power systems

F. Khorrami P. Krishnamurthy · H. Melkote

Modeling and Adaptive Nonlinear Control of Electric Motors



Modeling And Adaptive Nonlinear Control Of Electric Motors

Patricia Melin

Modeling And Adaptive Nonlinear Control Of Electric Motors:

Modeling and Adaptive Nonlinear Control of Electric Motors Farshad Khorrami, Prashanth Krishnamurthy, Hemant Melkote, 2003-05-21 In this book modeling and control design of electric motors namely step motors brushless DC motors and induction motors are considered. The book focuses on recent advances on feedback control designs for various types of electric motors with a slight emphasis on stepper motors For this purpose the authors explore modeling of these devices to the extent needed to provide a high performance controller but at the same time one amenable to model based nonlinear designs The control designs focus primarily on recent robust adaptive nonlinear controllers to attain high performance It is shown that the adaptive robust nonlinear controller on its own achieves reasonably good performance without requiring the exact knowledge of motor parameters While carefully tuned classical controllers often achieve required performance in many applications it is hoped that the advocated robust and adaptive designs will lead to standard universal controllers with minimal need for fine tuning of control parameters **AC Electric Motors Control** Fouad Giri, 2013-03-25 The complexity of AC motor control lies in the multivariable and nonlinear nature of AC machine dynamics Recent advancements in control theory now make it possible to deal with long standing problems in AC motors control This text expertly draws on these developments to apply a wide range of model based control designmethods to a variety of AC motors Contributions from over thirty top researchers explain how modern control design methods can be used to achieve tight speed regulation optimal energetic efficiency and operation reliability and safety by considering online state variable estimation in the absence of mechanical sensors power factor correction machine flux optimization fault detection and isolation and fault tolerant control Describing the complete control approach both controller and observer designs are demonstrated using advanced nonlinear methods stability and performance are analysed using powerful techniques including implementation considerations using digital computing means Other key features Covers the main types of AC motors including triphase multiphase and doubly fed induction motors wound rotor permanent magnet and interior PM synchronous motors Illustrates the usefulness of the advanced control methods via industrial applications including electric vehicles high speed trains steel mills and more Includes special focus on sensorless nonlinear observers adaptive and robust nonlinear controllers output feedback controllers fault detection and isolation algorithms and fault tolerant controllers This comprehensive volume provides researchers and designers and R D engineers with a single source reference on AC motor system drives in the automotive and transportation industry It will also appeal to advanced students in automatic control electrical power systems mechanical engineering and robotics as well as mechatronic process and applied control system engineers *Induction Motor Control* Design Riccardo Marino, Patrizio Tomei, Cristiano M. Verrelli, 2010-08-20 This book provides the most important steps and concerns in the design of estimation and control algorithms for induction motors A single notation and modern nonlinear control terminology is used to make the book accessible although a more theoretical control viewpoint is also given Focusing

on the induction motor with the concepts of stability and nonlinear control theory given in appendices this book covers speed sensorless control design of adaptive observers and parameter estimators a discussion of nonlinear adaptive controls containing parameter estimation algorithms and comparative simulations of different control algorithms. The book sets out basic assumptions structural properties modelling state feedback control and estimation algorithms then moves to more complex output feedback control algorithms based on stator current measurements and modelling for speed sensorless control The induction motor exhibits many typical and unavoidable nonlinear features **Vector Control of Three-Phase AC Machines** Nguyen Phung Quang, Jörg-Andreas Dittrich, 2015-05-14 This book addresses the vector control of three phase AC machines in particular induction motors with squirrel cage rotors IM permanent magnet synchronous motors PMSM and doubly fed induction machines DFIM from a practical design and development perspective The main focus is on the application of IM and PMSM in electrical drive systems where field orientated control has been successfully established in practice It also discusses the use of grid voltage oriented control of DFIMs in wind power plants This second enlarged edition includes new insights into flatness based nonlinear control of IM PMSM and DFIM The book is useful for practitioners as well as development engineers and designers in the area of electrical drives and wind power technology It is a valuable resource for researchers and students Adaptive Control for Robotic Manipulators Dan Zhang, Bin Wei, 2017-02-03 The robotic mechanism and its controller make a complete system As the robotic mechanism is reconfigured the control system has to be adapted accordingly The need for the reconfiguration usually arises from the changing functional requirements This book will focus on the adaptive control of robotic manipulators to address the changed conditions. The aim of the book is to summarise and introduce the state of the art technologies in the field of adaptive control of robotic manipulators in order to improve the methodologies on the adaptive control of robotic manipulators Advances made in the past decades are described in the book including adaptive control theories and design and application of adaptive control to robotic manipulators

Discrete-Time High Order Neural Control Edgar N. Sanchez, Alma Y. Alanís, Alexander G. Loukianov, 2008-06-24 Neural networks have become a well established methodology as exempli ed by their applications to identication and control of general nonlinear and complex systems the use of high order neural networks for modeling and learning has recently increased Usingneural networks controlal gorithms can be developed to be robust to uncertainties and modeling errors. The most used NN structures are Feedf ward networks and Recurrent networks. The latter type o ers a better suited tool to model and control of nonlinear systems. There exist dierent training algorithms for neural networks which he ever normally encounter some technical problems such as local minima slow learning and high sensitivity to initial conditions among others. As a viable alternative new training algorithms for example those based on Kalman Itering have been proposed. There already exists publications about trajectory tracking using neural networks however most of those works were developed for continuous time systems. On the other hand while extensive literature is available for linear discrete timecontrol system.

