Control Theory of Systems Governed by Partial Differential Equations

A. R. AZEZ A.W. WINGATE M. J. BALAS

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J. F. Pommaret

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1982 to the present KR Control Theory for Partial Differential Equations: Volume 2, Abstract Hyperbolic-like **Systems Over a Finite Time Horizon** Irena Lasiecka, Roberto Triggiani, 2000-02-13 Originally published in 2000 this is the second volume of a comprehensive two volume treatment of quadratic optimal control theory for partial differential equations over a finite or infinite time horizon and related differential integral and algebraic Riccati equations Both continuous theory and numerical approximation theory are included The authors use an abstract space operator theoretic approach which is based on semigroups methods and which unifies across a few basic classes of evolution The various abstract frameworks are motivated by and ultimately directed to partial differential equations with boundary point control Volume 2 is focused on the optimal control problem over a finite time interval for hyperbolic dynamical systems A few abstract models are considered each motivated by a particular canonical hyperbolic dynamics It presents numerous fascinating results These volumes will appeal to graduate students and researchers in pure and applied mathematics and theoretical engineering with an interest in optimal control problems Optimal Control of Partial Differential Equations Fredi Tröltzsch, 2024-03-21 Optimal control theory is concerned with finding control functions that minimize cost functions for systems described by differential equations The methods have found widespread applications in aeronautics mechanical engineering the life sciences and many other disciplines This book focuses on optimal control problems where the state equation is an elliptic or parabolic partial differential equation Included are topics such as the existence of optimal solutions necessary optimality conditions and adjoint equations second order sufficient conditions and main principles of selected numerical techniques It also contains a survey on the Karush Kuhn Tucker theory of nonlinear programming in Banach spaces The exposition begins with control problems with linear equations quadratic cost functions and control constraints To make the book self contained basic facts on weak solutions of elliptic and parabolic equations are introduced Principles of functional analysis are introduced and explained as they are needed Many simple examples illustrate the theory and its hidden difficulties This start to the book makes it fairly self contained and suitable for advanced undergraduates or beginning graduate students Advanced control problems for nonlinear partial differential equations are also discussed As prerequisites results on boundedness and continuity of solutions to semilinear elliptic and parabolic equations are addressed These topics are not yet readily available in books on PDEs making the exposition also interesting for researchers Alongside the main theme of the analysis of problems of optimal control Tr ltzsch also discusses numerical techniques The exposition is confined to brief introductions into the basic ideas in order to give the reader an impression of how the theory can be realized numerically After reading this book the reader will be familiar with the main principles of the numerical analysis of PDE constrained optimization

Advances in Partial Differential Equations and Control Kaïs Ammari, Anna Doubova, Stéphane Gerbi, Manuel González-Burgos, 2024-07-27 This volume presents a timely overview of control theory and related topics such as the reconstruction problem the stability of PDEs and the Calder n problem The chapters are based on talks given at the

conference Control Related Fields held in Seville Spain in March 2023 In addition to providing a snapshot of these areas chapters also highlight breakthroughs on more specific topics such as Stabilization of an acoustic system The Kramers Fokker Planck operator Control of parabolic equations Control of the wave equation Advances in Partial Differential Equations and Control will be a valuable resource for both established researchers as well as more junior members of the community Optimal Control Theory Applied to Systems Described by Partial Differential Equations William L.

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Kogut,Günter R. Leugering,2011-09-09 In the development of optimal control the complexity of the systems to which it is applied has increased significantly becoming an issue in scientific computing In order to carry out model reduction on these systems the authors of this work have developed a method based on asymptotic analysis Moving from abstract explanations to examples and applications with a focus on structural network problems they aim at combining techniques of homogenization and approximation Optimal Control Problems for Partial Differential Equations on Reticulated Domains is an excellent reference tool for graduate students researchers and practitioners in mathematics and areas of engineering involving reticulated domains

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