although the theory of nonlinear filters is developing rapidly as it is evident by the numerous research papers and a few specialized monographs now available Our research interests in this area created opportunity for cooperation and co authored publications during the past few years in many nonlinear filter families described in this book As a result of this cooperation and a visit from John Pitas on a research leave at the University of Toronto in September 1988 the idea for this book was first conceived The difficulty in writing such a monograph was that the area seemed fragmented and no general theory was available to encompass the many different kinds of filters presented in the literature However the similarities of some families of nonlinear filters and the need for such a monograph providing a broad overview of the whole area made the project worthwhile The result is the book now in your hands typeset at the Department of Electrical Engineering of the University of Toronto during the summer of 1989

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