nonlineardiscrete timecontroldesigntechniques have not been discussed to the same degree Besides discrete time neural networks are better tted for real time implementations *Foundations of Fuzzy Logic and Soft Computing* Patricia Melin,2007-06-05 This book comprises a selection of papers from IFSA 2007 on new methods and theories that contribute to the foundations of fuzzy logic and soft computing Coverage includes the application of fuzzy logic and soft computing in flexible querying philosophical and human scientific aspects of soft computing search engine and information processing and retrieval as well as intelligent agents and knowledge ant colony <u>Contemporary Computing</u> Sanjay Ranka,Arunava Banerjee,Kanad Kishore Biswas,Sumeet Dua,Prabhat Mishra,Rajat Moona,Sheung-Hung Poon,Cho-Li Wang,2010-08-12 This book constitutes the first part of the refereed proceedings of the Third International Conference IC3 2010 held in Noida India in August 2010 The 23 revised full papers presented were carefully reviewed and selected from numerous submissions

<u>Introduction to Linear Control Systems</u> Yazdan Bavafa-Toosi,2017-09-19 Introduction to Linear Control Systems is designed as a standard introduction to linear control systems for all those who one way or another deal with control systems It can be used as a comprehensive up to date textbook for a one semester 3 credit undergraduate course on linear control systems as the first course on this topic at university This includes the faculties of electrical engineering mechanical engineering aerospace engineering chemical and petroleum engineering industrial engineering civil engineering bio engineering economics mathematics physics management and social sciences etc The book covers foundations of linear control systems their raison detre different types modelling representations computations stability concepts tools for time domain and frequency domain analysis and synthesis and fundamental limitations with an emphasis on frequency domain methods Every chapter includes a part on further readings where more advanced topics and pertinent references are introduced for further studies The presentation is theoretically firm contemporary and self contained Appendices cover Laplace transform and differential equations dynamics MATLAB and SIMULINK treatise on stability concepts and tools treatise on Routh Hurwitz method random optimization techniques as well as convex and non convex problems and sample midterm and endterm exams The book is divided to the sequel 3 parts plus appendices PART I In this part of the book chapters 1 5 we present foundations of linear control systems This includes the introduction to control systems their raison detre their different types modelling of control systems different methods for their representation and fundamental computations basic stability concepts and tools for both analysis and design basic time domain analysis and design details and the root locus as a stability analysis and synthesis tool PART II In this part of the book Chapters 6 9 we present what is generally referred to as the frequency domain methods This refers to the experiment of applying a sinusoidal input to the system and studying its output There are basically three different methods for representation and studying of the data of the aforementioned frequency response experiment these are the Nyquist plot the Bode diagram and the Krohn Manger Nichols chart We study these methods in details We learn that the output is also a sinusoid with the same frequency but generally

with different phase and magnitude By dividing the output by the input we obtain the so called sinusoidal or frequency transfer function of the system which is the same as the transfer function when the Laplace variable s is substituted with Finally we use the Bode diagram for the design process PART III In this part Chapter 10 we introduce some miscellaneous advanced topics under the theme fundamental limitations which should be included in this undergraduate course at least in an introductory level We make bridges between some seemingly disparate aspects of a control system and theoretically complement the previously studied subjects Appendices The book contains seven appendices Appendix A is on the Laplace transform and differential equations Appendix B is an introduction to dynamics Appendix C is an introduction to MATLAB including SIMULINK Appendix D is a survey on stability concepts and tools A glossary and road map of the available stability concepts and tests is provided which is missing even in the research literature Appendix E is a survey on the Routh Hurwitz method also missing in the literature Appendix F is an introduction to random optimization techniques and convex and non convex problems Finally appendix G presents sample midterm and endterm exams which are class tested several times

Multi-Objective Memetic Algorithms Chi-Keong Goh, Yew Soon Ong, Kay Chen Tan, 2009-02-26 The application of sophisticated evolutionary computing approaches for solving complex problems with multiple conflicting objectives in science and engineering have increased steadily in the recent years Within this growing trend Memetic algorithms are perhaps one of the most successful stories having demonstrated better efficacy in dealing with multi objective problems as compared to its conventional counterparts Nonetheless researchers are only beginning to realize the vast potential of multi objective Memetic algorithm and there remain many open topics in its design This book presents a very first comprehensive collection of works written by leading researchers in the field and reflects the current state of the art in the theory and practice of multi objective Memetic algorithms Multi Objective Memetic algorithms is organized for a wide readership and will be a valuable reference for engineers researchers senior undergraduates and graduate students who are interested in the areas of Memetic algorithms and multi objective optimization

Unveiling the Power of Verbal Beauty: An Mental Sojourn through **Modeling And Adaptive Nonlinear Control Of Electric Motors**

In a world inundated with displays and the cacophony of quick connection, the profound energy and psychological resonance of verbal artistry often disappear in to obscurity, eclipsed by the regular barrage of sound and distractions. Yet, nestled within the lyrical pages of **Modeling And Adaptive Nonlinear Control Of Electric Motors**, a charming work of fictional elegance that impulses with natural thoughts, lies an wonderful trip waiting to be embarked upon. Composed with a virtuoso wordsmith, that enchanting opus guides viewers on an emotional odyssey, gently exposing the latent potential and profound influence embedded within the complex internet of language. Within the heart-wrenching expanse of the evocative examination, we can embark upon an introspective exploration of the book is main themes, dissect its charming writing design, and immerse ourselves in the indelible impact it leaves upon the depths of readers souls.

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