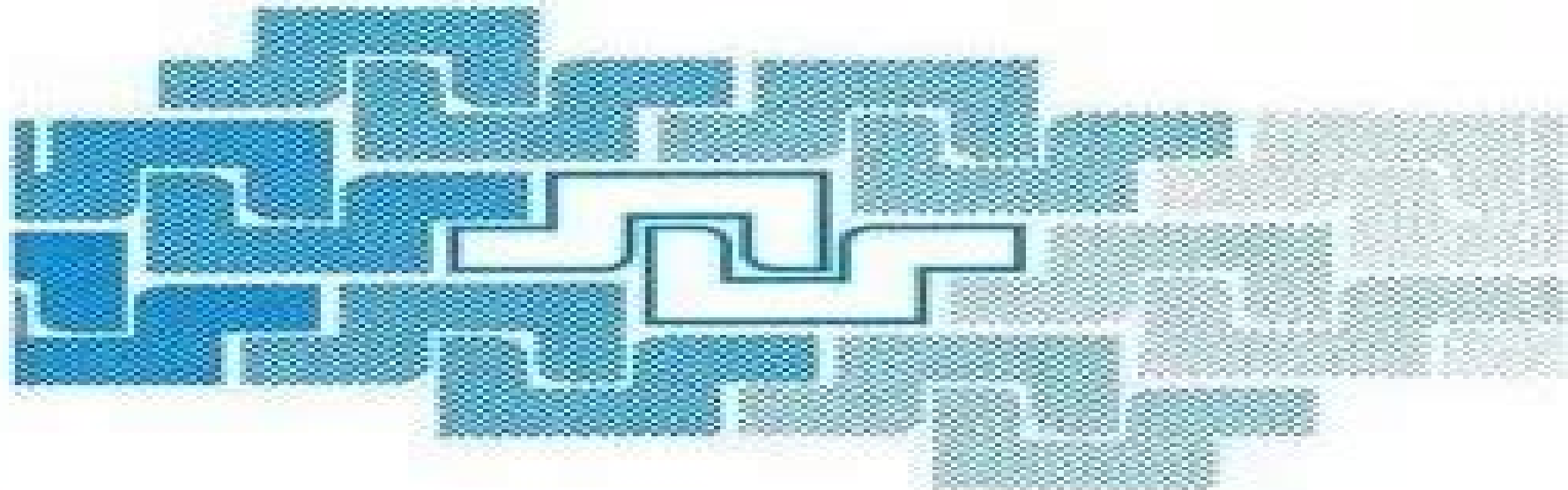




Magnetic Resonance in Colloid and Interface Science

Edited by

Jacques Fraissard and Olga Lapina

NATO Science Series

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web based on the user commands the robot moves and pick and place the objects the robotic arm used here is similar to a human arm which is programmed to perform the pick and place functions the remainder of this paper is organized as follows the section 2 provides information about the existing works section 3 gives details of the proposed

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